# Multi-loop Controller with Multifunction Display Model C7G 

## Overview

The C7G multi-loop controller with multifunction display can calculate diagnostic parameters (a health index) that help to predict the failure of connected equipment, in addition to calculations for PID control of process variables such as temperature, pressure, flow rate, pH , and liquid level.
The controller consists of a display unit with a 3.5 -inch QVGA LCD touchscreen and a main unit capable of controlling up to four loops with an input sampling cycle of 10 ms and an indication accuracy of $\pm 0.1 \%$ FS.
The display unit and main unit can be installed separately for installation flexibility and longer service life of the display unit in the case of a harsh environment.
A wide variety of interfaces, including Ethernet, RS-485 serial communication, microSD card, Micro USB port, and 7 digital input/outputs are provided as standard features. Setup, operation, and monitoring can be easily accomplished using the display unit and Smart Loader Package.

## Features

- High-speed and high-accuracy control is available with an input sampling cycle as fast as 10 ms and an indication accuracy of $\pm 0.1 \%$ FS. Process data can be stored with the compact data storage function (microSD card).
- Diagnostic and management information is created with our unique process data-processing technology (the health index function).
- One module can execute PID control for up to 4 loops.
- Various information is displayed on a 3.5 -inch QVGA LCD with easy touchscreen operation.
- The display unit and main unit can be installed separately. Standard distance: less than 30 m
If display unit is separately powered: 30 to 100 m

- Protective structure of display face: IP67
- Ethernet and RS-485 serial communication (Modbus) is supported as a standard feature.
- For setup and file management the SLP-C7 Smart Loader Package can be used.
- The C7G is powered through a Micro-USB cable, and parameters can be set using the Smart Loader Package even if the controller's power is off.

*1. There are 7 digital inputs (DI) and digital outputs ( DO ) in total. DI and DO can be switched by changing the setting.
*2. There are from 1 to 4 analog inputs, depending on the model.
*3. There are from 0 to 4 analog outputs and VT inputs, depending on the model.
*4. There are from 0 to 8 CT inputs, depending on the model.
*5. There are from 0 to 4 voltage pulse outputs, depending on the model.
*6. There is either 0 or 1 motor drive output (with MFB), depending on the model.
*7. There are from 1 to 4 control loops, depending on the number of analog inputs and the loop type settings.
*8. To use an additional display, a model with the additional display unit block must be selected and an additional display unit (C7D_) must be purchased.
${ }^{*} 9$. There are from 0 to 8 digital inputs, depending on the model, in addition to the digital inputs mentioned in *1.
*10. There are from 0 to 8 digital outputs, depending on the model, in addition to the digital outputs mentioned in *1.

Specifications

| Display unit (included) Additional display unit (C7D-_____) |  | Screen specifications | 3.5-inch QVGA LCD |
| :---: | :---: | :---: | :---: |
|  |  | Status display (LED) | 1 (power) |
|  |  | Operation buttons | Touchscreen (resistive) and 3 hardware buttons |
|  |  | Power for display unit | Power from main unit if distance from main unit (display unit connector / additional display unit block) to display unit is less than 30 m Power from external power source ( 5 $\mathrm{V} D C$ ) if distance from main unit (display unit connector / additional display unit block) to display unit is |
|  |  | Protection rating | IP67 (front of display unit only) |
|  |  | Interface language | English/Japanese (switchable) |
|  |  | Service life of LCD | 5 years (at ambient temperature of $25^{\circ} \mathrm{C}$ and brightness setting 4 , for half-life of backlight brightness) |
| DI (digital input)/ DO (digital output) |  | No. of I/Os | 7 max. (select DI, DO, or TP by setting), shared common <br> Note: TP (time proportioning output) can be selected for output Nos. 4 to 7. |
| block | Digital input | Compatible output type | Non-voltage contacts or open collector (sink type) |
|  |  | Open terminal voltage | 7 V max. |
|  |  | Terminal current (when shorted) | 1 mA (under standard conditions) |
|  |  | On-state contact resistance (no-voltage contact) | $500 \Omega$ max. (under standard conditions) |
|  |  | Off-state contact resistance (no-voltage contact) | $100 \mathrm{k} \Omega$ max. (under standard conditions) |
|  |  | Allowable on-state residual voltage for open collector | 1 V max. (under standard conditions) |
|  |  | Allowable off-state residual current for open collector | $100 \mu \mathrm{~A}$ max. (under standard conditions) |
|  |  | Input sampling cycle | 10 ms |
|  |  | Minimum pulse width for ON detection | 20 ms min. ( 10 ms sampling cycle), 50 ms min. ( 50 ms sampling cycle), 100 ms min. ( 100 ms sampling cycle) |
|  |  | Function assignment | LSP group selection, PID group selection, PV hold, fixed value output group selection, output linearization table group selection, switching of: RUN/READY*, AUTO/MANUAL*, LSP/RSP*, AT stop/start, control operation forward/reverse, Timer stop/start selection, Release all latches, RUN selection*, READY selection*, AUTO selection*, MANUAL selection*, Constant value operation / Pattern operation mode selection* / pattern operation*; ADVANCE*, HOLD*, G. SOAK cancellation, pattern selection. <br> * indicates edge specification function. |
|  | Digital output | Output method | Open collector (sink type) |
|  |  | Load voltage | 4.5 to 28.8 V DC |
|  |  | Maximum load current | 100 mA for each terminal |
|  |  | Overcurrent detection | 130 mA or more <br> When an overcurrent is detected, output is turned OFF and the status is checked every 5 seconds. If the status returns to normal, the output automatically returns to normal. |
|  |  | On-state residual voltage | 0.5 V max. (under standard conditions) |
|  |  | Off-state leak current | $100 \mu \mathrm{~A}$ max. (under standard conditions) |
|  |  | Function assignment | Select an event status or a standard bit code |
|  | Time proportional output (TP) | Output method | Same as digital output |
|  |  | Number of outputs | 4 max. (DI/DO terminals 4 to 7 ) |
|  |  | Min. OFF time / ON time | 1 ms when time proportional cycle is less than 10 s . 250 ms when time proportional cycle is 10 s or more |


| Al block |  | Input type | Full multi-range for thermocouple, resistance temperature detector (RTD), DC current, and DC voltage |
| :---: | :---: | :---: | :---: |
|  |  | No. of control loops | 4 loops max. (configurable by the loop type setting) |
|  |  | Range type | $\bigcirc$ Table 1. Input types and ranges (p.10) |
|  |  | Sampling cycle | $10 \mathrm{~ms}, 50 \mathrm{~ms}, 100 \mathrm{~ms}$ (factory default: 50 ms ) |
|  |  | Burnout | Depends on the input range ( $\leqslant$ Table 1. Input types and ranges (p.10)) |
|  |  | Over-range judgment | Below -10\% or above $110 \%$ of the range |
|  |  | Decimal point position | 0 to 4 digits after the decimal point are displayed. Values are displayed so that the entire value does not exceed 5 digits. (Note: Effective resolution depends on the range.) |
|  | Thermocouple | Reference junction compensation accuracy | $\pm 0.5^{\circ} \mathrm{C}$ (ambient temperature 21 to $27^{\circ} \mathrm{C}$, under standard conditions) <br> $\pm 1.5^{\circ} \mathrm{C}$ (ambient temperature 0 to $50^{\circ} \mathrm{C}$, under standard conditions except for ambient temperature) |
|  |  | Reference junction compensation method | Compensation within the C7G |
|  |  | Input bias current | Input bias current: $0.12 \mu \mathrm{~A}$ max. (under standard conditions). Note: Current flows from the + terminal. |
|  |  | Allowable input voltage | -1.5 to +1.5 V |
|  | Resistance temperature detector (RTD) | Measuring current | 1.0 mA (typical, from terminals A and B, under standard conditions) |
|  |  | Allowable wiring resistance | $85 \Omega$ max. (per wire) |
|  |  | Effect of wiring resistance | Effect of wiring resistance: $0.013^{\circ} \mathrm{C} / \Omega$ (under standard conditions, within allowable wiring resistance) |
|  | DC voltage DC current | Input bias current | 0 to 10 V range : $10 \mu \mathrm{~A}$ max. (under standard conditions) -10 to +10 V range: -10 to $+10 \mu \mathrm{~A}$ (under standard conditions) $1-5 \mathrm{~V}$ or $0-5 \mathrm{~V}$ range: $5 \mu \mathrm{~A}$ max. (under standard conditions) |
|  |  | Allowable input voltage | DC voltage input: -15 to +15 V <br> DC current input: -1.5 to +1.5 V |
|  |  | Input impedance | DC voltage input: $1 \mathrm{M} \Omega$ or more DC current input: $50 \Omega$ |
|  |  | Scaling | -32000 to $+32000 \cup$ ( 5 digits within this range, max. 4 digits after the decimal point, reverse scaling possible) |
| AO-C block | Current output(1) | Type | 4 to $20 \mathrm{~mA} \mathrm{DC} \mathrm{/} 0$ to 20 mA DC |
|  |  | Output type | Control output (MV), process value (PV), set value (SP), standard numerical code, etc. |
|  |  | Accuracy | $\pm 0.1$ \% FS |
|  |  | Allowable load resistance | $600 \Omega$ max. |
|  |  | Output resolution | 1/16000 min. |
|  | CT (current) input (1) | Recommended current transformer | QN206A (hole dia. $5.8 \mathrm{~mm}, 800$ turns), QN212A (hole dia. $12 \mathrm{~mm}, 800$ turns) Note: Not UL-certified |
|  |  | Measuring current range | 0.4-50.0 A AC, 50/60 Hz (peak current: 71 A max., 800 turns, 1 power wire loop) |
|  |  | Maximum allowable current | 70 A AC (peak current: 99 A max. with 800 turns and 1 pass of the power wire) |
|  |  | Indication accuracy | $\pm 1 \% \mathrm{FS} \pm 1$ digit (under standard conditions, CT accuracy is not included) |
|  |  | Indication resolution | 0.1 A AC |
|  |  | Indication update cycle | 100 ms |
|  | VT (voltage) input (1) | Recommended voltage transformer | 81406725-003 (primary side: 200V, secondary side: 10V) (not UL-certified) |
|  |  | Voltage measurement range | 24 to $240 \mathrm{~V} \mathrm{AC}, 50 / 60 \mathrm{~Hz}$ (peak voltage: 339 V max.; transformer primary side 200 V , secondary side 10 V ) |
|  |  | Maximum allowable voltage | 264 V AC (peak voltage: 373 V max.; transformer primary side: 200 V , secondary side: 10 V ) |
|  |  | Indication accuracy | $\pm 1 \% \mathrm{FS} \pm 1$ digit |
|  |  | Indication resolution | 0.1 V AC |
|  |  | Input impedance | $160 \mathrm{k} \Omega$ (typ) |
|  |  | Indication update cycle | 100 ms |
| V-P block | Voltage pulse output (1) | Output voltage | 12 V DC +15/-10 \% (under standard conditions) |
|  |  | Allowable current | 25 mA max. |
|  |  | Load limit current | $30 \mathrm{~mA} \pm 10$ \% |
|  |  | OFF-state leak current | $100 \mu \mathrm{~A}$ max. (under standard conditions) |
|  |  | Output response time | $100 \mu \mathrm{~s} \mathrm{max}$. for $10 \% \leftrightarrow 90 \%$ of output voltage |
|  | CT (current) input (2) | Specifications | Same as CT (current) input for the AO-C block |


| MOTOR block | Motor drive output relay | Contact configuration | Switching between OPEN output and CLOSE output (with function for turning both outputs OFF at the same time) |
| :---: | :---: | :---: | :---: |
|  |  | Contact rating | $250 \mathrm{~V} \mathrm{AC} ,2 \mathrm{~A}(\cos \phi=0.4) ; 24 \mathrm{~V} \mathrm{DC}, 2.5 \mathrm{~A}(\mathrm{~L} / \mathrm{R}=0.7 \mathrm{~ms})$ |
|  |  | Contact voltage | 250 V AC / 125 V DC max. |
|  |  | Service life | 100,000 cycles min. (at the rated specifications) |
|  |  | Minimum requirements for switching | 40 mA (when using 24 V DC power) |
|  |  | Interlock | With prevention of simultaneous ON if contact welding occurs (when output of close side is ON, output of open side is forced OFF, meaning that close-side output is prioritized) |
|  | MFB (motor feedback) input | Allowable potentiometer | 100 to $2500 \Omega$ (wiring resistance included) |
|  |  | Indication accuracy | $\pm 0.5 \%$ FS (under standard conditions) |
|  |  | Sampling cycle | 100 ms |
|  |  | Operation at burnout | Y line break: downscale Other line break: upscale |
| DI block |  | Number of inputs | 4 (common) |
|  |  | Compatible output type | Non-voltage contacts or open collector |
|  |  | Input type | Photocoupler (two-way) |
|  |  | Rated input voltage | 24 V DC, +20/-15 \% |
|  |  | Terminal current | 4 mA (with 24 V DC input) |
|  |  | ON voltage/current | $19 \mathrm{~V} / 3 \mathrm{~mA}$ min. |
|  |  | OFF voltage/current | $7 \mathrm{~V} / 1 \mathrm{~mA}$ max. |
|  |  | Input sampling cycle | 10 ms |
|  |  | Minimum pulse width for ON detection | $20 \mathrm{~ms} \mathrm{min}. \mathrm{(for} \mathrm{a} 10 \mathrm{~ms} \mathrm{sampling} \mathrm{cycle)}$ |
|  |  | $50 \mathrm{~ms} \mathrm{min}. \mathrm{(for} 50 \mathrm{~ms}$ sampling cycle) |
|  |  | 100 ms min . (for 100 ms sampling cycle) |
|  |  | Function assignment | LSP group selection, PID group selection, PV hold, fixed value output group selection, output linearization table group selection, switching of: RUN/READY*, AUTO/MANUAL*, LSP/RSP*, AT stop/start, control action forward/reverse, Timer stop/start selection, Release all latches, RUN selection*, READY selection*, Constant value operation / Pattern operation mode selection* / pattern operation*; ADVANCE*, HOLD*, G. SOAK cancellation, pattern selection. <br> * indicates edge specification function. |
| DO block |  |  | Number of outputs | 4 (common) |
|  |  |  | Output type | Open collector (sink type) |
|  |  | Load voltage | 4.5 to 28.8 V DC |
|  |  | Maximum load current | 100 mA for each terminal |
|  |  | Overcurrent detection | 130 mA and above <br> When an overcurrent is detected, the output is turned OFF and the status is checked every 5 seconds. If the status returns to normal, the output automatically returns to normal. |
|  |  | On-state residual voltage | 0.5 V max. (under standard conditions) |
|  |  | Off-state leak current | $100 \mu \mathrm{~A}$ max. (under standard conditions) |
|  |  | Function assignment | Select an event status or a standard bit code |
| CLOCK block (with battery) |  | Clock function | Hours, minutes, seconds, calendar (years 2000 to 2099, supports leap years) |
|  |  | Clock accuracy | Monthly error of less than $\pm 65 \mathrm{~s}$ (under standard conditions) |
|  |  | Service life | 10 years (battery life when not energized, under standard conditions) |
|  |  | Built-in battery | Lithium battery |
|  |  | Block replacement | Possible (optional parts sold separately) |
| HMI2 block |  | Number of connectable units | 1 |
|  |  | Connector | RJ-45 |


| Control unit | Control operation | PID control (reverse action, direct action, heating and cooling action), ON/OFF control (reverse action, direct action) |  |
| :---: | :---: | :---: | :---: |
|  | Control method | Continuous proportional, time proportional, position proportional, cascade |  |
|  | PID control | Proportional band (P) | 0.1 to 3200 \% ( 5 digits within this range, 4 digits max. after the decimal point) |
|  |  | Integral time (I) | 0 to 32000 s ( 5 digits within this range, 4 digits max. after the decimal point) <br> No integral calculation when the setting is 0 . |
|  |  | Derivative time (D) | 0 to 32000 s ( 5 digits within this range, 4 digits max. after the decimal point) <br> No derivative calculation when the setting is 0 . |
|  |  | MV limits | -10 to $+110 \%$ ( 5 digits within this range, 4 digits max. after the decimal point) |
|  |  | Manual reset | -10 to $+110 \%$ ( 5 digits within this range, 4 digits max. after the decimal point) |
|  |  | Number of PID groups | 8 groups (per loop) |
|  |  | PID group selection | For constant-value operation (LSP, RSP), a PID group can be set for each SP group <br> Alternatively, selection by the DI function or zone PID function is possible. <br> For pattern operation, a PID group can be set for each segment. Alternatively, selection by the DI function or zone PID function is possible. |
|  |  | MV change limit | 0.0 to $10000 \% / \mathrm{s}$ ( 5 digits within this range, 4 digits max. after the decimal point) <br> No limit when the setting is 0.0 . |
|  |  | Auto-tuning | PID automatic setting using the limit cycle method |
|  |  | Control AT type | 0: Normal, 1: Fast response, 2: Stable |
|  |  | Control AT adjustment factor | 0.0000 to 320.00 (specifiable for proportional band, integral time, and derivative time) |
|  |  | Control cycle | Same as sampling cycle |
|  | ON/OFF control | Differential | 0 to 32000 ( 5 digits max.within this range 4 digits max.after the decimal point) |
|  | $\begin{aligned} & \text { SP } \\ & \text { (LSP: local SP) } \end{aligned}$ | Number of LSP groups | 8 groups per loop |
|  |  | SP ramp unit | 0: s, 1: min, 2: h |
|  |  | Ramp up and down slopes | 0 to 32000 |
|  | Direct/reverse operation selection | Switchable |  |
|  | Heating/cooling control deadband | -100.0 to +100.0 \% |  |
| Analog input processing unit | Linear scaling low and high limits | -32000 to +32000 ( 5 digits within this range, 4 digits max. after the decimal point) |  |
|  | Filter | 0.0000 to 120.00 s |  |
|  | Ratio | 0.0010 to 10.000 |  |
|  | Bias | -32000 to +32000 ( 5 digits within this range, 4 digits max. after the decimal point) |  |
|  | Square root drop out | $\begin{array}{\|l\|} \hline 0.0001 \text { to } 10.000 \% \\ \text { No square root extraction if set to } 0.0000 \\ \hline \end{array}$ |  |
| Linear approximation function | Number of groups | 8 |  |
|  | Breakpoints per group | 20 |  |
|  | Available for | Analog input, analog output, etc. |  |
| Event functions | Number of events | 16 |  |
|  | Operation types | PV high limit, PV low limit, PV high and low limits, deviation high limit, deviation low limit, deviation high and low limits, deviation high limit (final SP basis), deviation low limit (final SP reference), deviation high and low limits (final SP basis), SP high limit, SP low limit, SP high and low limits, MV high limit, MV low limit, MV high and low limits, MFB high and low limits, standard numerical code high limit, standard numerical code low limit, standard numerical code high and low limits, PV change rate, PV change rate high limit, PV change rate low limit, standard numerical code change rate high limit, standard numerical code change rate low limit, alarm (state), READY (state), MANUAL (state), RSP (state), AT running (state), SP ramp running (state), control direct action (state), control with estimated MFB (state), timer (state) |  |
|  | Main setting / subsetting | -32000 to +32000 ( 5 digits within this range, 4 digits max. after the decimal point) |  |
|  | Hysteresis | 0 to 32000 ( 5 digits within this range, 4 digits max. after the decimal point) |  |
|  | READY mode operation | Selectable from "continuation" and "forced OFF." |  |
|  | Direct/reverse | Select the polarity to turn ON/OFF in event output |  |
|  | Standby | 0 : None, 1: Standby, 2: Standby + standby when the SP is modified |  |
|  | On-delay time | 0 to 3200 s (4 digits within this range, 4 digits max. after the decimal point) |  |
|  | OFF-delay time | 0 to 3200 s (4 digits within this range, 4 digits max. after the decimal point) |  |


| Pattern operation functions |  | Number of patterns | 16 |
| :---: | :---: | :---: | :---: |
|  |  | Number of segments | 32 per pattern |
|  |  | Segment setting method | Set by set point (SP) and time |
|  |  | Time units | $0.01 \mathrm{~s}, 0.1 \mathrm{~s}, 1 \mathrm{~s}, 1 \mathrm{~min}$ |
|  |  | Functions | HOLD, G. SOAK (start point, end point), PV start, ADVANCE, cyclical operation, pattern link, etc. |
|  |  | Operation end state | READY, END, constant-value |
|  |  | Event | Segment events 1 to 32 |
|  |  | Time accuracy | Accuracy of built-in clock: less than $\pm 140 \mathrm{~s} /$ month |
| Logical operation function |  | Number of logical operation | 32 |
|  |  | Operation type | 1: Calculation 1 ( $A$ and $B$ ) or ( $C$ and $D$ ) <br> 2: Calculation 2 ( $A$ or $B$ ) and ( $C$ or $D$ ) <br> 3: Calculation 3 (A or B or C or D) <br> 4: Calculation 4 ( $A$ and $B$ and $C$ and $D$ ) |
|  |  | ON delay | 0 to 3200s(5 digits max.within this range 4 digits max.after the decimal point) |
|  |  | OFF delay | 0 to 3200s(5 digits max.within this range 4 digits max.after the decimal point) |
|  |  | Reverse | 0: Direct <br> 1: Reverse <br> 2: Rising <br> 3: Falling |
|  |  | Latch | 0: Not latched <br> 1: Latched when turned ON <br> 2: Latched when turned OFF <br> (Except for OFF when power is turned ON) |
| Numerical operation function |  | Number of unit | 32 |
|  |  | Operation type | No operation aX+bY, Division, Switch selector, High selector, Low selector, Soft switching selector, High/low limiter, Change rate limiter, Lead/lag, Absolute value, Linearization table, Hold, One shot timer, Timer, Deviation monitor, Square-root extraction, Integration pulse output I, Integration pulse output II, Logarithm, Exponent, Derivation, Integration, Dead time, Moving average |
| Other functions |  |  | Time setting, unit character setting, key lock setting, fixed value output, power voltage compensation, resistance value calculation (from the VT input and CT input), reception monitoring, user-defined alarm, input assignment, virtual analog input,FF-FITTER |
| External communication | Ethernet | Transmission line type | Compliant with IEEE 802.3u 100BASE-TX (FastEthernet) |
|  |  | Communication method | Full duplex |
|  |  | No. of connections | 4 (The total number of connections for Modbus/TCP and loader communications via Ethernet is 1 to 3 , and the number of connections for PLC link communication is fixed at 1.) |
|  |  | Transmission speed | 100 Mbps max. |
|  |  | No. of physical ports (connectors) | 1 (RJ-45) |
|  |  | Cable | UTP cable (4P) Cat 5e min. (straight) (ANSI/TIA/EIA-568-B both ends) |
|  |  | Protocol: | Modbus/TCP, Mitsubishi SLMP (3E) (for PLC link communication), Loder communications via Ethernet |
|  | RS-485 communication | Signal level | RS-485-compliant |
|  |  | Network | Multidrop (up to 31 slave stations for 1 host station) |
|  |  | Communications/ synchronization type | Half-duplex, start-stop synchronization |
|  |  | Maximum cable length | 500 m max. |
|  |  | No. of communication wires | 3-wire system |
|  |  | Transmission speed | 9600, 19200, 38400, 57600, 115200 bps |
|  |  | Terminating resistor | External (120 $\Omega$, 1/2 W min.) |
|  |  | Data length | 8 bits |
|  |  | Stop bits | 1 or 2 bits |
|  |  | Parity bit | Even parity, odd parity, or no parity |
|  |  | Protocol | Modbus/RTU |
|  | Loader communication | Dedicated PC loader | SLP-C7FJ91 (free version), SLP-C7-J91 (paid version) |
|  |  | Cable | USB-to-Micro-USB (Type A/B) cable (USB 2.0 supported, 5 m max.) or Ethernet cable |
|  |  | Power supply | When connected with a USB cable, the device can be powered by the PC and parameters can be changed. |
| Data storage |  | SD | microSD/SDHC-compliant (4GB), for the compact data storage and health index functions |



| General specifications | Standard conditions | Ambient temperature | $23^{\circ} \mathrm{C}-2 /+5^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: | :---: |
|  |  | Ambient humidity | $60 \pm 5$ \% RH |
|  |  | Power | AC models: 105 V AC $\pm 10$ \%. DC models: 24 V DC $\pm 5$ \% |
|  |  | Power frequency | AC models: $50 \mathrm{~Hz} \pm 1 \%, 60 \mathrm{~Hz} \pm 1 \%$ |
|  |  | Vibration | $0 \mathrm{~m} / \mathrm{s}^{2}$ |
|  |  | Shock | $0 \mathrm{~m} / \mathrm{s}^{2}$ |
|  |  | Mounting angle | Main unit: Reference plane $\pm 3^{\circ}$, Display unit: No restriction (if mounted separately from the main unit) |
|  |  | Space | 100 mm min. above and below, and on all sides (main unit); gang mounting acceptable (display unit) |
|  | Operating conditions | Ambient temperature | 0 to $50{ }^{\circ} \mathrm{C}$ ( 0 to $40{ }^{\circ} \mathrm{C}$ if main units are gang-mounted) |
|  |  | Ambient humidity | 10 to 90 \% RH (without condensation) |
|  |  | Rated power | AC models: 100 to 240 V AC (operating input voltage: 85 to 264 V AC ) DC models: 24 V DC (operating input voltage: 20.4 to 28.8 V DC) |
|  |  | Power frequency | AC models: $50 \mathrm{~Hz} \pm 2$ \% or $60 \mathrm{~Hz} \pm 2$ \% |
|  |  | Vibration | 0 to $5 \mathrm{~m} / \mathrm{s}^{2}$ (10 to 60 Hz for 2 h each in $\mathrm{x}, \mathrm{y}$, and z directions) |
|  |  | Shock | 0 to $100 \mathrm{~m} / \mathrm{s}^{2}$ |
|  |  | Mounting angle | Reference plane $\pm 10^{\circ}$ for main unit and display unit in integrated mounting. No restriction for display unit in standard mounting. |
|  |  | Altitude | 2000 m max. |
|  |  | Pollution degree | 2 |
|  |  | Installation location | Indoors |
|  |  | Space | For the main unit, leave at least 50 mm above, below, and in front of the unit. No space is needed on the right or left. <br> For the display unit, no space is needed above, below, on the right, or on the left. |
|  | Transportation and storage conditions | Ambient temperature | -20 to $+70{ }^{\circ} \mathrm{C}$ |
|  |  | Ambient humidity | 10 to $95 \%$ RH (without condensation) |
|  |  | Vibration | 0 to $10 \mathrm{~m} / \mathrm{s}^{2}$ (10 to 60 Hz for 2 h each in $\mathrm{x}, \mathrm{y}$, and z directions) |
|  |  | Shock | 0 to $300 \mathrm{~m} / \mathrm{s}^{2}$ (3 times each in $x, y$, and $z$ directions) |

Table 1. Input types and ranges

| Input type | Range type Nos. | Sensor | Range |  |  |  | Accuracy | Resolution | Burnout |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Range (Celsius) |  | Range (Fehrenheit) |  |  |  |  |
| Thermocouple | 1 | K | -200 to | $+1200{ }^{\circ} \mathrm{C}$ | -300 to | $+2200{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit ${ }^{*}$ | $0.1{ }^{\circ} \mathrm{C}$ | $\begin{gathered} \text { Upscale } \\ (110 \text { \% FS) } \end{gathered}$ |
|  | 2 | K | 0 to | $1200{ }^{\circ} \mathrm{C}$ | 0 to | $2200{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 3 | K | 0 to | $800^{\circ} \mathrm{C}$ | 0 to | $1500{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 4 | K | 0 to | $600^{\circ} \mathrm{C}$ | 0 to | $1100{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 5 | K | 0 to | $400^{\circ} \mathrm{C}$ | 0 to | $700{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 6 | K | -200 to | $+400^{\circ} \mathrm{C}$ | -300 to | +700 ${ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit *1 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 7 | K | -200 to | $+200^{\circ} \mathrm{C}$ | -300 to | $+400^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit *1 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 8 | J | 0 to | $1200{ }^{\circ} \mathrm{C}$ | 0 to | $2200{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 9 | J | 0 to | $800^{\circ} \mathrm{C}$ | 0 to | $1500{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 10 | J | 0 to | $600{ }^{\circ} \mathrm{C}$ | 0 to | $1100{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 11 | J | -200 to | $+400{ }^{\circ} \mathrm{C}$ | -300 to | $+700{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit ${ }^{\text {1 }}$ | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 12 | E | 0 to | $800^{\circ} \mathrm{C}$ | 0 to | $1500{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 13 | E | 0 to | $600^{\circ} \mathrm{C}$ | 0 to | $1100{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 14 | T | -200 to | $+400{ }^{\circ} \mathrm{C}$ | -300 to | $+700{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit *1 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 15 | R | 0 to | $1600^{\circ} \mathrm{C}$ | 0 to | $3000^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit *2 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 16 | S | 0 to | $1600^{\circ} \mathrm{C}$ | 0 to | $3000{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit *2 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 17 | B | 0 to | $1800{ }^{\circ} \mathrm{C}$ | 0 to | $3300{ }^{\circ} \mathrm{F}$ | $\pm 0.2$ \% FS $\pm 1$ digit *3 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 18 | N | 0 to | $1300{ }^{\circ} \mathrm{C}$ | 0 to | $2300^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 19 | PLII | 0 to | $1300{ }^{\circ} \mathrm{C}$ | 0 to | $2300{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ | Upscale (105 \% FS) |
|  | 20 | WRe5-26 | 0 to | $1400{ }^{\circ} \mathrm{C}$ | 0 to | $2400{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ | Upscale (110 \% FS) |
|  | 21 | WRe5-26 | 0 to | $2300^{\circ} \mathrm{C}$ | 0 to | $4200{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 23 | PR40-20 | 0 to | $1900{ }^{\circ} \mathrm{C}$ | 0 to | $3400{ }^{\circ} \mathrm{F}$ | $\pm 0.5$ \% FS $\pm 1$ digit *4 | $0.1{ }^{\circ} \mathrm{C}$ |  |

*1. For -200 to $0^{\circ} \mathrm{C}, \pm 0.2 \% \mathrm{FS} \pm 1$ digit
*2. For 0 to $100^{\circ} \mathrm{C}, \pm 0.2 \% \mathrm{FS} \pm 1$ digit
${ }^{*} 3$. For 0 to $260^{\circ} \mathrm{C}, \pm 4 \% \mathrm{FS} \pm 1$ digit. For 260 to $800^{\circ} \mathrm{C}, \pm 0.4 \% \mathrm{FS} \pm 1$ digit
*4. For 0 to $300^{\circ} \mathrm{C}, \pm 2.5 \% \mathrm{FS} \pm 1$ digit. For 300 to $800^{\circ} \mathrm{C}, \pm 1.5 \% \mathrm{FS} \pm 1$ digit

| Input type | Range type Nos. | Sensor | Range |  |  |  | Accuracy | Resolution | Burnout |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Range (Celsius) |  | Range (Fehrenheit) |  |  |  |  |
| Resistance temperature detector (RTD) | 41 | Pt100 | -200 to | $+500^{\circ} \mathrm{C}$ | -300 to | $+900^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ | Upscale (110 \% FS) |
|  | 43 | Pt100 | -200 to | $+200^{\circ} \mathrm{C}$ | -300 to | $+400{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 45 | Pt100 | -100 to | $+300^{\circ} \mathrm{C}$ | -150 to | $+500{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 47 | Pt100 | -100 to | $+200^{\circ} \mathrm{C}$ | -150 to | $+400{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 49 | Pt100 | -100 to | $+150{ }^{\circ} \mathrm{C}$ | -150 to | $+300{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 51 | Pt100 | -50 to | $+200^{\circ} \mathrm{C}$ | -50 to | $+400{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 53 | Pt100 | -50 to | $+100^{\circ} \mathrm{C}$ | -50 to | $+200^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 55 | Pt100 | -60 to | $+40^{\circ} \mathrm{C}$ | -60 to | $+100^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 57 | Pt100 | -40 to | $+60^{\circ} \mathrm{C}$ | -40 to | $+140{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 59 | Pt100 | -10 to | $+60^{\circ} \mathrm{C}$ | -10 to | +140 ${ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 61 | Pt100 | 0 to | $100^{\circ} \mathrm{C}$ | 0 to | $200^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 63 | Pt100 | 0 to | $200^{\circ} \mathrm{C}$ | 0 to | $400{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 65 | Pt100 | 0 to | $300^{\circ} \mathrm{C}$ | 0 to | $500^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 67 | Pt100 | 0 to | $500^{\circ} \mathrm{C}$ | 0 to | $900^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 69 | Pt100 | -200 to | $+850^{\circ} \mathrm{C}$ | -300 to | $+1550{ }^{\circ} \mathrm{F}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
| Linear | 86 | Voltage (V) | 1 to | 5 V | 1 to | 5 V | $\pm 0.1$ \% FS $\pm 1$ digit | $1 / 90000 \mathrm{~min}$. | Downscale (-10 \% FS) |
|  | 87 | Voltage (V) | 0 to | 5 V | 0 to | 5 V | $\pm 0.1$ \% FS $\pm 1$ digit |  | Burnout not detected (around 0 \% FS) |
|  | 88 | Voltage (V) | 0 to | 10 V | 0 to | 10 V | $\pm 0.1$ \% FS $\pm 1$ digit |  | Burnout not detected (around 0 \% FS) |
|  | 89 | Current (mA) | 0 to | 20 mA | 0 to | 20 mA | $\pm 0.1$ \% FS $\pm 1$ digit |  | Burnout not detected (around 0 \% FS) |
|  | 90 | Current (mA) | 4 to | 20 mA | 4 to | 20 mA | $\pm 0.1$ \% FS $\pm 1$ digit |  | $\begin{aligned} & \hline \text { Downscale } \\ & (-10 \% \text { FS }) \end{aligned}$ |
|  | 92 | Voltage (V) | -10 to | +10 V | -10 to | +10 V | $\pm 0.1$ \% FS $\pm 1$ digit |  | Burnout not detected (around 50 \% FS) |


| Input type | Range type Nos. | Sensor | Range | Accuracy | Resolution | Burnout |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Not used | 0 | None | Fixed at 0 | --- | --- | --- |

## ! Handling Precautions

- Do not use Fahrenheit ranges in Japan.


## Input sensor standards reference

Thermocouple
K, E, J, T, B, R, S, N:
WRe 5-26:
PR40-20, PLII:

JIS C 1602:2015
ASTM E988-96 (reapproved 2002) (JIS C 1602:2015, C Thermocouple)
ASTM E1751/E1751M-15

Resistance temperature detector Pt100: JIS C 1604:2013

Table 2. Compact data storage (CDS)

| Item |  | "Data selection" setting |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Standard | Custom | Ring |
| Save destination |  | microSD memory card | Same as on the left. | Same as on the left. |
| Folder | Root folder name | CDS | Same as on the left. | LOG |
|  | Folder name | BLK _ <br> _: a sequential number from 0 to 64 | Same as on the left. | LOG _ <br> _: Serial number from 001 <br> to 100 |
|  | Maximum number of files in a folder | 1,000 | Same as on the left. | 200 |
|  | Maximum number of files in the microSD memory card. | 65,000 | Same as on the left. | 20,000 |
| File | File name | xxxx_yyyyy_z.dat <br> xxxx: number of power ON/OFF <br> cycles <br> yyyyy: number of files created since power ON <br> z: $\quad$ File division classification <br> (0: first file, 1 : following file) | xxxx_yyyyy_z.csv <br> xxxx: Number of power ON/OFF cycles <br> yyyyy: Number of files created since power ON <br> z: File division classification (0: first file, 1: following file) | xxx_yyyy.csv <br> xxx: Same as _ in the folder name <br> yyyy:Serial number from 0001 to 0200 |
|  | Management file name | None | Same as on the left. | xxx_yyyy.last <br> xxx_yyyy: Same as the name of the last written file. |
|  | Maximum file size for each file | Approx. 2 MB | Same as on the left. | Approx. 192 KB |
|  | Character code | Characters: Shift-JIS (ASCII) <br> Line feed: CR + LF <br> (hexadecimal 0DH and 0AH) <br> Delimiter: comma (,), <br> 2 CH in hexadecimal <br> Decimal point: period (.), <br> hexadecimal 2EH | Same as on the left. | Same as on the left. |
| Recording content | Health index data | Available* | None | Same as on the left. |
|  | Section | Consists of the context section and time sequence data section. <br> Table 2-1. Sections of standard CDS (p.12) (for details). | Consists of the header section and data section. <br> Table 2-2. Sections of custom and loop CDS (p.12) (for details). | Same as on the left. |
|  | Number of data items | 10 data items $\times$ number of loops | Selectable from 1 to 40 | Same as on the left. |
|  | Data types | Records diagnostic data for enabled loops, including the PID constant, health index (specific $R$ value, $R$ value), SP, PV, and MV. <br> Table 2-2. Sections of custom and loop CDS (p.12) (for details). | Select from standard bit codes and standard numerical codes <br> Table 4. List of standard bit codes (p.13) and ${ }^{3}$ Table 5. List of standard numerical codes (p.15) (for standard bit codes and standard numerical codes respectively. | Same as on the left. |
| Recording operation | Recording cycle | Selected from "Same as sampling cycle, $0.1 \mathrm{~s}, 1 \mathrm{~s}, 10 \mathrm{~s}, 1 \mathrm{~min}$, and 10 min ." | Same as on the left. | Same as on the left. |
|  | Start and stop | Selected from "DI1 to 2, events 1 to 16 , and standard bit code" <br> Table 4. List of standard bit codes (p.13). | Same as on the left. | Same as on the left. |
|  | Alarm concerning the number of files and capacity | An SD card error alarm is issued in any of the following cases. <br> - When there is an attempt to write data exceeding the capacity of the microSD memory card <br> - When there is an attempt to write a new file when there are 1,000 files in BLK64 (the last folder) | Same as on the left. | No alarm occurs as the oldest file is rewritten (however, if files recorded by standard or custom recording remain, an alarm may be issued). |

[^0]Table 2-1. Sections of standard CDS

| Section | Data | Notes |
| :---: | :---: | :---: |
| Context section <br> (From Section Context to SectionEnd) | P (Proportional band) | Records the setting when CDS starts. |
|  | I (Integral time) |  |
|  | D (Derivative time) |  |
|  | OL (MV low limit) |  |
|  | OH (MV high limit) |  |
|  | SP high limit |  |
|  | Specific $R$ value (diagnostic parameter) | Normalization responsiveness (Kp/Tp) <br> (Gain is defined as Kp and time constant as Tp in the transfer function.) <br> Calculated from the data when the PV is rising during batch processing. <br> Records the definite value when CDS ends. |
| Time sequence data section (From Section TemporalData to SectionEnd) <br> (Updated in each recording cycle) | Timestamp | Year, month, day, hour, minute, second, millisecond |
|  | SP |  |
|  | PV |  |
|  | MV |  |
|  | R value |  |
|  | DT5 | Varies depending on the type of output block to which the MV is assigned. <br> AO-C block: RMS current (CT) <br> V-P block: RMS current (CT1) <br> Other: 0 (fixed) <br> (However, fixed at 0 if heating MV and cooling MV are assigned) |
|  | DT6 | Varies depending on the type of output block to which the MV is assigned. <br> AO-C block: RMS voltage (VT) <br> V-P block: RMS current (CT2) <br> Other: 0 (fixed) <br> (However, fixed at 0 if heating MV and cooling MV are assigned) |
|  | DT7 | Varies depending on the type of output block to which the MV is assigned. <br> AO-C block: Operation terminal (heater) resistance value (calculated from the CT input current and VT input voltage) <br> Other: $\quad 0$ (fixed) |
|  | DT8 | 0 (fixed) |
|  | DT9 |  |
|  | DT10 |  |

Table 2-2. Sections of custom and loop CDS

| Section | Data | Notes |
| :--- | :--- | :--- |
| Header section <br> (lines 1 to 2) | Data number | Standard bit code, standard numerical code |
|  | Data name |  |
| Data section <br> (lines 3 and after) | Timestamp | Year, month, day, hour, minute, second, millisecond |
|  | Data | Values for standard bits and standard numbers |

Table 3. Health index

| Diagnostic operation | Start and Stop | Select from DI 1 to 2, event 1 to 16, standard bit (can be set for each loop) Standard Bit Codes <br> Table 4. List of standard bit codes (p.13). |
| :---: | :---: | :---: |
|  | Graph display | The health index graph bank displays the last 10 specific $R$ values (diagnostic parameters) for each control loop as points and numbers on a graph. |
| Settings | R value scale | 0 to 10 (specifies the result of calculation $\times$ a power of 10) |
|  | Ideal data | 0.0000 to 32000 |
|  | Deviation low limit | 0.0000 to 32000 (no low limit when 0.0000) |
|  | Deviation high limit | 0.0000 to 32000 (no high limit when 0.0000) |
|  | SP high limit | -32000 to +32000 |

Table 4. List of standard bit codes
The range of standard bit codes is 1024 to 2047.
Codes not listed below are reserved for the system, so do not use them for configuration.

| Standard bit code | Meaning of the standard bit codes | Standard bit code | Meaning of the standard bit codes | Standard bit code | Meaning of the standard bit codes |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1024 | Always 0 (Off) | 1282 | V-P terminal status (A1 block) | 1409 | User-defined bit 2 |
| 1025 | Always 1 (On) | 1283 | V-P terminal status (B1 block) | 1410 | User-defined bit 3 |
| 1088 | Event 1 | 1290 | Result of numerical operation 1 (bit) | 1411 | User-defined bit 4 |
| 1089 | Event 2 | 1291 | Result of numerical operation 2 (bit) | 1412 | User-defined bit 5 |
| 1090 | Event 3 | 1292 | Result of numerical operation 3 (bit) | 1413 | User-defined bit 6 |
| 1091 | Event 4 | 1293 | Result of numerical operation 4 (bit) | 1414 | User-defined bit 7 |
| 1092 | Event 5 | 1294 | Result of numerical operation 5 (bit) | 1415 | User-defined bit 8 |
| 1093 | Event 6 | 1295 | Result of numerical operation 6 (bit) | 1416 | User-defined bit 9 |
| 1094 | Event 7 | 1296 | Result of numerical operation 7 (bit) | 1417 | User-defined bit 10 |
| 1095 | Event 8 | 1297 | Result of numerical operation 8 (bit) | 1418 | User-defined bit 11 |
| 1096 | Event 9 | 1298 | Result of numerical operation 9 (bit) | 1419 | User-defined bit 12 |
| 1097 | Event 10 | 1299 | Result of numerical operation 10 (bit) | 1420 | User-defined bit 13 |
| 1098 | Event 11 | 1300 | Result of numerical operation 11 (bit) | 1421 | User-defined bit 14 |
| 1099 | Event 12 | 1301 | Result of numerical operation 12 (bit) | 1422 | User-defined bit 15 |
| 1100 | Event 13 | 1302 | Result of numerical operation 13 (bit) | 1423 | User-defined bit 16 |
| 1101 | Event 14 | 1303 | Result of numerical operation 14 (bit) | 1424 | User-defined bit 17 |
| 1102 | Event 15 | 1304 | Result of numerical operation 15 (bit) | 1425 | User-defined bit 18 |
| 1103 | Event 16 | 1305 | Result of numerical operation 16 (bit) | 1426 | User-defined bit 19 |
| 1120 | CT1 heater burnout detection (A2 block) | 1306 | Result of numerical operation 17 (bit) | 1427 | User-defined bit 20 |
| 1121 | CT2 heater burnout detection (A2 block) | 1307 | Result of numerical operation 18 (bit) | 1428 | User-defined bit 21 |
| 1122 | CT1 heater burnout detection (B2 block) | 1308 | Result of numerical operation 19 (bit) | 1429 | User-defined bit 22 |
| 1123 | CT2 heater burnout detection (B2 block) | 1309 | Result of numerical operation 20 (bit) | 1430 | User-defined bit 23 |
| 1124 | CT1 heater burnout detection (A1 block) | 1310 | Result of numerical operation 21 (bit) | 1431 | User-defined bit 24 |
| 1125 | CT2 heater burnout detection (A1 block) | 1311 | Result of numerical operation 22 (bit) | 1432 | User-defined bit 25 |
| 1126 | CT1 heater burnout detection (B1 block) | 1312 | Result of numerical operation 23 (bit) | 1433 | User-defined bit 26 |
| 1127 | CT2 heater burnout detection (B1 block) | 1313 | Result of numerical operation 24 (bit) | 1434 | User-defined bit 27 |
| 1128 | CT1 overcurrent detection (A2 block) | 1314 | Result of numerical operation 25 (bit) | 1435 | User-defined bit 28 |
| 1129 | CT2 overcurrent detection (A2 block) | 1315 | Result of numerical operation 26 (bit) | 1436 | User-defined bit 29 |
| 1130 | CT1 overcurrent detection (B2 block) | 1316 | Result of numerical operation 27 (bit) | 1437 | User-defined bit 30 |
| 1131 | CT2 overcurrent detection (B2 block) | 1317 | Result of numerical operation 28 (bit) | 1438 | User-defined bit 31 |
| 1132 | CT1 overcurrent detection (A1 block) | 1318 | Result of numerical operation 29 (bit) | 1439 | User-defined bit 32 |
| 1133 | CT2 overcurrent detection (A1 block) | 1319 | Result of numerical operation 30 (bit) | 1440 | Result of logical operation 1 |
| 1134 | CT1 overcurrent detection (B1 block) | 1320 | Result of numerical operation 31 (bit) | 1441 | Result of logical operation 2 |
| 1135 | CT2 overcurrent detection (B1 block) | 1321 | Result of numerical operation 32 (bit) | 1442 | Result of logical operation 3 |
| 1136 | CT1 short-circuit detection (A2 block) | 1360 | Segment event 1 | 1443 | Result of logical operation 4 |
| 1137 | CT2 short-circuit detection (A2 block) | 1361 | Segment event 2 | 1444 | Result of logical operation 5 |
| 1138 | CT1 short-circuit detection (B2 block) | 1362 | Segment event 3 | 1445 | Result of logical operation 6 |
| 1139 | CT2 short-circuit detection (B2 block) | 1363 | Segment event 4 | 1446 | Result of logical operation 7 |
| 1140 | CT1 short-circuit detection (A1 block) | 1364 | Segment event 5 | 1447 | Result of logical operation 8 |
| 1141 | CT2 short-circuit detection (A1 block) | 1365 | Segment event 6 | 1448 | Result of logical operation 9 |
| 1142 | CT1 short-circuit detection (B1 block) | 1366 | Segment event 7 | 1449 | Result of logical operation 10 |
| 1143 | CT2 short-circuit detection (B1 block) | 1367 | Segment event 8 | 1450 | Result of logical operation 11 |
| 1168 | DI/DO1 terminal status | 1368 | Segment event 9 | 1451 | Result of logical operation 12 |
| 1169 | DI/DO2 terminal status | 1369 | Segment event 10 | 1452 | Result of logical operation 13 |
| 1170 | DI/DO3 terminal status | 1370 | Segment event 11 | 1453 | Result of logical operation 14 |
| 1171 | DI/DO4 terminal status | 1371 | Segment event 12 | 1454 | Result of logical operation 15 |
| 1172 | DI/DO5 terminal status | 1372 | Segment event 13 | 1455 | Result of logical operation 16 |
| 1173 | DI/D06 terminal status | 1373 | Segment event 14 | 1456 | Result of logical operation 17 |
| 1174 | DI/DO7 terminal status | 1374 | Segment event 15 | 1457 | Result of logical operation 18 |
| 1208 | D11 terminal status (A3 block) | 1375 | Segment event 16 | 1458 | Result of logical operation 19 |
| 1209 | DI2 terminal status (A3 block) | 1376 | Segment event 17 | 1459 | Result of logical operation 20 |
| 1210 | DI3 terminal status (A3 block) | 1377 | Segment event 18 | 1460 | Result of logical operation 21 |
| 1211 | DI4 terminal status (A3 block) | 1378 | Segment event 19 | 1461 | Result of logical operation 22 |
| 1212 | D11 terminal status (B3 block) | 1379 | Segment event 20 | 1462 | Result of logical operation 23 |
| 1213 | DI2 terminal status (B3 block) | 1380 | Segment event 21 | 1463 | Result of logical operation 24 |
| 1214 | D13 terminal status (B3 block) | 1381 | Segment event 22 | 1464 | Result of logical operation 25 |
| 1215 | DI4 terminal status (B3 block) | 1382 | Segment event 23 | 1465 | Result of logical operation 26 |
| 1224 | DO1 terminal status (A1 block) | 1383 | Segment event 24 | 1466 | Result of logical operation 27 |
| 1225 | DO2 terminal status (A1 block) | 1384 | Segment event 25 | 1467 | Result of logical operation 28 |
| 1226 | DO3 terminal status (A1 block) | 1385 | Segment event 26 | 1468 | Result of logical operation 29 |
| 1227 | DO4 terminal status (A1 block) | 1386 | Segment event 27 | 1469 | Result of logical operation 30 |
| 1228 | DO1 terminal status (B1 block) | 1387 | Segment event 28 | 1470 | Result of logical operation 31 |
| 1229 | DO2 terminal status (B1 block) | 1388 | Segment event 29 | 1471 | Result of logical operation 32 |
| 1230 | DO3 terminal status (B1 block) | 1389 | Segment event 30 | 1504 | At CDS start |
| 1231 | DO4 terminal status (B1 block) | 1390 | Segment event 31 | 1505 | Loop 1 health index running |
| 1280 | V-P terminal status (A2 block) | 1391 | Segment event 32 | 1506 | Loop 2 health index running |
| 1281 | V-P terminal status (B2 block) | 1408 | User-defined bit 1 | 1507 | Loop 3 health index running |


| Standard <br> bit code | Meaning of the standard bit codes |
| :---: | :--- |
| 1508 | Loop 4 health index running |
| 1517 | Display unit connection status |
| 1518 | Additional display unit connection status |
| 1568 | Loop 1 RUN/READY status |
| 1569 | Loop 2 RUN/READY status |
| 1570 | Loop 3 RUN/READY status |
| 1571 | Loop 4 RUN/READY status |
| 1584 | Loop 1 Auto/manual status |
| 1585 | Loop 2 Auto/Manual status |
| 1586 | Loop 3 Auto/Manual status |
| 1587 | Loop 4 Auto/Manual status |
| 1600 | Loop 1 AT stop/start status |
| 1601 | Loop 2 AT stop/start status |
| 1602 | Loop 3 AT stop/start status |
| 1603 | Loop 4 AT stop/start status |
| 1608 | Loop 1 AT error |
| 1609 | Loop 2 AT error |
| 1610 | Loop 3 AT error |
| 1611 | Loop 4 AT error |
| 1616 | Loop 1 LSP/RSP status |
| 1617 | Loop 2 LSP/RSP status |
| 1618 | Loop 3 LSP/RSP status |
| 1619 | Loop 4 LSP/RSP status |
| 1648 | Loop 1 SP ramp-up in progress |
| 1649 | Loop 2 SP ramp-up in progress |
| 1650 | Loop 3 SP ramp-up in progress |
| 1651 | Loop 4 SP ramp-up in progress |
| 1652 | Loop 1 SP ramp-down in progress |
| 1653 | Loop 2 SP ramp-down in progress |
| 1654 | Loop 3 SP ramp-down in progress |
| 1655 | Loop 4 SP ramp-down in progress |
| 1670 | Loop 1 pattern SP increase change limit in progress |
| 1671 | Loop 2 pattern SP increase change limit in progress |
| 1672 | Loop 3 pattern SP increase change limit in progress |
| 1673 | Loop 4 pattern SP increase change limit in progress |
| 1674 | Loop 1 pattern SP decrease change limit in progress |
| 1675 | Loop 2 pattern SP decrease change limit in progress |
| 1676 | Loop 3 pattern SP decrease change limiti in progress |
| 1677 | Loop 4 pattern SP decrease change limit in progress |
| 1712 | Loop 1 pattern operation mode |


| Standard <br> bit code | Meaning of the standard bit codes |
| :---: | :--- |
| 1713 | Loop 2 pattern operation mode |
| 1714 | Loop 3 pattern operation mode |
| 1715 | Loop 4 pattern operation mode |
| 1720 | Loop 1 HOLD status |
| 1721 | Loop 2 HOLD status |
| 1722 | Loop 3 HOLD status |
| 1723 | Loop 4 HOLD status |
| 1728 | Loop 1 END status |
| 1729 | Loop 2 END status |
| 1730 | Loop 3 END status |
| 1731 | Loop 4 END status |
| 1736 | Loop 1 G. SOAK status |
| 1737 | Loop 2 G. SOAK status |
| 1738 | Loop 3 G. SOAK status |
| 1739 | Loop 4 G. SOAK status |
| 1792 | All typical alarms <br> (logical OR of all alarms be displayed) |
| 1824 | Loop 1 PV low limit error |
| 1825 | Loop 1 PV high limit error |
| 1826 | Loop 1 RSP low limit error |
| 1827 | Loop 1 RSP high limit error |
| 1828 | Loop 2 PV low limit error |
| 1829 | Loop 2 PV high limit error |
| 1830 | Loop 2 RSP low limit error |
| 1831 | Loop 2 RSP high limit error |
| 1832 | Loop 3 PV low limit error |
| 1833 | Loop 3 PV high limit error |
| 1834 | Loop 3 RSP low limit error |
| 1835 | Loop 3 RSP high limit error |
| 1836 | Loop 4 PV low limit error |
| 1837 | Loop 4 PV high limit error |
| 1838 | Loop 4 RSP low limit error |
| 1839 | Loop 4 RSP high limit error |
| 1880 | MFB input error |
| 1884 | Adjusting MFB |
| 1888 | Estimating MFB |
| 1896 | MFB adjustment error |
| 1900 | Motor drive output OPEN |
| 1904 | Motor drive output CLOSE |
| 1920 | Reception monitoring 1 |


| Standard <br> bit code | Meaning of the standard bit codes |
| :---: | :--- |
| 1921 | Reception monitoring 2 |
| 1922 | Reception monitoring 3 |
| 1940 | User-defined alarm 1 |
| 1941 | User-defined alarm 2 |
| 1942 | User-defined alarm 3 |
| 1943 | User-defined alarm 4 |
| 1952 | CT/VT input error (block A2 CT) |
| 1953 | CT/VT input error (block A2 VT) |
| 1954 | CT/VT input error (block B2 CT) |
| 1955 | CT/VT input error (block B2 VT) |
| 1956 | CT/VT input error (block A1 CT) |
| 1957 | CT/VT input error (block A1 VT) |
| 1958 | CT/VT input error (block B1 CT) |
| 1959 | CT/VT input error (block B1 VT) |
| 1960 | CT/CT input error (block A2 CT1) |
| 1961 | CT/CT input error (block A2 CT2) |
| 1962 | CT/CT input error (block B2 CT1) |
| 1963 | CT/CT input error (block B2 CT2) |
| 1964 | CT/CT input error (block A1 CT1) |
| 1965 | CT/CT input error (block A1 CT2) |
| 1966 | CT/CT input error (block B1 CT1) |
| 1967 | CT/CT input error (block B1 CT2) |
| 1973 | Memory error |
| 1977 | Battery error (CLOCK block) |
| 1991 | Block error |
| 1992 | SD card error |
| 1993 | Numerical operation alarm |
| 1994 | Buff. setting alarm |
| 2000 | Block alarm IO failure (block A1) |
| 2001 | Block alarm IO failure (block A2) |
| 2002 | Block alarm IO failure (block A3) |
| 2003 | Block alarm IO failure (block A4) |
| 2004 | Block alarm IO failure (block B1) |
| 2005 | Block alarm IO failure (block B2) |
| 2006 | Block alarm IO failure (block B3) |
| 2007 | Block alarm IO failure (block B4) |
| 2008 | Block alarm HMI block failure |
| 2009 | Block alarm SUB2 block failure (RS-485) |
| 2010 | Block alarm SUB1 block failure (DI DO) |
| 2011 | Block alarm MAIN block failure |

Table 5. List of standard numerical codes
The range of the standard numerical codes is 2048 to 3071.
Codes not listed below are reserved for the system, so do not use them for configuration.

| Standard numerical code No. | Meaning of the standard numerical codes | Standard numerical code No. | Meaning of the standard numerical codes |
| :---: | :---: | :---: | :---: |
| 2048 | Always 0.0 | 2416 | Loop 1 MV |
| 2111 | User-defined value 1 | 2417 | Loop 2 MV |
| 2112 | User-defined value 2 | 2418 | Loop 3 MV |
| 2113 | User-defined value 3 | 2419 | Loop 4 MV |
| 2114 | User-defined value 4 | 2432 | Loop 1 MV for heating |
| 2115 | User-defined value 5 | 2433 | Loop 2 MV for heating |
| 2116 | User-defined value 6 | 2434 | Loop 3 MV for heating |
| 2117 | User-defined value 7 | 2435 | Loop 4 MV for heating |
| 2118 | User-defined value 8 | 2448 | Loop 1 MV for cooling |
| 2119 | User-defined value 9 | 2449 | Loop 2 MV for cooling |
| 2120 | User-defined value 10 | 2450 | Loop 3 MV for cooling |
| 2121 | User-defined value 11 | 2451 | Loop 4 MV for cooling |
| 2122 | User-defined value 12 | 2464 | MFB opening amount (estimated) |
| 2123 | User-defined value 13 | 2472 | MFB opening amount (actual value) |
| 2124 | User-defined value 14 | 2479 | MFB count value |
| 2125 | User-defined value 15 | 2496 | CT1 measured current when output ON (block A2) |
| 2126 | User-defined value 16 | 2497 | CT2 measured current when output ON (block A2) |
| 2127 | User-defined value 17 | 2498 | CT1 measured current when output ON (block B2) |
| 2128 | User-defined value 18 | 2499 | CT2 measured current when output ON (block B2) |
| 2129 | User-defined value 19 | 2500 | CT1 measured current when output ON (block A1) |
| 2130 | User-defined value 20 | 2501 | CT2 measured current when output ON (block A1) |
| 2131 | User-defined value 21 | 2502 | CT1 measured current when output ON (block B1) |
| 2132 | User-defined value 22 | 2503 | CT2 measured current when output ON (block B1) |
| 2133 | User-defined value 23 | 2512 | CT1 measured current when output OFF (block A2) |
| 2134 | User-defined value 24 | 2513 | CT2 measured current when output OFF (block A2) |
| 2135 | User-defined value 25 | 2514 | CT1 measured current when output OFF (block B2) |
| 2136 | User-defined value 26 | 2515 | CT2 measured current when output OFF (block B2) |
| 2137 | User-defined value 27 | 2516 | CT1 measured current when output OFF (block A1) |
| 2138 | User-defined value 28 | 2517 | CT2 measured current when output OFF (block A1) |
| 2139 | User-defined value 29 | 2518 | CT1 measured current when output OFF (block B1) |
| 2140 | User-defined value 30 | 2519 | CT2 measured current when output OFF (block B1) |
| 2141 | User-defined value 31 | 2528 | Loop 1 deviation (PV - SP) |
| 2142 | User-defined value 32 | 2529 | Loop 2 deviation (PV - SP) |
| 2288 | Virtual Al1 | 2530 | Loop 3 deviation (PV - SP) |
| 2289 | Virtual Al2 | 2531 | Loop 4 deviation (PV - SP) |
| 2290 | Virtual Al3 | 2544 | CT input value (block A2) |
| 2291 | Virtual AI4 | 2545 | CT input value (block B2) |
| 2296 | Virtual PV1 | 2546 | CT input value (block A1) |
| 2297 | Virtual PV2 | 2547 | CT input value (block B1) |
| 2298 | Virtual PV3 | 2548 | VT input value (block A2) |
| 2299 | Virtual PV4 | 2549 | VT input value (block B2) |
| 2304 | AI (block A4) | 2550 | VT input value (block A1) |
| 2305 | Al (block B4) | 2551 | VT input value (block B1) |
| 2306 | Al (block A3) | 2552 | Resistance (block A2) |
| 2307 | Al (block B3) | 2553 | Resistance (block B2) |
| 2312 | PV (block A4) | 2554 | Resistance (block A1) |
| 2313 | PV (block B4) | 2555 | Resistance (block B1) |
| 2314 | PV (block A3) | 2656 | Event 1 timer remaining time |
| 2315 | PV (block B3) | 2657 | Event 2 timer remaining time |
| 2320 | Loop 1 PV | 2658 | Event 3 timer remaining time |
| 2321 | Loop 2 PV | 2659 | Event 4 timer remaining time |
| 2322 | Loop 3 PV | 2660 | Event 5 timer remaining time |
| 2323 | Loop 4 PV | 2661 | Event 6 timer remaining time |
| 2336 | Loop 1 SP (in use) | 2662 | Event 7 timer remaining time |
| 2337 | LOOP2 SP (in use) | 2663 | Event 8 timer remaining time |
| 2338 | Loop 3 SP (in use) | 2664 | Event 9 timer remaining time |
| 2339 | Loop 4 SP (in use) | 2665 | Event 10 timer remaining time |
| 2352 | Loop 1 SP (final value) | 2666 | Event 11 timer remaining time |
| 2353 | Loop 2 SP (final value) | 2667 | Event 12 timer remaining time |
| 2354 | Loop 3 SP (final value) | 2668 | Event 13 timer remaining time |
| 2355 | Loop 4 SP (final value) | 2669 | Event 14 timer remaining time |
| 2368 | Loop 1 current LSP | 2670 | Event 15 timer remaining time |
| 2369 | Loop 2 current LSP | 2671 | Event 16 timer remaining time |
| 2370 | Loop 3 current LSP | 2736 | CT1 Time proportioning current (block A2) |
| 2371 | Loop 4 current LSP | 2737 | CT2 Time proportioning current (block A2) |
| 2384 | Loop 1 RSP | 2738 | CT1 Time proportioning current (block B2) |
| 2385 | Loop 2 RSP | 2739 | CT2 Time proportioning current (block B2) |
| 2386 | Loop 3 RSP | 2740 | CT1 Time proportioning current (block A1) |
| 2387 | Loop 4 RSP | 2741 | CT2 Time proportioning current (block A1) |


| Standard numerical code No. | Meaning of the standard numerical codes |
| :---: | :---: |
| 2742 | CT1 Time proportioning current (block B1) |
| 2743 | CT2 Time proportioning current (block B1) |
| 2752 | Loop 1 definite R value |
| 2753 | Loop 2 definite R value |
| 2754 | Loop 3 definite $R$ value |
| 2755 | Loop 4 definite $R$ value |
| 2760 | Loop 1 R value |
| 2761 | Loop 2 R value |
| 2762 | Loop 3 R value |
| 2763 | Loop 4 R value |
| 2768 | AO-C percent output value (block A2) |
| 2769 | AO-C percent output value (block B2) |
| 2770 | AO-C percent output value (block A1) |
| 2771 | AO-C percent output value (block B1) |
| 2776 | V-P percent output value (block A2) |
| 2777 | V-P percent output value (block B2) |
| 2778 | V-P percent output value (block A1) |
| 2779 | V-P percent output value (block B1) |
| 2787 | TP percent output value (DO4) |
| 2788 | TP percent output value (DO5) |
| 2789 | TP percent output value (DO6) |
| 2790 | TP percent output value (DO7) |
| 2800 | Result of numerical operation 1 |
| 2801 | Result of numerical operation 2 |
| 2802 | Result of numerical operation 3 |
| 2803 | Result of numerical operation 4 |
| 2804 | Result of numerical operation 5 |
| 2805 | Result of numerical operation 6 |
| 2806 | Result of numerical operation 7 |
| 2807 | Result of numerical operation 8 |
| 2808 | Result of numerical operation 9 |
| 2809 | Result of numerical operation 10 |
| 2810 | Result of numerical operation 11 |
| 2811 | Result of numerical operation 12 |
| 2812 | Result of numerical operation 13 |
| 2813 | Result of numerical operation 14 |
| 2814 | Result of numerical operation 15 |
| 2815 | Result of numerical operation 16 |
| 2816 | Result of numerical operation 17 |
| 2817 | Result of numerical operation 18 |
| 2818 | Result of numerical operation 19 |
| 2819 | Result of numerical operation 20 |
| 2820 | Result of numerical operation 21 |
| 2821 | Result of numerical operation 22 |
| 2822 | Result of numerical operation 23 |
| 2823 | Result of numerical operation 24 |
| 2824 | Result of numerical operation 25 |
| 2825 | Result of numerical operation 26 |
| 2826 | Result of numerical operation 27 |
| 2827 | Result of numerical operation 28 |
| 2828 | Result of numerical operation 29 |
| 2829 | Result of numerical operation 30 |
| 2830 | Result of numerical operation 31 |
| 2831 | Result of numerical operation 32 |



| Symbol | Block Name | Description | *1. A integrated mounting bracket and a dedicated cable for connecting the display unit are included with the product. <br> *2. RSP1 can be switched for use as PV3. |
| :---: | :---: | :---: | :---: |
| AI | Analog Input | Full-multi range (thermocouple, RTD, DC current, DC voltage) input × 1 |  |
| V-P | Voltage pulse output | Voltage pulse output ( 12 V DC) $\times 1$ <br> Input terminals for the current transformer (CT) for detecting heater burnout, overcurrent, and short circuit are included ( $\times 2$ ). ${ }^{* 4}$ |  |
| AO-C | Analog current output | Current output ( $4-20 \mathrm{~mA} \mathrm{DC} \mathrm{/} \mathrm{0-20} \mathrm{~mA} \mathrm{DC)} \times 1$ <br> Input terminals for the current transformer (CT) for measuring current and the voltage transformer (VT) for measuring voltage are included ( 1 each).*4 |  |
| HMI2 | Additional display unit | Additional connector for the second display unit *5 |  |
| CLOCK | Clock function | Clock (available for CDS and health index) with a battery | *4. Current transformer (CT) and voltage transformer |
| DI | Digital input | 4 digital inputs (external power required) | are sold separately. |
| DO | Digital output | 4 digital outputs (sink output) | *5. Additional display unit is sold separately |

- Recommended models

| Current output | 1 output |  | 2 outputs |  |  | 3 outputs |  |  | 4 outputs |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8-9th digits | CO |  | CC |  |  | FC |  |  | FF |  |  |
| Layout |  | ① <br> (2) | (A) |  | ① <br> 2 | A <br> AO-C <br> AO-C | (B) <br> AO-C | $1$ | (A) <br> AO-C <br> AO-C | 18 <br> AO-C <br> AO-C | $\left\{\begin{array}{l}\text { (1) } \\ \text { 22 }\end{array}\right.$ |
| Analog Input | 1 input |  | 2 inputs |  |  | 3 inputs |  |  | 4 inputs |  |  |
| $\begin{aligned} & \text { 6-7th } \\ & \text { digits } \end{aligned}$ | 10 |  | 11 |  |  | 21 |  |  | 22 |  |  |
| Layout | (A) [B] |  | (A) (B) |  |  | (A) (B) |  | 3 | (A) | A (B) |  |
|  | 3 |  |  |  | 3 | AI |  |  | AI | AI | 3 |
|  | AI | 4 | AI | AI | 4. | Al | AI | (4) | AI | AI | (4) |

## - Block layout example



| Main unit |  |  |  |  | I/O slot |  |  |  | Other |  |  |  | Description |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Basic model No. |  |  | Comm. | Size | $\begin{gathered} \text { Slot } \\ \text { A4 } \end{gathered}$ | $\begin{gathered} \text { Slot } \\ \text { B4 } \end{gathered}$ | Slots <br> A2-3, <br> B2-3 | $\begin{aligned} & \text { Slots } \\ & \text { A1, B1 } \end{aligned}$ | Option | Add'I proc. | Add'I spec. | Special support |  |  |  |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 |  |  |  |
| C | 7 | G |  |  |  |  |  |  |  |  |  |  | Multi-loop controller with multifunction display |  |  |
|  |  |  | A |  |  |  |  |  |  |  |  |  | Communications (Ethernet, RS-485, USB), DI/DO ( $\times 7$, sink output, source input) |  |  |
|  |  |  |  | 3 |  |  |  |  |  |  |  |  | Integrated mounting*1 |  |  |
|  |  |  |  | 4 |  |  |  |  |  |  |  |  | Standard (separate) mounting |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  | Slot A4 |  |
|  |  |  |  |  | 1 |  |  |  |  |  |  |  | PV1 (full-multi) | AI |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  | Slot B4 |  |
|  |  |  |  |  |  | 0 |  |  |  |  |  |  | None |  |  |
|  |  |  |  |  |  | 1 |  |  |  |  |  |  | PV2 (full-multi) *2 | AI |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  | Slots A2-3, B2-3 |  |
|  |  |  |  |  |  |  | M |  |  |  |  |  | Motor drive output (with MFB input) | MOTOR |  |
|  |  |  |  |  |  |  |  | 0 |  |  |  |  |  | Slot A1 Slot B1 $^{\text {B }}$ |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  | None |  |  |
|  |  |  |  |  |  |  |  | C |  |  |  |  | Current output (CT and VT inputs, 1 each) $\times 1$ | AO-C |  |
|  |  |  |  |  |  |  |  | V |  |  |  |  | Voltage pulse output (2 CT inputs) $\times 1$ | V-P |  |
|  |  |  |  |  |  |  |  | N |  |  |  |  | Current output (CT and VT inputs, 1 each) + voltage pulse output (2 CT inputs) | AO-C | V-P |
|  |  |  |  |  |  |  |  | G |  |  |  |  | Current output (CT and VT inputs, 1 each) + additional display unit | AO-C | HMI2 |
|  |  |  |  |  |  |  |  | L |  |  |  |  | Current output (CT and VT inputs, 1 each) + clock (with battery) | AO-C | CLOCK |
|  |  |  |  |  |  |  |  | 1 |  |  |  |  | Current output (CT and VT inputs, 1 each) + DO ( $\times 4$ ) (sink output) | AO-C | DO |
|  |  |  |  |  |  |  |  | 4 |  |  |  |  | DO ( $\times 4$ ) (sink output) + clock (with battery) | DO | CLOCK |
|  |  |  |  |  |  |  |  |  | 0 |  |  |  | None |  |  |
|  |  |  |  |  |  |  |  |  |  | 0 |  |  | None |  |  |
|  |  |  |  |  |  |  |  |  |  | D |  |  | With inspection report |  |  |
|  |  |  |  |  |  |  |  |  |  | Y |  |  | With traceability certificate |  |  |
|  |  |  |  |  |  |  |  |  |  |  | 0 |  | AC power. CE, KC, UKCA-compliant |  |  |
|  |  |  |  |  |  |  |  |  |  |  | D |  | DC power. CE, KC, UKCA-compliant |  |  |
|  |  |  |  |  |  |  |  |  |  |  | A |  | AC power. CE, KC, UKCA, UL-compliant |  |  |
|  |  |  |  |  |  |  |  |  |  |  | B |  | DC power. CE, KC, UKCA, UL-compliant |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  | 0 | No special support |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  | F | Overseas models: switchable between Celsius/Fahrenheit Do not use these models in Japan. |  |  |


| Symbol | Block Name | Description |
| :---: | :---: | :--- |
| AI | Analog Input | Full-multi range (thermocouple, RTD, DC current, DC voltage) input $\times 1$ |
| V-P | Voltage pulse output | Voltage pulse output (12 V DC) $\times 1$ <br> Input terminals for the current transformer (CT) for detecting heater burnout, overcurrent, <br> and short circuit are included ( $\times 2$ 2). *3 |
| AO-C | Analog current output | Current output (4-20 mA DC / 0-20 mA DC) $\times 1$ <br> Input terminals for the current transformer (CT) for measuring current and the voltage <br> transformer (VT) for measuring voltage are included (1 each). *3 |
| MOTOR | Motor drive output | Motor drive output (100/200 V AC) forward (OPEN) output, reverse (CLOSE) output <br> with MFB (motor feedback) input |
| HMI2 | Additional display unit | Additional connector for the second display unit *4 |
| CLOCK | Clock function | Clock (available for CDS and health index) with a battery |
| DO | Digital output | 4 digital outputs (sink output) |

*1. A integrated mounting bracket and a dedicated cable for connecting the display unit are included with the product.
2. PV2 can be switched for use as RSP1
3. Current transformer (CT) and voltage transformer (VT) are sold separately.
4. Additional display unit is sold separately.

Block layout example
(A) B

(A) B


## Option parts

■ Additional display unit (sold separately)

$\square$ Service parts (sold separately)

| Part name | Model No. |
| :--- | :---: |
| SLP-C7 Smart Loader Package (free version) ${ }^{* 1}$ | SLP-C7FJ91 |
| SLP-C7 Smart Loader Package (paid version) | SLP-C7-J91 |
| Power terminal covers (10) | $\mathbf{8 1 4 4 7 7 0 4 - 0 0 1}$ |
| C7 (display unit) mounting method change kit *2 | $\mathbf{8 4 5 0 3 1 6 7 - 0 0 1}$ |
| MicroSD card (for replacement) | $\mathbf{8 4 5 0 2 5 5 2 - 0 0 1}$ |
| CLOCK block (for replacement) *3 | $\mathbf{8 4 5 0 1 4 2 0 - 0 0 1}$ |
| MOTOR block (for replacement) *3 | 84501421-001 |
| Current transformer (5.8 mm in diameter) | QN206A |
| Current transformer (12 mm in diameter) | QN212A |
| Voltage transformer (for 200 V AC) | $\mathbf{8 1 4 0 6 7 2 5 - 0 0 3}$ |

*1. Downloadable from our website
https://www.azbil.com/products/factory/factory-product/controller-recorder/controller/index.html
*2. A integrated mounting bracket, a dedicated cable for connecting the display unit, and standard gasket,gasket with $92 \times 92 \mathrm{~mm}$ hole are included with the product.
*3. Mounting bracket for replacement is included.

## Accessories

| Applicable <br> model No. | Part name | Qty. | Remarks |
| :---: | :--- | :---: | :---: |
| C7G__4 | Standard gasket | 1 | For the display unit |
|  | Display unit mounting screws $(6 \mathrm{~mm})$ | 5 |  |
|  | Display unit mounting screws $(10 \mathrm{~mm})$ | 5 |  |
|  | Set screws (for securing temporarily) | 2 |  |
| C7G _ 3 | Gasket with $92 \times 92$ mm hole | 1 |  |
|  | Integrated-mounting bracket | 1 |  |
|  | Display unit mounting screws $(6 \mathrm{~mm})$ | 5 |  |
|  | Integrated-mounting cable | 1 |  |

Model No. and loop type
The following table shows the possible combinations of model No. and loop type with regard to analog input.

OK: Combination is possible
$\Delta$ : Possible when the advanced loop type setting is enabled.

PV1: LOOP1 PV
PV2: LOOP2 PV
PV3: LOOP3 PV
PV4: LOOP4 PV

RSP1: RSP for loop 1
RSP2: RSP for loop 2
RSP3: RSP for loop 3
RSP4: RSP for loop 4
Unused: Although an analog input of the AI block is present, it is not assigned to the PV or RSP of the loop.

| Loop type | 6th and 7th digits of the model No. (C7GA |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 10/A0 | 20 | 11/1A/1B/A1/AA/AB | 21/2A/2B | 22 |
| $\text { 0: } 1 \text { loop }$ | OK <br> A4: PV1 | OK <br> A4: PV1 <br> A3: Not used | OK <br> A4: PV1 <br> B4: Not used | OK <br> A4: PV1 <br> A3: Not used <br> B4: Not used | OK <br> A4: PV1 <br> A3: Not used <br> B4: Not used <br> B3: Not used |
| 1: 1 loop, 1 RSP | $\Delta$ | OK <br> A4: PV1 <br> A3: RSP1 | $\Delta$ | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: Not used | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: Not used <br> B3: Not used |
| 2: 2 loops | $\Delta$ | $\Delta$ | A4: PV1 B4: PV2 | OK <br> A4: PV1 <br> A3: Not used <br> B4: PV2 | OK <br> A4: PV1 <br> A3: Not used <br> B4: PV2 <br> B3: Not used |
| 3:2 loops, 1 RSP | $\Delta$ | $\Delta$ | $\Delta$ | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: PV2 | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: PV2 <br> B3: Not used |
| 4: 2 loops, 2 RSPs | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: PV2 <br> B3: RSP2 |
| 5: 3 loops | $\Delta$ | $\Delta$ | $\Delta$ | OK <br> A4: PV1 <br> A3: PV3 <br> B4: PV2 | OK <br> A4: PV1 <br> A3: PV3 <br> B4: PV2 <br> B3: Not used |
| 6: 3 loops, 1 RSP | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ | OK <br> A4: PV1 <br> A3: PV3 <br> B4: PV2 <br> B3: RSP2 |
| 7: 4 loops | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ | OK <br> A4: PV1 <br> A3: PV3 <br> B4: PV2 <br> B3: PV4 |


| Loop type |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 10/A0 | 20 | 11/1A/1B/A1/AA/AB | 21/2A/2B | 22 |
| 8: 1 loop, 1 RSP | $\Delta$ | $\Delta$ | OK <br> A4: PV1 <br> B4: RSP1 | $\Delta$ | $\Delta$ |
| 9: Internal cascade | $\Delta$ | $\Delta$ | OK <br> A4: PV1 (master) <br> B4: PV2 (slave) | OK <br> A4: PV1 (master) <br> A3: None <br> B4: PV2 (slave) | OK <br> A4: PV1 (master) <br> A3: None <br> B4: PV2 (slave) <br> B3: None |
| 10: Internal cascade +1 loop | $\Delta$ | $\Delta$ | $\Delta$ | OK <br> A4: PV1 (master) <br> A3: PV3 <br> B4: PV2 (slave) | OK <br> A4: PV1 (master) <br> A3: PV3 <br> B4: PV2 (slave) <br> B3: None |
| 11: Internal cascade +2 loops | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ | OK <br> A4: PV1 (master) <br> A3: PV3 <br> B4: PV2 (slave) <br> B3: PV4 |
| 12: Internal cascade, 1 RSP | $\Delta$ | $\Delta$ | $\Delta$ | OK <br> A4: PV1 (master) <br> A3: RSP1 <br> B4: PV2 (slave) | OK <br> A4: PV1 (master) <br> A3: RSP1 <br> B4: PV2 (slave) <br> B3: None |
| 20: 3 loops, 3 RSPs | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ |
| 21: 4 loops, 4 RSPs | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ |
| 22: Internal cascade +2 loops, 3 RSPs | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ |
| 23:2 internal cascades, 2 RSPs | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ | $\Delta$ |

! Handling Precautions

- The value of an unused AI cannot be displayed. To display the value of the AI, even if it is not a control target, assign it to PV in the loop type. However, since the AI is actually not controlled, it is not necessary to assign the MV to the analog output or DI/DO.
- If the advanced loop type setting is enabled for [Loop type], any loop type can be selected regardless of the model number.


## External Dimensions

Standard Installation
(Unit: mm)


Integrated Installation
(Unit: mm)


## Part Names and Functions

## - Display unit



- Integrated mounting bracket (included with integrated mounting models)



## I/O isolation

| Power input |  | C | Internal circuit | Motor drive output | Motor |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | DC | Frame ground |  | MFB input | block |
| DI/DO block |  |  |  | Al block |  |
|  |  | DO |  |  |  |
| LAN |  |  |  | AO-C block |  |
|  |  |  | Analog VT | CT input |
| RS-485 block |  |  |  | V-P block |  |
|  |  |  | $\|$Voltage, $\mid,-----\quad$ CT1 <br> pulse <br> output <br> out | CT2 |
| USB |  |  |  | CLOCK block |  |
| HMI block |  |  |  | HMI2 block |  |
| DI block |  |  |  | DO block |  |

[^1]- Main unit



## Wiring Precautions

Before touching the main unit or display unit, or removing/ inserting cables, touch a grounded panel to discharge static electricity from your body.

## - Power input

AC power


DC power
1: DC power +
2: DC power -


3: Frame ground

## ! Handling Precautions

- Before touching the power input terminal box, shut off the input power.
- After completing the work, be sure to put the cover on the power input terminal block.
Note: For power input use crimp terminals for M4 screws (max. width 8.5 mm ). Proper tightening torque: $1.4 \mathrm{~N} \cdot \mathrm{~m}$

DI/DO Block (7 digital input/outputs, input/ output selectable)
Either digital input or digital output (sink output) can be specified for each of terminals N1 to N7.
In the following wiring example, terminals $\mathrm{N} 1-\mathrm{N} 4$ are used for digital input and N5-N7 are used for digital output.

- : N.C. (Do not connect to this terminal.)

N1: Digital input 1
N2 : Digital input 2
N3: Digital input 3
N4 : Digital input 4
N5: Digital output 5
N6: Digital output 6
N7: Digital output 7
V- : COM (common terminal)


## RS-485 Block

When connecting to the middle of the communication wire
C1: DA (+)
C2 : —— DA (+)
C3: DB (-)
C4: ——DB (-)
C5: SG
C 1 and C2, and C3 and C4, are electrically continuous inside the port.

## ! Handling Precautions

- Connect a terminating resistor ( $120 \Omega, 1 / 2 \mathrm{~W}$ ) to both ends of the communication line. If a resistor with leads is used, insert the leads directly without using ferrules. Do not connect a terminating resistor to the middle part of the communication line.
- To connect two terminals together such as SG, use a crimp terminal without an insulation sleeve.

AI Block (analog input)


Allowable input voltage
DC current input: -1.5 to +1.5 V
DC voltage input: -15 to +15 V
Thermocouple input: -1.5 to +1.5 V

## AO-C Block (current outputs / CT, VT inputs)

1: CT input
2 : CT/VT common
3 : VT input


4 : Current output +


5 : Current output -
Maximum allowable input
CT: 90 mA AC and 130 mA peak, 1 V AC and 1.4 V peak
VT: 18 V AC and 26 V peak
Transient overvoltage
CT: supply voltage +250 V

## $!$ Handling Precautions

- If using a current transformer with the UL model of this product, use a UL 2808-certified product in the UL XOBA or XOBA7 category. An uncertified current transformer cannot be used with the UL model.

■ V-P Block (voltage pulse outputs / 2 CT inputs)
1: CT1 input
$2:$ CT common
3 : CT2 input


5 : Voltage pulse output -
Maximum input
CT: 90 mA AC and 130 mA peak, 1 V AC and 1.4 V peak
Transient overvoltage
CT: supply voltage +250 V
Load current:
Voltage pulse output: 25 mA max.

## ! Handling Precautions

- If a current transformer is used for a UL-compliant model, the transformer must be compliant with UL 2808 (categories XOBA and XOBA7). Do not use an uncertified current transformer.


## ■ DI Block (4 digital inputs)

1 : Digital input 1
2 : Digital input 2
3 : Digital input 3
4 : Digital input 4
5 : COM (common terminal)


## ■ DO Block (4 digital outputs, sink output)

1 : Digital output 1
2 : Digital output 2
3 : Digital output 3
4 : Digital output 4
5 : COM (common terminal)


■ MOTOR Block (motor drive outputs and motor feedback inputs)


For models other than UL-compliant models
$2 \mathrm{~A}, 250 \mathrm{~V} \mathrm{AC}$ (inductive load)
$2.5 \mathrm{~A}, 24 \mathrm{~V}$ DC (inductive load)
For UL-compliant models
$2 \mathrm{~A}, 250 \mathrm{~V} \mathrm{AC}$ (general use)
FLA: 2A, 240 V AC (100 W)
Potentiometer for motor feedback 100 to $2500 \Omega$

## ! Handling Precautions

- UL-compliant models cannot be used at the 24 V DC contact rating.
- For the motor connection, use cables with a rated voltage of 300 V or more and a rated temperature of at least $60^{\circ} \mathrm{C}$.

■ Ferrules
For details about the types and sizes of ferrules, see the table below.
Manufacturer: Phoenix Contact
Crimping tool: CRIMPFOX 6

- The use of ferrules to connect the I/O signal lines of this device is recommended.
- If you do not use ferrules, use the following types of wire.
DI/DO, RS-485, AI, AO-C, V-P, DI, DO:
Use 0.2 to $1.5 \mathrm{~mm}^{2}$ solid or stranded wire and strip off 8 mm of insulation.
Display unit:
Use 0.2 to $0.5 \mathrm{~mm}^{2}$ solid or stranded wire and strip off 6 mm of insulation.
- If using stranded wire, do not solder the end of the wire.
Insert it while pressing the release button straight with a flat-blade screwdriver.

DI/DO, RS-485, AI, AO-C, V-P, DI, DO

| Model number | Product number | Cross section area [ $\mathrm{mm}^{2}$ ] | Notes |
| :---: | :---: | :---: | :---: |
| AI 0,25-8 YE | 3203037 | 0.25 (24 AWG) | With insulating sleeve |
| AI 0,34-8-TQ | 3203066 | 0.34 (22 AWG) | With insulating sleeve |
| AI 0,5-8 WH | 3200014 | 0.50 (20 AWG) | With insulating sleeve |
| Al 0,75-8 GY | 3200519 | 0.75 (18 AWG) | With insulating sleeve |
| A1-8 | 3202517 | 1.00 (18 AWG) | Without insulating sleeve. For crimping two wires, each $0.5 \mathrm{~mm}^{2}$ (in crosssectional area), together |
| A1,5-7 | 3200263 | 1.50 (16 AWG) | Without insulating sleeve. For crimping two wires, each $0.75 \mathrm{~mm}^{2}$ (in crosssectional area), together |
| AI-TWIN $2 \times 0$, 5-8 WH | 3200933 | 0.50 (20 AWG) | With insulating sleeve. For crimping two wires, each $0.5 \mathrm{~mm}^{2}$ (in crosssectional area), together |
| $\begin{aligned} & \text { AI-TWIN 2x0, } \\ & 75-8 \mathrm{GY} \end{aligned}$ | 3200807 | 0.75 (18 AWG) | With insulating sleeve. For crimping two wires, each $0.75 \mathrm{~mm}^{2}$ (in crosssectional area), together |

## MOTOR

| Model number | Product number | Cross sectional area [ $\mathrm{mm}^{2}$ ] | Notes |
| :---: | :---: | :---: | :---: |
| AIO,75-8 BU | 3200027 | 0.75 (18 AWG) | With insulating sleeve |
| Al1-8 RD | 3200030 | 1.00 (18 AWG) | With insulating sleeve |
| Al1,5-8 RD | 3201136 | 1.50 (16 AWG) | With insulating sleeve |
| AI2,5-10 BU | 3202533 | 2.00(14 AWG) | With insulating sleeve |

HMI (display unit)

| Model number | Product <br> number | Cross sectional <br> area $\left[\mathrm{mm}^{2}\right]$ | Notes |
| :--- | :---: | :---: | :--- |
| AI 0,25-6 YE | 3203024 | $0.25(24$ AWG $)$ | Without insulating sleeve <br> When connecting an <br> external power supply <br> to the terminal block of <br> display unit. |

## - USB connection

Connect the device to the PC using a USB-MicroUSB cable (type A/B).

## Note

- Use a data communication cable.

Inserting/removing micro SD Memory Card
To insert the card, push it all the way in. To eject the card, press it slightly.

## ! Handling Precautions

- Do not insert or remove the card while the indicator near the connector is on.
- To avoid danger, shut off the power supply before inserting/removing a microSD because it is located near the power supply terminal.


## - LAN Cable for Ethernet

Use a LAN cable of Cat5E or higher for connection.

## - Connecting Main Unit and Display Unit

- For standard installation and additional display unit (cable length: less than 30 m )
Use a Cat5E or higher straight LAN cable to connect them. (Cat5E, T568A or T568B wiring, both ends RJ45 plug (8P8C modular))
Note 1. The main unit and display unit cannot be connected with a 4 -core LAN cable.

2. If the length of the cable between the main unit and the display unit is from 30 m to 100 m , an external power source must be connected for the display.
B the User's Manual for C7G Multi-loop Controller with Multifunction Display, No.CP-SP-1402E, (see Relevant USER'S Manual) for details.

## - Wiring for integrating installation

Insert the ferrules (part of the cable for integrated mounting supplied with the product) with the specified colors into the terminal block of the display unit.

| 1: White/orange | 4:White/green |
| :--- | :--- |
| 2: Blue | 5: Green |
| 3: White/blue | 6: Brown |

## Operation Check

When the power is turned on after connecting the main unit and display unit, the display turns on. The screen first displayed after power-on is called the initial screen.

- Display change button: Switches displays
- HOME button: Returns to the initial screen
- MENU/Key lock button:Displays a menu. Pressing the button for four seconds or longer leads to a key lock status in which only disabling of the key lock can be performed. Pressing the button for four seconds or longer again disables the key lock.


## Troubleshooting

## ■ Model Number and Serial Number

Model number and serial number are printed on the front of the upper part of the main unit. Please refer to them when making an inquiry.

## ■ Handling Problems in Installation

First, check the following regarding wiring
Connectors are securely inserted into the ports.
Connectors are inserted into the right ports.

- Wires are properly connected to the power terminal block.

Power is not turned on

| Status | Countermeasures |
| :--- | :--- |
| The status indicator on the <br> main unit is off. | Check the the power input connections <br> and voltage. |
| The status indicator on <br> the main unit is lit green or <br> the power indicator on the <br> display unit is off. | Standard mounting: <br> Check the LAN cable (8-core straight). <br> Check the connectors. <br> Integrated mounting: <br> Check if the wiring on the back of <br> the display unit is correct. Check <br> connectors on the main unit. |
| The power indicator on the <br> display unit is lit green and <br> the LCD remains black. | There may be a problem with the device. <br> Please contact us. |
| The status indicator on the <br> main unit is lit red. | There may be a problem with the device. <br> Please contact us. |

## - Blurry images on display

A thin protective film is sealed on the display to protect the product label in transportation. Remove the protective film. If it is hard to remove the film, use cellophane tape.

## - Occurrence of an alarm

B Multi-loop Controller with Multifunction Display Model C7G Installation and Configuration Manual, No. CP-SP-1402E.

MEMO

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[^0]:    * It is necessary to configure the settings for the health index.

    Start the CDS and health index at the start of batch processing, and stop the CDS and health index when batch processing ends.

[^1]:    Reinforced insulation
    $\square$ Functional isolation
    [---------------------- No isolation

