Specification

Multi-loop Controller with Multifunction Display Model C7G

Overview

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The C7G multi-loop controller with multifunction display can calculate diagnostic parameters (a health index) that help to predict the failure of connected equipment, in addition to calculations for PID control of process variables such as temperature, pressure, flow rate, pH, and liquid level.

The controller consists of a display unit with a 3.5-inch QVGA LCD touchscreen and a main unit capable of controlling up to four loops with an input sampling cycle of 10 ms and an indication accuracy of ± 0.1 % FS.

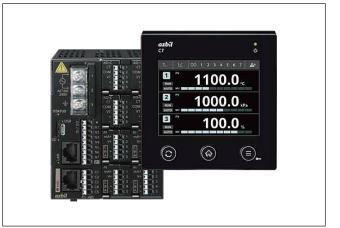
The display unit and main unit can be installed separately for installation flexibility and longer service life of the display unit in the case of a harsh environment.

A wide variety of interfaces, including Ethernet, RS-485 serial communication, microSD card, Micro USB port, and 7 digital input/outputs are provided as standard features.

Setup, operation, and monitoring can be easily accomplished using the display unit and Smart Loader Package.

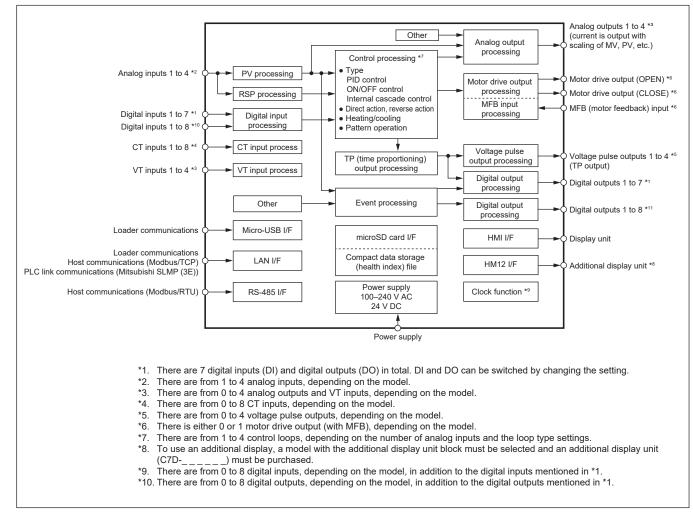
Features

- High-speed and high-accuracy control is available with an input sampling cycle as fast as 10 ms and an indication accuracy of \pm 0.1 % FS. Process data can be stored with the compact data storage function (microSD card).
- Diagnostic and management information is created with our unique process data-processing technology (the health index function).
- One module can execute PID control for up to 4 loops.
- Various information is displayed on a 3.5-inch QVGA LCD with easy touchscreen operation.
- The display unit and main unit can be installed separately. Standard distance: less than 30 m
 If display unit is separately powered: 30 to 100 m



- Protective structure of display face: IP67
- Ethernet and RS-485 serial communication (Modbus) is supported as a standard feature.
- For setup and file management the SLP-C7 Smart Loader Package can be used.
- The C7G is powered through a Micro-USB cable, and parameters can be set using the Smart Loader Package even if the controller's power is off.

C7G Basic Functional Blocks



Specifications

Display unit (included) Additional display unit		Screen specifications	3.5-inch QVGA LCD
Additional display unit (C7D)		Status display (LED)	1 (power)
		Operation buttons	Touchscreen (resistive) and 3 hardware buttons
		Power for display unit	Power from main unit if distance from main unit (display unit connector / additional display unit block) to display unit is less than 30 m Power from external power source (5 V DC) if distance from main unit (display unit connector / additional display unit block) to display unit is
		Protection rating	IP67 (front of display unit only)
		Interface language	English/Japanese (switchable)
		Service life of LCD	5 years (at ambient temperature of 25 $^\circ\mathrm{C}$ and brightness setting 4, for half-life of back-light brightness)
DI (digital inp DO (digital ou		No. of I/Os	7 max. (select DI, DO, or TP by setting), shared common Note: TP (time proportioning output) can be selected for output Nos. 4 to 7.
block	Digital	Compatible output type	Non-voltage contacts or open collector (sink type)
	input	Open terminal voltage	7 V max.
		Terminal current (when shorted)	1 mA (under standard conditions)
		On-state contact resis- tance (no-voltage contact)	500 Ω max. (under standard conditions)
		Off-state contact resis- tance (no-voltage contact)	100 k Ω max. (under standard conditions)
		Allowable on-state residual voltage for open collector	1 V max. (under standard conditions)
		Allowable off-state residual current for open collector	100 μA max. (under standard conditions)
		Input sampling cycle	10 ms
		Minimum pulse width for ON detection	20 ms min. (10 ms sampling cycle), 50 ms min. (50 ms sampling cycle), 100 ms min. (100 ms sampling cycle)
		Function assignment	LSP group selection, PID group selection, PV hold, fixed value output group selection, output linearization table group selection, switching of: RUN/READY*, AUTO/MANUAL* LSP/RSP*, AT stop/start, control operation forward/reverse, Timer stop/start selection, Release all latches, RUN selection*, READY selection*, AUTO selection*, MANUAL se- lection*, Constant value operation / Pattern operation mode selection* / pattern opera- tion*; ADVANCE*, HOLD*, G. SOAK cancellation, pattern selection. * indicates edge specification function
	Digital	Output method	Open collector (sink type)
	output	Load voltage	4.5 to 28.8 V DC
		Maximum load current	100 mA for each terminal
		Overcurrent detection	130 mA or more When an overcurrent is detected, output is turned OFF and the status is checked every 5 seconds. If the status returns to normal, the output automatically returns to normal.
		On-state residual voltage	0.5 V max. (under standard conditions)
		Off-state leak current	100 μA max. (under standard conditions)
		Function assignment	Select an event status or a standard bit code
	Time propor-	Output method	Same as digital output
	tional output	Number of outputs	4 max. (DI/DO terminals 4 to 7)
(ТР)		Min. OFF time / ON time	1 ms when time proportional cycle is less than 10 s. 250 ms when time proportional cycle is 10 s or more

Al block		Input type	Full multi-range for thermocouple, resistance temperature detector (RTD), DC current, and DC voltage	
		No. of control loops	4 loops max. (configurable by the loop type setting)	
		Range type	🕞 Table 1. Input types and ranges (p.10)	
Sampling cycle Burnout Over-range judg		Sampling cycle	10 ms, 50 ms, 100 ms (factory default: 50 ms)	
		Burnout	Depends on the input range (Table 1. Input types and ranges (p.10))	
			Below -10 % or above 110 % of the range	
		Decimal point position	0 to 4 digits after the decimal point are displayed. Values are displayed so that the entire value does not exceed 5 digits. (Note: Effective resolution depends on the range.)	
	Thermocouple	compensation	± 0.5 °C (ambient temperature 21 to 27 °C, under standard conditions) ± 1.5 °C (ambient temperature 0 to 50 °C, under standard conditions except for ambient temperature)	
		accuracy Reference junction compensation method	Compensation within the C7G	
		Input bias current	Input bias current: 0.12 μA max. (under standard conditions). Note: Current flows from the + terminal.	
		Allowable input voltage	-1.5 to +1.5 V	
	Resistance	Measuring current	1.0 mA (typical, from terminals A and B, under standard conditions)	
	temperature	Allowable wiring	85Ω max. (per wire)	
	detector (RTD)	resistance		
		Effect of wiring resistance	Effect of wiring resistance: 0.013 $^\circ\text{C}/\Omega$ (under standard conditions, within allowable wiring resistance)	
DC voltage DC current	Input bias current	0 to 10 V range : 10 μA max. (under standard conditions) -10 to +10 V range: -10 to +10 μA (under standard conditions) 1–5 V or 0–5 V range: 5 μA max. (under standard conditions)		
		Allowable input voltage	DC voltage input: -15 to +15 V DC current input: -1.5 to +1.5 V	
		Input impedance	DC voltage input: 1 M Ω or more DC current input: 50 Ω	
	Scaling		-32000 to +32000 U (5 digits within this range, max. 4 digits after the decimal point, reverse scaling possible)	
	Current output (1)	Туре	4 to 20 mA DC / 0 to 20 mA DC	
		Output type	Control output (MV), process value (PV), set value (SP), standard numerical code, etc.	
		Accuracy	±0.1 % FS	
		Allowable load resistance	600 Ω max.	
		Output resolution	1/16000 min.	
	CT (current) input (1)	Recommended current transformer	QN206A (hole dia. 5.8 mm, 800 turns), QN212A (hole dia. 12 mm, 800 turns) Note: Not UL-certified	
		Measuring current range	0.4–50.0 A AC, 50/60 Hz (peak current: 71 A max., 800 turns, 1 power wire loop)	
		Maximum allowable current	70 A AC (peak current: 99 A max. with 800 turns and 1 pass of the power wire)	
		Indication accuracy	±1 % FS ± 1 digit (under standard conditions, CT accuracy is not included)	
		Indication resolution	0.1 A AC	
		Indication update cycle	100 ms	
	VT (voltage) input (1)	Recommended voltage transformer	81406725-003 (primary side: 200V, secondary side: 10V) (not UL-certified)	
		Voltage measurement range	24 to 240 V AC, 50/60 Hz (peak voltage: 339 V max.; transformer primary side 200 V, secondary side 10 V)	
		Maximum allowable voltage	264 V AC (peak voltage: 373 V max.; transformer primary side: 200 V, secondary side: 10 V)	
		Indication accuracy	±1 % FS ± 1 digit	
		Indication resolution	0.1 V AC	
		Input impedance	160 kΩ (typ)	
		Indication update cycle	100 ms	
V-P block	Voltage pulse	Output voltage	12 V DC +15/-10 % (under standard conditions)	
	output (1)	Allowable current	25 mA max.	
		Load limit current	30 mA ±10 %	
		OFF-state leak current	100 μA max. (under standard conditions)	
		Output response time	100 µs max. for 10 %↔90 % of output voltage	
	CT (current) input (2)	Specifications	Same as CT (current) input for the AO-C block	

MOTOR	Motor drive	Contact configuration	Switching between OPEN output and CLOSE output (with function for turning both		
block output relay		contact configuration	outputs OFF at the same time)		
		Contact rating	250 V AC, 2 A (cos φ = 0.4); 24 V DC, 2.5 A (L/R = 0.7 ms)		
		Contact voltage	250 V AC / 125 V DC max.		
		Service life	100,000 cycles min. (at the rated specifications)		
		Minimum require- ments for switching	40 mA (when using 24 V DC power)		
		Interlock	With prevention of simultaneous ON if contact welding occurs (when output of close side is ON, output of open side is forced OFF, meaning that close-side output is prioritized)		
	MFB (motor	Allowable potentiometer	100 to 2500 Ω (wiring resistance included)		
	feedback) input	Indication accuracy	±0.5 % FS (under standard conditions)		
	mput	Sampling cycle	100 ms		
		Operation at burnout	Y line break: downscale Other line break: upscale		
DI block		Number of inputs	4 (common)		
		Compatible output type	Non-voltage contacts or open collector		
		Input type	Photocoupler (two-way)		
		Rated input voltage	24 V DC, +20/-15 %		
		Terminal current	4 mA (with 24 V DC input)		
		ON voltage/current	19 V / 3 mA min.		
		OFF voltage/current	7 V / 1 mA max.		
		Input sampling cycle	10 ms		
		Minimum pulse width	20 ms min. (for a 10 ms sampling cycle)		
		for ON detection	50 ms min. (for 50 ms sampling cycle)		
			100 ms min. (for 100 ms sampling cycle)		
		Function assignment	LSP group selection, PID group selection, PV hold, fixed value output group selection output linearization table group selection, switching of: RUN/READY*, AUTO/MANU/ LSP/RSP*, AT stop/start, control action forward/reverse, Timer stop/start selection, F lease all latches, RUN selection*, READY selection*, Constant value operation / Patt operation mode selection* / pattern operation*; ADVANCE*, HOLD*, G. SOAK cance tion, pattern selection. * indicates edge specification function		
DO block		Number of outputs	4 (common)		
		Output type	Open collector (sink type)		
		Load voltage	4.5 to 28.8 V DC		
		Maximum load current	100 mA for each terminal		
		Overcurrent detection	130 mA and above When an overcurrent is detected, the output is turned OFF and the status is checked every 5 seconds. If the status returns to normal, the output automatically returns to normal.		
		On-state residual voltage	0.5 V max. (under standard conditions)		
		Off-state leak current	100 μA max. (under standard conditions)		
		Function assignment	Select an event status or a standard bit code		
CLOCK block		Clock function	Hours, minutes, seconds, calendar (years 2000 to 2099, supports leap years)		
(with battery)		Clock accuracy	Monthly error of less than ±65 s (under standard conditions)		
		Service life	10 years (battery life when not energized, under standard conditions)		
		Built-in battery	Lithium battery		
		Block replacement	Possible (optional parts sold separately)		
HMI2 block		Number of connect- able units	1		
		Connector	RJ-45		

Control unit	Control operation	PID control (reverse a (reverse action, direct	action, direct action, heating and cooling action), ON/OFF control t action)				
	Control method	Continuous proportio	nal, time proportional, position proportional, cascade				
	PID control	Proportional band (P)	0.1 to 3200 % (5 digits within this range, 4 digits max. after the decimal point)				
		Integral time (I)	0 to 32000 s (5 digits within this range, 4 digits max. after the decimal point) No integral calculation when the setting is 0.				
		Derivative time (D)	0 to 32000 s (5 digits within this range, 4 digits max. after the decimal point) No derivative calculation when the setting is 0.				
		MV limits	-10 to +110 % (5 digits within this range, 4 digits max. after the decimal point)				
		Manual reset	-10 to +110 % (5 digits within this range, 4 digits max. after the decimal point)				
		Number of PID groups	8 groups (per loop)				
		PID group selection	For constant-value operation (LSP, RSP), a PID group can be set for each SP group Alternatively, selection by the DI function or zone PID function is possible. For pattern operation, a PID group can be set for each segment. Alternatively, selection by the DI function or zone PID function is possible.				
		MV change limit	0.0 to 10000 %/s (5 digits within this range, 4 digits max. after the decimal point) No limit when the setting is 0.0.				
		Auto-tuning	PID automatic setting using the limit cycle method				
		Control AT type	0: Normal, 1: Fast response, 2: Stable				
		Control AT adjustment factor	0.0000 to 320.00 (specifiable for proportional band, integral time, and derivative time)				
		Control cycle	Same as sampling cycle				
	ON/OFF control	Differential	0 to 32000 (5 digits max.within this range 4 digits max.after the decimal point)				
	SP	Number of LSP groups	8 groups per loop				
	(LSP: local SP)	SP ramp unit	0: s, 1: min, 2: h				
		Ramp up and down slopes 0 to 32000					
	Direct/reverse operation selection	Switchable					
	Heating/cooling control deadband	-100.0 to +100.0 %					
Analog input processing unit	Linear scaling low and high limits						
	Filter Ratio	0.0000 to 120.00 s 0.0010 to 10.000					
	Bias		digits within this range 4 digits may after the decimal point)				
	Square root drop out	-32000 to +32000 (5 digits within this range, 4 digits max. after the decimal poi 0.0001 to 10.000 % No square root extraction if set to 0.0000					
Linear approximation func-	Number of groups	8					
tion	Breakpoints per group						
	Available for	Analog input, analog output, etc.					
Event functions	Number of events	16					
	Operation types	PV high limit, PV low limit, PV high and low limits, deviation high limit, deviation low limit, deviation high and low limits, deviation high limit (final SP basis), deviation low limit (final SP reference), deviation high and low limits (final SP basis), SP high limit, SP low limit, SP high and low limits, MV high limit, MV low limit, MV high and low limits, MFB high and low limits, standard numerical code high limit, standard numerical code low limits, tandard numerical code high and low limits, PV change rate high limit, standard numerical code change rate low limit, standard numerical code change rate low limit, standard numerical code change rate high limit, standard numerical code change rate low limit, standard nu					
	Main setting / subsetting Hysteresis	-32000 to +32000 (5 digits within this range, 4 digits max. after the decimal point) 0 to 32000 (5 digits within this range, 4 digits max. after the decimal point)					
	READY mode operation		inuation" and "forced OFF."				
	Direct/reverse		turn ON/OFF in event output				
			· · · · · · · · · · · · · · · · · · ·				
		0: None, 1: Standby, 2: Standby + standby when the SP is modified					
	Standby On-delay time		vithin this range, 4 digits max. after the decimal point)				

Pattern opera	tion functions	Number of patterns	16			
		Number of segments	32 per pattern			
		Segment setting method				
			0.01 s, 0.1 s, 1 s, 1 min			
FunctionsHOperation end stateFEventS			HOLD, G. SOAK (start point, end point), PV start, ADVANCE, cyclical operation, pattern link, etc.			
		•	READY, END, constant-value			
			Segment events 1 to 32			
		Time accuracy	Accuracy of built-in clock: less than ±140 s/month			
Logical opera	tion function	Number of logical operation				
		Operation type	1: Calculation 1 (A and B) or (C and D) 2: Calculation 2 (A or B) and (C or D) 3: Calculation 3 (A or B or C or D) 4: Calculation 4 (A and B and C and D)			
		ON delay	0 to 3200s(5 digits max.within this range 4 digits max.after the decimal point)			
		OFF delay	0 to 3200s(5 digits max.within this range 4 digits max.after the decimal point)			
		Reverse	0: Direct 1: Reverse 2: Rising 3: Falling			
		Latch	0: Not latched 1: Latched when turned ON 2: Latched when turned OFF (Except for OFF when power is turned ON)			
Numerical ope	eration function	Number of unit	32			
		Operation type	No operation aX+bY, Division, Switch selector, High selector, Low selector, Soft switching selecto High/low limiter, Change rate limiter, Lead/lag, Absolute value, Linearization table, H One shot timer, Timer, Deviation monitor, Square-root extraction, Integration pulse output I, Integration pulse output II, Logarithm, Exponent, Derivation, Integration, De time, Moving average			
Other function	าร		Time setting, unit character setting, key lock setting, fixed value output, power voltage compensation, resistance value calculation (from the VT input and CT input), reception monitoring, user-defined alarm, input assignment, virtual analog input,FF-FITTER			
External	Ethernet	Transmission line type	Compliant with IEEE 802.3u 100BASE-TX (FastEthernet)			
communica-		Communication method	Full duplex			
tion		No. of connections	4 (The total number of connections for Modbus/TCP and loader communications via Ethernet is 1 to 3, and the number of connections for PLC link communication is fixed at 1.)			
		Transmission speed	100 Mbps max.			
		No. of physical ports (connectors)	1 (RJ-45)			
		Cable	UTP cable (4P) Cat 5e min. (straight) (ANSI/TIA/EIA-568-B both ends)			
		Protocol:	Modbus/TCP, Mitsubishi SLMP (3E) (for PLC link communication), Loder communica- tions via Ethernet			
	RS-485 com-	Signal level	RS-485-compliant			
	munication	Network	Multidrop (up to 31 slave stations for 1 host station)			
		Communications/ synchronization type	Half-duplex, start-stop synchronization			
		Maximum cable length	500 m max.			
		No. of communication wires	3-wire system			
		Transmission speed	9600, 19200, 38400, 57600, 115200 bps			
		Terminating resistor	External (120 Ω, 1/2 W min.)			
		Data length	8 bits			
		Stop bits	1 or 2 bits			
		Parity bit	Even parity, odd parity, or no parity			
		Protocol	Modbus/RTU			
	Loader com-	Dedicated PC loader	SLP-C7FJ91 (free version), SLP-C7-J91 (paid version)			
	munication	Cable	USB-to-Micro-USB (Type A/B) cable (USB 2.0 supported, 5 m max.) or Ethernet cable			
		Power supply	When connected with a USB cable, the device can be powered by the PC and parameters can be changed.			
Data storage		SD				
LIATA STORAGE		SD	microSD/SDHC-compliant (4 GB), for the compact data storage and health index functions			

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General specifications	Memory backup	EEPROM (durability: 1 million erase-write cycles min., for parameter settings) AC models: 25 VA 10 W max. DC models: 12 W max.								
	Power consumption			max. DC models: 12 V	V max.					
	Power-on inrush current		./10 ms max.							
	Start delay at power ON		-		is under standard conditions)					
	Allowable transient power loss	AC mode	ls: 20 ms max.	DC models: 5 ms max						
	Insulation resistance		n. (between po) V DC megger)		l or #2) and frame ground terminal (#3),					
	Dielectric strength	 AC models: 1500 V AC for 1 min Between AC power supply terminal (#1 or #2) and frame ground terminal (#3) Between AC power supply terminals (#1 or #2) and secondary terminals Between AC power supply terminal (#1 or #2) and motor block terminals (#1 to #3) Between motor block output terminals (#1 to #3) and frame ground terminal (#3) Between motor block output terminals (#1 to #3) and secondary terminals (excludin motor block output terminals (#1 to #3)) DC models 1500 V AC for 1 min Between motor block output terminals (#1 to #3) and frame ground terminal (#3) Between motor block output terminals (#1 to #3) and frame ground terminal (#3) Between motor block output terminals (#1 to #3) and bc power supply terminal (#1 or #2) Between motor block output terminals (#1 to #3) and secondary terminals (excludin motor block output terminals (#1 to #3)) 500 V AC for 1 min Between Dc power supply terminal (#1 or #2) and frame ground terminal (#3) Between DC power supply terminal (#1 or #2) and frame ground terminal (#3) Between DC power supply terminal (#1 or #2) and frame ground terminal (#3) 								
	Case material				(board holder, front mask) e (back cover), PET film (protective sheet)					
	Case color	Black								
	Regulations and		Regulations	Approvals	Remarks					
	approvals	UL		QUYX.E246616	UL 61010-1 (UL-compliant models only)					
		cUL		QUYX7.E246616	CAN/CSA-C22.2 No. 61010-1-12 (UL-compliant models only)					
		CE	EMC		EN 61326-1 (For use in industrial locations)					
		CE	LVD		EN 61010-1					
		CE	RoHS		EN IEC63000					
		UKCA	2016 No.1091		EN 61326-1 (For use in industrial locations)					
		UKCA	2016 No.1101		EN 61010-1					
		UKCA	2012 No.3032		EN IEC63000					
		KC Mark		MSIP-REM-A2B-A131						
		-		eading or output may fl	uctuate by ±10 % FS.					
	Overvoltage category	Category	II (IEC 60364-4	1-443, IEC 60664-1)						
	Installation	Main unit: Mounting on a DIN rail (standard) or on the display unit using the mounting bracket Display unit: Mounting using 3∳ screws (standard) or the mounting bracket (mount in a 92 × 92 mm hole)								
	Weight	Display u	: 500 g max. nit: 150 g max. I mounting brac	ket : 150 g max.						
	Built-in clock accuracy	 Monthly error: Less than ±140 s The time is reset to 00:000, Jan. 1, 2000(default) upon power-on (including power restoration after a power loss). However, if the firmware version of the MAIN block is 3.*.* or earlier, the time is reset to 00:00:00, Jan. 1, 2014(default). Note: When using the CLOCK block (with battery), the specification for monthly difference is a maximum of ± 65 s, and the correct date and time are maintained evin a power failure. Note: In time processing of the pattern operation function, the built-in clock is not used. 								

General	Standard con-	Ambient temperature	23 °C -2/+5 °C
specifica-	ditions	Ambient humidity	60 ±5 % RH
tions	tions	Power	AC models: 105 V AC ±10 %. DC models: 24 V DC ±5 %
		Power frequency	AC models: 50 Hz ±1 %, 60 Hz ±1 %
		Vibration	0 m/s ²
		Shock	0 m/s ²
		Mounting angle	Main unit: Reference plane $\pm 3^{\circ}$, Display unit: No restriction (if mounted separately from the main unit)
		Space	100 mm min. above and below, and on all sides (main unit); gang mounting acceptable (display unit)
	Operating	Ambient temperature	0 to 50 °C (0 to 40 °C if main units are gang-mounted)
conditions	Ambient humidity	10 to 90 % RH (without condensation)	
		Rated power	AC models: 100 to 240 V AC (operating input voltage: 85 to 264 V AC) DC models: 24 V DC (operating input voltage: 20.4 to 28.8 V DC)
		Power frequency	AC models: 50 Hz ±2 % or 60 Hz ±2 %
		Vibration	0 to 5 m/s ² (10 to 60 Hz for 2 h each in x, y, and z directions)
		Shock	0 to 100 m/s ²
		Mounting angle	Reference plane $\pm 10^{\circ}$ for main unit and display unit in integrated mounting. No restriction for display unit in standard mounting.
		Altitude	2000 m max.
		Pollution degree	2
		Installation location	Indoors
		Space	For the main unit, leave at least 50 mm above, below, and in front of the unit. No space is needed on the right or left. For the display unit, no space is needed above, below, on the right, or on the left.
	Transpor-	Ambient temperature	-20 to +70 °C
	tation and	Ambient humidity	10 to 95 % RH (without condensation)
	storage condi- tions	Vibration	0 to 10 m/s ² (10 to 60 Hz for 2 h each in x, y, and z directions)
		Shock	0 to 300 m/s² (3 times each in x, y, and z directions)

Table 1. Input types and ranges

Input type				Rai	nge			Accuracy	Resolution	Burnout
	Nos.		Range (Celsius)	Rang	e (Fe	hrenheit)			
Thermo-	1	K	-200 to	+1200 °C	-300	to	+2200 °F	±0.1 % FS ±1 digit *1	0.1 °C	Upscale
couple	2	K	0 to	1200 °C	0	to	2200 °F	±0.1 % FS ± 1 digit	0.1 °C	(110 % FS)
	3	K	0 to	800 °C	0	to	1500 °F	±0.1 % FS ± 1 digit	0.1 °C	
	4	K	0 to	600 °C	0	to	1100 °F	±0.1 % FS ± 1 digit	0.1 °C	
	5	ĸ	0 to	400 °C	0	to	700 °F	±0.1 % FS ± 1 digit	0.1 °C	
	6	K	-200 to	+400 °C	-300	to	+700 °F	±0.1 % FS ±1 digit *1	0.1 °C	
	7	K	-200 to	+200 °C	-300	to	+400 °F	±0.1 % FS ±1 digit *1	0.1 °C	
	8	J	0 to	1200 °C	0	to	2200 °F	±0.1 % FS ± 1 digit	0.1 °C	
	9	J	0 to	800 °C	0	to	1500 °F	±0.1 % FS ± 1 digit	0.1 °C	
	10	J	0 to	600 °C	0	to	1100 °F	±0.1 % FS ± 1 digit	0.1 °C	
	11	J	-200 to	+400 °C	-300	to	+700 °F	±0.1 % FS ±1 digit *1	0.1 °C	
	12	E	0 to	800 °C	0	to	1500 °F	±0.1 % FS ± 1 digit	0.1 °C	
	13	E	0 to	600 °C	0	to	1100 °F	±0.1 % FS ± 1 digit	0.1 °C	
	14	Т	-200 to	+400 °C	-300	to	+700 °F	±0.1 % FS ±1 digit *1	0.1 °C	
	15	R	0 to	1600 °C	0	to	3000 °F	±0.1 % FS ±1 digit *2	0.1 °C	
	16	S	0 to	1600 °C	0	to	3000 °F	±0.1 % FS ±1 digit *2	0.1 °C	
	17	В	0 to	1800 °C	0	to	3300 °F	±0.2 % FS ±1 digit *3	0.1 °C	
	18	N	0 to	1300 °C	0	to	2300 °F	±0.1 % FS ± 1 digit	0.1 °C	
	19	PLII	0 to	1300 °C	0	to	2300 °F	±0.1 % FS ± 1 digit	0.1 °C	Upscale (105 % FS)
	20	WRe5-26	0 to	1400 °C	0	to	2400 °F	±0.1 % FS ± 1 digit	0.1 °C	Upscale (110 % FS)
	21	WRe5-26	0 to	2300 °C	0	to	4200 °F	±0.1 % FS ± 1 digit	0.1 °C	
	23	PR40-20	0 to	1900 °C	0	to	3400 °F	±0.5 % FS ±1 digit *4	0.1 °C	

*1. For -200 to 0 °C, ±0.2 % FS ±1 digit
*2. For 0 to 100 °C, ±0.2 % FS ±1 digit
*3. For 0 to 260 °C, ±4 % FS ±1 digit. For 260 to 800 °C, ±0.4 % FS ±1 digit
*4. For 0 to 300 °C, ±2.5 % FS ±1 digit. For 300 to 800 °C, ±1.5 % FS ±1 digit

Input type			Range					Accurac	у	Resolution	Burnout
	Nos.		Range	(Celsius)	Rang	e (Fe	hrenheit)				
Resis-	41	Pt100	-200 to	+500 °C	-300	to	+900 °F	±0.1 % FS ± 1	digit	0.1 °C	Upscale
tance tem-	43	Pt100	-200 to	+200 °C	-300	to	+400 °F	±0.1 % FS ± 1	digit	0.01 °C	(110 % FS)
perature detector	45	Pt100	-100 to	+300 °C	-150	to	+500 °F	±0.1 % FS ± 1	digit	0.01 °C	
(RTD)	47	Pt100	-100 to	+200 °C	-150	to	+400 °F	±0.1 % FS ± 1	digit	0.01 °C	
()	49	Pt100	-100 to	+150 °C	-150	to	+300 °F	±0.1 % FS ± 1	digit	0.01 °C	
	51	Pt100	-50 to	+200 °C	-50	to	+400 °F	±0.1 % FS ± 1	digit	0.01 °C	
	53	Pt100	-50 to	+100 °C	-50	to	+200 °F	±0.1 % FS ± 1	digit	0.01 °C	
	55	Pt100	-60 to	+40 °C	-60	to	+100 °F	±0.1 % FS ± 1	digit	0.01 °C	
	57	Pt100	-40 to	+60 °C	-40	to	+140 °F	±0.1 % FS ± 1	digit	0.01 °C	
	59	Pt100	-10 to	+60 °C	-10	to	+140 °F	±0.1 % FS ± 1	digit	0.01 °C	
	61	Pt100	0 to	100 °C	0	to	200 °F	±0.1 % FS ± 1	digit	0.01 °C	
	63	Pt100	0 to	200 °C	0	to	400 °F	±0.1 % FS ± 1	digit	0.01 °C	
	65	Pt100	0 to	300 °C	0	to	500 °F	±0.1 % FS ± 1	digit	0.01 °C	
	67	Pt100	0 to	500 °C	0	to	900 °F	±0.1 % FS ± 1	digit	0.1 °C	
	69	Pt100	-200 to	+850 °C	-300	to	+1550 °F	±0.1 % FS ± 1	digit	0.1 °C	900 °C, 1650 °F
Linear	86	Voltage (V)	1 to	5 V	1	to	5 V	±0.1 % FS ± 1	digit	1/90000 min.	Downscale (-10 % FS)
	87	Voltage (V)	0 to	5 V	0	to	5 V	±0.1 % FS ± 1	digit		Burnout not detected (around 0 % FS)
	88	Voltage (V)	0 to	10 V	0	to	10 V	±0.1 % FS ± 1	digit		Burnout not detected (around 0 % FS)
	89	Current (mA)	0 to	20 mA	0	to	20 mA	±0.1 % FS ± 1	digit		Burnout not detected (around 0 % FS)
	90	Current (mA)	4 to	20 mA	4	to	20 mA	±0.1 % FS ± 1	digit		Downscale (-10 % FS)
	92	Voltage (V)	-10 to	+10 V	-10	to	+10 V	±0.1 % FS ± 1	digit		Burnout not detected (around 50 % FS)
Input typ		type Nos	Sonsor		2000			couracy	-	solution	Burnout

Input type	Range type Nos.	Sensor	Range	Accuracy	Resolution	Burnout
Not used	0	None	Fixed at 0			

! Handling Precautions

• Do not use Fahrenheit ranges in Japan.

Input sensor standards reference

K, E, J, T, B, R, S, N: JIS C 1602:2015 Thermocouple WRe 5-26: ASTM E988 - 96 (reapproved 2002) (JIS C 1602:2015, C Thermocouple) PR40-20, PLII: ASTM E1751/E1751M-15

Table 2. Compact data storage (CDS)

	Item		"Data selection" setting	1		
		Standard	Custom	Ring		
		microSD memory card	Same as on the left.	Same as on the left.		
Folder	Root folder name Folder name	CDS BLK _ _: a sequential number from 0 to 64	Same as on the left. Same as on the left.	LOG LOG _ _: Serial number from 001 to 100		
	Maximum number of files in a folder	1,000	Same as on the left.	200		
	Maximum number of files in the microSD memory card.	65,000	Same as on the left.	20,000		
File	File name	xxxx_yyyyy_z.dat xxxx: number of power ON/OFF cycles yyyyy: number of files created since power ON z: File division classification (0: first file, 1: following file)	xxxx_yyyyy_z.csv xxxx: Number of power ON/OFF cycles yyyyy: Number of files created since power ON z: File division classification (0: first file, 1: following file)	xxx_yyyy.csv xxx: Same as _ in the folder name yyyy:Serial number from 0001 to 0200		
	Management file name	None	Same as on the left.	xxx_yyyy.last xxx_yyyy: Same as the name of the last written file.		
	Maximum file size for each file	Approx. 2 MB	Same as on the left.	Approx. 192 KB		
Character code		Characters: Shift-JIS (ASCII) Line feed: CR + LF (hexadecimal 0DH and 0AH) Delimiter: comma (,), 2CH in hexadecimal Decimal point: period (.), hexadecimal 2EH	Same as on the left.	Same as on the left.		
Recording	Health index data	Available*	None	Same as on the left.		
content	Section	Consists of the context section and time sequence data section.	Consists of the header section and data section. Table 2-2. Sections of custom and loop CDS (p.12) (for details).	Same as on the left.		
	Number of data items	10 data items × number of loops	Selectable from 1 to 40	Same as on the left.		
Data types		Records diagnostic data for enabled loops, including the PID constant, health index (specific R value, R value), SP, PV, and MV. Table 2-2. Sections of custom and loop CDS (p.12) (for details).	Select from standard bit codes and standard numerical codes Table 4. List of standard bit codes (p.13) and Table 5. List of standard numerical codes (p.15) (for standard bit codes and standard numerical codes respectively.	Same as on the left.		
Recording operation	Recording cycle	Selected from "Same as sampling cycle, 0.1 s, 1 s, 10 s, 1 min, and 10 min."	Same as on the left.	Same as on the left.		
	Start and stop	Selected from "DI1 to 2, events 1 to 16, and standard bit code" Table 4. List of standard bit codes (p.13).	Same as on the left.	Same as on the left.		
Alarm concerning the number of files and capacity		 An SD card error alarm is issued in any of the following cases. When there is an attempt to write data exceeding the capacity of the microSD memory card When there is an attempt to write a new file when there are 1,000 files in BLK64 (the last folder) 	Same as on the left.	No alarm occurs as the oldest file is rewritten (however, if files recorded by standard or custom re- cording remain, an alarm may be issued).		

* It is necessary to configure the settings for the health index. Start the CDS and health index at the start of batch processing, and stop the CDS and health index when batch processing ends.

Table 2-1. Sections of standard CDS

Section	Data	Notes
Context section	P (Proportional band)	Records the setting when CDS starts.
(From Section Context to Sec-	I (Integral time)	
tionEnd)	D (Derivative time)	
	OL (MV low limit)	
	OH (MV high limit)	
	SP high limit	
	Specific R value	Normalization responsiveness (Kp/Tp)
	(diagnostic parameter)	(Gain is defined as Kp and time constant as Tp in the transfer
		function.) Calculated from the data when the PV is rising during batch pro-
		cessing.
		Records the definite value when CDS ends.
Time sequence data section	Timestamp	Year, month, day, hour, minute, second, millisecond
(From Section TemporalData	SP	
to SectionEnd)	PV	
(Indeted in each recording	MV	
Updated in each recording cycle)	R value	
	DT5	Varies depending on the type of output block to which the MV is assigned. AO-C block: RMS current (CT) V-P block: RMS current (CT1) Other: 0 (fixed) (However, fixed at 0 if heating MV and cooling MV are assigned)
	DT6	Varies depending on the type of output block to which the MV is assigned. AO-C block: RMS voltage (VT) V-P block: RMS current (CT2) Other: 0 (fixed) (However, fixed at 0 if heating MV and cooling MV are assigned)
	DT7	Varies depending on the type of output block to which the MV is assigned. AO-C block: Operation terminal (heater) resistance value (calculated from the CT input current and VT input voltage) Other: 0 (fixed)
	DT8	0 (fixed)
	DT9	
	DT10	

Table 2-2. Sections of custom and loop CDS

Section	Data	Notes				
Header section	Data number	Standard bit code, standard numerical code				
(lines 1 to 2)	Data name					
Data section	Timestamp	Year, month, day, hour, minute, second, millisecond				
(lines 3 and after)	Data	Values for standard bits and standard numbers				

Table 3. Health index

Diagnostic operation	Start and Stop	Select from DI 1 to 2, event 1 to 16, standard bit (can be set for each loop) Standard Bit Codes Table 4. List of standard bit codes (p.13).							
Graph display The health index graph bank displays the last 10 specific R values (diagnostic parameters) control loop as points and numbers on a graph.									
Settings	R value scale	0 to 10 (specifies the result of calculation × a power of 10)							
	Ideal data	0.0000 to 32000							
	Deviation low limit 0.0000 to 32000 (no low limit when 0.0000)								
	0.0000 to 32000 (no high limit when 0.0000)								
	SP high limit	-32000 to +32000							

Table 4. List of standard bit codes

The range of standard bit codes is 1024 to 2047. Codes not listed below are reserved for the system, so do not use them for configuration

. . .

Standard	Codes not listed below are rese	sta
bit code	Meaning of the standard bit codes	bit
1024	Always 0 (Off)	1
1025	Always 1 (On)	1
1088	Event 1	
1089	Event 2	1
1090 1091	Event 3 Event 4	
1091	Event 5	
1093	Event 6	1
1094	Event 7	1
1095	Event 8	1
1096	Event 9	1
1097	Event 10	1
1098	Event 11	1
1099	Event 12	
1100	Event 13	
1101 1102	Event 14 Event 15	1
1102	Event 16	
1120	CT1 heater burnout detection (A2 block)	
1120	CT2 heater burnout detection (A2 block)	
1122	CT1 heater burnout detection (B2 block)	1
1123	CT2 heater burnout detection (B2 block)	1
1124	CT1 heater burnout detection (A1 block)	1
1125	CT2 heater burnout detection (A1 block)	1
1126	CT1 heater burnout detection (B1 block)	1
1127	CT2 heater burnout detection (B1 block)	1
1128	CT1 overcurrent detection (A2 block)	
1129 1130	CT2 overcurrent detection (A2 block)	
1130	CT1 overcurrent detection (B2 block) CT2 overcurrent detection (B2 block)	
1132	CT1 overcurrent detection (A1 block)	
1133	CT2 overcurrent detection (A1 block)	1
1134	CT1 overcurrent detection (B1 block)	1
1135	CT2 overcurrent detection (B1 block)	1
1136	CT1 short-circuit detection (A2 block)	1
1137	CT2 short-circuit detection (A2 block)	1
1138	CT1 short-circuit detection (B2 block)	
1139	CT2 short-circuit detection (B2 block)	
1140 1141	CT1 short-circuit detection (A1 block) CT2 short-circuit detection (A1 block)	
1142	CT1 short-circuit detection (R1 block)	1
1143	CT2 short-circuit detection (B1 block)	
1168	DI/DO1 terminal status	1
1169	DI/DO2 terminal status	1
1170	DI/DO3 terminal status	1
1171	DI/DO4 terminal status	1
1172	DI/DO5 terminal status	
1173	DI/DO6 terminal status	1
1174	DI/DO7 terminal status	
1208 1209	DI1 terminal status (A3 block) DI2 terminal status (A3 block)	
1209	DI2 terminal status (A3 block)	
1210	DI4 terminal status (A3 block)	1
1212	DI1 terminal status (B3 block)	1
1213	DI2 terminal status (B3 block)	1
1214	DI3 terminal status (B3 block)	1
1215	DI4 terminal status (B3 block)	1
1224	DO1 terminal status (A1 block)	1
1225	DO2 terminal status (A1 block)	1
1226	DO3 terminal status (A1 block)	1
1227 1228	DO4 terminal status (A1 block) DO1 terminal status (B1 block)	
1228	DO1 terminal status (B1 block)	
1229	DO3 terminal status (B1 block)	1
1231	DO4 terminal status (B1 block)	1
1280	V-P terminal status (A2 block)	1
1281	V-P terminal status (B2 block)	1
		-

Standard bit code	Meaning of the standard bit codes
1282	V-P terminal status (A1 block)
1283	V-P terminal status (B1 block)
1290	Result of numerical operation 1 (bit)
1291	Result of numerical operation 2 (bit)
1292	Result of numerical operation 3 (bit)
1293	Result of numerical operation 4 (bit)
1294	Result of numerical operation 5 (bit)
1295	Result of numerical operation 6 (bit)
1295	
	Result of numerical operation 7 (bit)
1297	Result of numerical operation 8 (bit)
1298	Result of numerical operation 9 (bit)
1299	Result of numerical operation 10 (bit)
1300	Result of numerical operation 11 (bit)
1301	Result of numerical operation 12 (bit)
1302	Result of numerical operation 13 (bit)
1303	Result of numerical operation 14 (bit)
1304	Result of numerical operation 15 (bit)
1305	Result of numerical operation 16 (bit)
1306	Result of numerical operation 17 (bit)
1300	Result of numerical operation 17 (bit) Result of numerical operation 18 (bit)
1308	Result of numerical operation 19 (bit)
1309	Result of numerical operation 20 (bit)
1310	Result of numerical operation 21 (bit)
1311	Result of numerical operation 22 (bit)
1312	Result of numerical operation 23 (bit)
1313	Result of numerical operation 24 (bit)
1314	Result of numerical operation 25 (bit)
1315	Result of numerical operation 26 (bit)
1316	Result of numerical operation 27 (bit)
1317	Result of numerical operation 28 (bit)
1318	Result of numerical operation 29 (bit)
1310	
	Result of numerical operation 30 (bit)
1320	Result of numerical operation 31 (bit)
1321	Result of numerical operation 32 (bit)
1360	Segment event 1
1361	Segment event 2
1362	Segment event 3
1363	Segment event 4
1364	Segment event 5
1365	Segment event 6
1366	Segment event 7
1367	Segment event 8
1368	Segment event 9
1369	Segment event 10
1309	•
	Segment event 11
1371	Segment event 12
1372	Segment event 13
1373	Segment event 14
1374	Segment event 15
1375	Segment event 16
1376	Segment event 17
1377	Segment event 18
1378	Segment event 19
1379	Segment event 20
1380	Segment event 21
1381	Segment event 22
1382	Segment event 23
1383	Segment event 24
1384	Segment event 25
1385	Segment event 26
1386	Segment event 27
1387	Segment event 28
1388	Segment event 29
1389	Segment event 30
1390	Segment event 31
1391	Seament event 32
1391 1408	Segment event 32 User-defined bit 1

	Standard	
	bit code	Meaning of the standard bit codes
	1409	User-defined bit 2
	1410	User-defined bit 3
	1411	User-defined bit 4
	1412	User-defined bit 5
Γ	1413	User-defined bit 6
	1414	User-defined bit 7
	1415	User-defined bit 8
	1416	User-defined bit 9
	1417	User-defined bit 10
	1418	User-defined bit 11
	1419	User-defined bit 12
	1420	User-defined bit 13
	1421	User-defined bit 14
	1422	User-defined bit 15
	1423	User-defined bit 16
	1424	User-defined bit 17
	1425	User-defined bit 18
	1426	User-defined bit 19
	1427	User-defined bit 20
	1428	User-defined bit 21
	1429	User-defined bit 22
	1430	User-defined bit 23
	1431	User-defined bit 24
	1432	User-defined bit 25
	1433	User-defined bit 26
	1434	User-defined bit 27
	1435	User-defined bit 28
	1436	User-defined bit 29
	1437	User-defined bit 30
	1438	User-defined bit 31
	1439	User-defined bit 32
	1440	Result of logical operation 1
	1441	Result of logical operation 2
-	1442	Result of logical operation 3
⊢	1443	Result of logical operation 4
-	1444	Result of logical operation 5
-	1445 1446	Result of logical operation 6
⊢	1440	Result of logical operation 7 Result of logical operation 8
ŀ	1447	Result of logical operation 9
ŀ	1449	Result of logical operation 10
ŀ	1450	Result of logical operation 11
⊢	1451	Result of logical operation 12
┢	1452	Result of logical operation 12
-	1453	Result of logical operation 14
⊢	1454	Result of logical operation 15
┢	1455	Result of logical operation 16
┢	1456	Result of logical operation 17
╞	1457	Result of logical operation 18
╞	1458	Result of logical operation 19
┢	1459	Result of logical operation 20
ŀ	1460	Result of logical operation 21
F	1461	Result of logical operation 22
F	1462	Result of logical operation 23
	1463	Result of logical operation 24
F	1464	Result of logical operation 25
F	1465	Result of logical operation 26
F	1466	Result of logical operation 27
	1467	Result of logical operation 28
F	1468	Result of logical operation 29
F	1469	Result of logical operation 30
F	1470	Result of logical operation 31
	1471	Result of logical operation 32
Γ	1504	At CDS start
	1505	Loop 1 health index running
	4500	Loop Q boolth index supping
	1506	Loop 2 health index running

Standard bit code	Meaning of the standard bit codes								
1508	Loop 4 health index running								
1517	Display unit connection status								
1518	Additional display unit connection status								
1568	Loop 1 RUN/READY status								
1569	Loop 2 RUN/READY status								
1570	Loop 3 RUN/READY status								
1571	Loop 4 RUN/READY status								
1584	Loop 1 Auto/manual status								
1585	Loop 2 Auto/Manual status								
1586	Loop 3 Auto/Manual status								
1587	Loop 4 Auto/Manual status								
1600	Loop 1 AT stop/start status								
1601	Loop 2 AT stop/start status								
1602	Loop 3 AT stop/start status								
1603	Loop 4 AT stop/start status								
1608	Loop 1 AT error								
1609	Loop 2 AT error								
1610	Loop 3 AT error								
1611	Loop 4 AT error								
1616	Loop 1 LSP/RSP status								
1617	Loop 2 LSP/RSP status								
1618	Loop 3 LSP/RSP status								
1619	Loop 4 LSP/RSP status								
1648	Loop 1 SP ramp-up in progress								
1649	Loop 2 SP ramp-up in progress								
1650	Loop 3 SP ramp-up in progress								
1651	Loop 4 SP ramp-up in progress								
1652	Loop 1 SP ramp-down in progress								
1653	Loop 2 SP ramp-down in progress								
1654	Loop 3 SP ramp-down in progress								
1655	Loop 4 SP ramp-down in progress								
1670	Loop 1 pattern SP increase change limit in progress								
1671	Loop 2 pattern SP increase change limit in progress								
1672	Loop 3 pattern SP increase change limit in progress								
1673	Loop 4 pattern SP increase change limit in progress								
1674	Loop 1 pattern SP decrease change limit in progress								
1675	Loop 2 pattern SP decrease change limit in progress								
1676	Loop 3 pattern SP decrease change limit in progress								
1677	Loop 4 pattern SP decrease change limit in progress								
1712	Loop 1 pattern operation mode								

Standard bit code	Meaning of the standard bit codes
1713	Loop 2 pattern operation mode
1714	Loop 3 pattern operation mode
1715	Loop 4 pattern operation mode
1720	Loop 1 HOLD status
1721	Loop 2 HOLD status
1722	Loop 3 HOLD status
1723	Loop 4 HOLD status
1728	Loop 1 END status
1729	Loop 2 END status
1730	Loop 3 END status
1731	Loop 4 END status
1736	Loop 1 G. SOAK status
1737	Loop 2 G. SOAK status
1738	Loop 3 G. SOAK status
1739	Loop 4 G. SOAK status
1792	All typical alarms
	(logical OR of all alarms be displayed)
1824	Loop 1 PV low limit error
1825	Loop 1 PV high limit error
1826	Loop 1 RSP low limit error
1827	Loop 1 RSP high limit error
1828	Loop 2 PV low limit error
1829	Loop 2 PV high limit error
1830	Loop 2 RSP low limit error
1831	Loop 2 RSP high limit error
1832	Loop 3 PV low limit error
1833	Loop 3 PV high limit error
1834	Loop 3 RSP low limit error
1835	Loop 3 RSP high limit error
1836	Loop 4 PV low limit error
1837	Loop 4 PV high limit error
1838	Loop 4 RSP low limit error
1839	Loop 4 RSP high limit error
1880	MFB input error
1884	Adjusting MFB
1888	Estimating MFB
1896	MFB adjustment error
1900	Motor drive output OPEN
1904	Motor drive output CLOSE
1920	Reception monitoring 1

Standard									
bit code	Meaning of the standard bit codes								
1921	Reception monitoring 2								
1922	Reception monitoring 3								
1940	User-defined alarm 1								
1941	User-defined alarm 2								
1942	User-defined alarm 3								
1943	User-defined alarm 4								
1952	CT/VT input error (block A2 CT)								
1953	CT/VT input error (block A2 VT)								
1954	CT/VT input error (block B2 CT)								
1955	CT/VT input error (block B2 VT)								
1956	CT/VT input error (block A1 CT)								
1957	CT/VT input error (block A1 VT)								
1958	CT/VT input error (block B1 CT)								
1959	CT/VT input error (block B1 VT)								
1960	CT/CT input error (block A2 CT1)								
1961	CT/CT input error (block A2 CT2)								
1962	CT/CT input error (block B2 CT1)								
1963	CT/CT input error (block B2 CT2)								
1964	CT/CT input error (block A1 CT1)								
1965	CT/CT input error (block A1 CT2)								
1966	CT/CT input error (block B1 CT1)								
1967	CT/CT input error (block B1 CT2)								
1973	Memory error								
1977	Battery error (CLOCK block)								
1991	Block error								
1992	SD card error								
1993	Numerical operation alarm								
1994	Buff. setting alarm								
2000	Block alarm IO failure (block A1)								
2001	Block alarm IO failure (block A2)								
2002	Block alarm IO failure (block A3)								
2003	Block alarm IO failure (block A4)								
2004	Block alarm IO failure (block B1)								
2005	Block alarm IO failure (block B2)								
2006	Block alarm IO failure (block B3)								
2007	Block alarm IO failure (block B4)								
2008	Block alarm HMI block failure								
2009	Block alarm SUB2 block failure (RS-485)								
2010	Block alarm SUB1 block failure (DI DO)								
2011	Block alarm MAIN block failure								

Table 5. List of standard numerical codes

The range of the standard numerical codes is 2048 to 3071.

Codes not listed below are reserved for the system, so do not use them for configuration.

Standard numerical code No.	Meaning of the standard numerical codes								
2048	Always 0.0								
2111	User-defined value 1								
2112	User-defined value 2								
2113	User-defined value 3								
2114	User-defined value 4								
2115	User-defined value 5								
2116	User-defined value 6								
2117	User-defined value 7								
2118	User-defined value 8								
2119	User-defined value 9								
2120	User-defined value 10								
2121 2122	User-defined value 11								
2122	User-defined value 12								
2123	User-defined value 13 User-defined value 14								
2124	User-defined value 15								
2126	User-defined value 16								
2127	User-defined value 17								
2128	User-defined value 18								
2129	User-defined value 19								
2130	User-defined value 20								
2131	User-defined value 21								
2132	User-defined value 22								
2133	User-defined value 23								
2134	User-defined value 24								
2135	User-defined value 25								
2136	User-defined value 26								
2137	User-defined value 27								
2138	User-defined value 28								
2139	User-defined value 29								
2140	User-defined value 30								
2141	User-defined value 31								
2142 2288	User-defined value 32 Virtual Al1								
2289	Virtual AI2								
2290	Virtual AI3								
2291	Virtual Al4								
2296	Virtual PV1								
2297	Virtual PV2								
2298	Virtual PV3								
2299	Virtual PV4								
2304	AI (block A4)								
2305	AI (block B4)								
2306	AI (block A3)								
2307	AI (block B3)								
2312	PV (block A4)								
2313 2314	PV (block B4)								
2314	PV (block A3) PV (block B3)								
2313	Loop 1 PV								
2320	Loop 2 PV								
2322	Loop 3 PV								
2323	Loop 4 PV								
2336	Loop 1 SP (in use)								
2337	LOOP2 SP (in use)								
2338	Loop 3 SP (in use)								
2339	Loop 4 SP (in use)								
2352	Loop 1 SP (final value)								
2353	Loop 2 SP (final value)								
2354	Loop 3 SP (final value)								
2355	Loop 4 SP (final value)								
2368	Loop 1 current LSP								
2369	Loop 2 current LSP								
2370 2371	Loop 3 current LSP Loop 4 current LSP								
2371	Loop 1 RSP								
2385	Loop 2 RSP								
2386	Loop 3 RSP								
2387	Loop 4 RSP								

Standard numerical code No.	Meaning of the standard numerical codes
2416	Loop 1 MV
2417	Loop 2 MV
2418	Loop 3 MV
2419	Loop 4 MV
2432	Loop 1 MV for heating
2433	Loop 2 MV for heating
2434	Loop 3 MV for heating
2435	Loop 4 MV for heating
2448	Loop 1 MV for cooling
2449	Loop 2 MV for cooling
2450	Loop 3 MV for cooling
2451	Loop 4 MV for cooling
2464	MFB opening amount (estimated)
2472	MFB opening amount (actual value)
2479	MFB count value
2496	CT1 measured current when output ON (block A2)
2497	CT2 measured current when output ON (block A2)
2498	CT1 measured current when output ON (block B2)
2499	CT2 measured current when output ON (block B2)
2500	CT1 measured current when output ON (block A1)
2501	CT2 measured current when output ON (block A1)
2502	CT1 measured current when output ON (block B1)
2503	CT2 measured current when output ON (block B1)
2512	CT1 measured current when output OFF (block A2)
2513	CT2 measured current when output OFF (block A2)
2514	CT1 measured current when output OFF (block B2)
2515	CT2 measured current when output OFF (block B2)
2516	CT1 measured current when output OFF (block A1)
2517	CT2 measured current when output OFF (block A1)
2518	CT1 measured current when output OFF (block B1)
2519	CT2 measured current when output OFF (block B1)
2528	Loop 1 deviation (PV - SP)
2529	Loop 2 deviation (PV - SP)
2530	Loop 3 deviation (PV - SP)
2531	Loop 4 deviation (PV - SP)
2544	CT input value (block A2)
2545	CT input value (block B2)
2546	CT input value (block A1)
2547	CT input value (block B1)
2548	VT input value (block A2)
2549	VT input value (block B2)
2550	VT input value (block A1)
2551	VT input value (block B1)
2552	Resistance (block A2)
2552	Resistance (block B2)
2553	Resistance (block A1)
2554	Resistance (block AT) Resistance (block B1)
2555	Event 1 timer remaining time
2656	-
	Event 2 timer remaining time Event 3 timer remaining time
2658	-
2659	Event 4 timer remaining time
2660	Event 5 timer remaining time
2661	Event 6 timer remaining time
2662	Event 7 timer remaining time
2663	Event 8 timer remaining time
2664	Event 9 timer remaining time
2665	Event 10 timer remaining time
2666	Event 11 timer remaining time
2667	Event 12 timer remaining time
2668	Event 13 timer remaining time
2669	Event 14 timer remaining time
2670	Event 15 timer remaining time
2671	Event 16 timer remaining time
2736	CT1 Time proportioning current (block A2)
2737	CT2 Time proportioning current (block A2)
2738	CT1 Time proportioning current (block B2)
	OTO Time a manual distribution of the set (black DO)
2739	CT2 Time proportioning current (block B2)
2739 2740	CT1 Time proportioning current (block B2) CT1 Time proportioning current (block A1)

configura								
Standard	Meaning of the standard							
numerical code No.	numerical codes							
2742	CT1 Time propertioning surrent (block P1)							
2742	CT1 Time proportioning current (block B1) CT2 Time proportioning current (block B1)							
2743	Loop 1 definite R value							
2752	Loop 2 definite R value							
2754	Loop 3 definite R value							
2755	Loop 4 definite R value							
2760	Loop 1 R value							
2761	Loop 2 R value							
2762	Loop 3 R value							
2763	Loop 4 R value							
2768	AO-C percent output value (block A2)							
2769	AO-C percent output value (block B2)							
2770	AO-C percent output value (block A1)							
2771	AO-C percent output value (block B1)							
2776	V-P percent output value (block A2)							
2777	V-P percent output value (block B2)							
2778	V-P percent output value (block A1)							
2779	V-P percent output value (block B1)							
2787	TP percent output value (DO4)							
2788	TP percent output value (DO5)							
2789	TP percent output value (DO6)							
2790	TP percent output value (DO7)							
2800	Result of numerical operation 1							
2801	Result of numerical operation 2							
2802	Result of numerical operation 3							
2803	Result of numerical operation 4							
2804 2805	Result of numerical operation 5 Result of numerical operation 6							
2805	Result of numerical operation 7							
2807	Result of numerical operation 8							
2808	Result of numerical operation 9							
2809	Result of numerical operation 10							
2810	Result of numerical operation 11							
2811	Result of numerical operation 12							
2812	Result of numerical operation 13							
2813	Result of numerical operation 14							
2814	Result of numerical operation 15							
2815	Result of numerical operation 16							
2816	Result of numerical operation 17							
2817	Result of numerical operation 18							
2818	Result of numerical operation 19							
2819	Result of numerical operation 20							
2820	Result of numerical operation 21							
2821	Result of numerical operation 22							
2822	Result of numerical operation 23							
2823	Result of numerical operation 24							
2824	Result of numerical operation 25							
2825	Result of numerical operation 26							
2826	Result of numerical operation 27							
2827	Result of numerical operation 28							
2828 2829	Result of numerical operation 29							
2829	Result of numerical operation 30 Result of numerical operation 31							
2830	Result of numerical operation 32							
2001	resear of numerical operation 52							

Model selection

Example: C7GA411CC0D00

	Main unit					I/O slot Oth					Ot	her				
Ва	sicı	nodel	No.	Comm.	Size	Slots A3, A4	Slots B3, B4	Slots A1, A2	Slots B1, B2	Option	Add'l proc.	Add'l spec.	Special support	Description		
1		2	3	4	5	6	7	8	9	10	11	12	13			
С		7	G											Multi-loop controller with multifunction display		
				Α										Communications (Ethernet, RS-485, USB), DI/DO (× 7, sink output,	source inp	out)
					3									Integrated mounting *1		
					4									Standard (separate) mounting		
															Slot A3	Slot A4
						1								PV1 (full-multi) × 1		AI
						2								PV1 (full-multi) + RSP1 (full-multi) *2	AI	AI
Cond	itior	1:				Α								PV1 (full-multi) + DI (× 4) (external power source required)	DI	AI
				ns indica											Slot B3	Slot B4
			ble if th atisfied	ne specif	lea		0							None		
				-			1							PV2 (full-multi) × 1		AI
If the	6th d	ligit (sl	ots A3	, A4) is 2			2							PV2 (full-multi) + RSP2 (full-multi) *3	AI	AI
If the	6th d	ligit (sl	ots A3	, A4) is 2	or A …		Α							PV2 (full-multi) + DI (× 4) (external power source required)	DI	AI
If the 9	th di	git (slo	ts B1, B2	2) is O,C			В							PV2 (full multi) + clock (with battery)	CLOCK	AI
				Ν,Ο	G, H, 1	, or 2									Slot A1	Slot A2
								С						Current output (CT and VT inputs, 1 each) × 1		AO-C
								v						Voltage pulse output (2 CT inputs) × 1		V-P
								F						Current output (CT and VT inputs, 1 each) × 2	AO-C	AO-C
								w						Voltage pulse output (2 CT inputs) × 2	V-P	V-P
								N						Current output (CT and VT inputs, 1 each) + voltage pulse output (2 CT inputs)	V-P	AO-C
								1						Current output (CT and VT inputs, 1 each) + DO (× 4) (sink output)	DO	AO-C
								2						Voltage pulse output (2 CT inputs) + DO (× 4) (sink output)	DO	V-P
															Slot B1	Slot B2
		÷ .		,		, or 2			0					None		
		÷ .		,		or 1			С					Current output (CT and VT inputs, 1 each) × 1	L	AO-C
						N, 1, or 2			v					Voltage pulse output (2 CT inputs) × 1	L	V-P
									F					Current output (CT and VT inputs, 1 each) × 2	AO-C	AO-C
				,					w					Voltage pulse output (2 CT inputs) × 2	V-P	V-P
									N					Current output (CT and VT inputs, 1 each) + voltage pulse output (2 CT inputs)	V-P	AO-C
						or 1			G					Current output (CT and VT inputs, 1 each) + additional display unit	HMI2	AO-C
		÷ .		,		N, 1, or 2			н					Voltage pulse output (2 CT inputs) + additional display unit	HMI2	V-P
		÷ .		,		or 1			L					Current output (CT and VT inputs, 1 each) + clock (with battery)	CLOCK	AO-C
						N, 1, or 2			Р					Voltage pulse output (2 CT inputs) + clock (with battery)	CLOCK	V-P
									1					Current output (CT and VT inputs, 1 each) + DO (× 4) (sink output)	DO	AO-C
If the	8th d	ligit (sl	ots A1,	A2) is V	V, N, 1,	or 2			2					Voltage pulse output (2 CT inputs) × DO (× 4)(sink output)	DO	V-P
										0				None		
											0			None		
											D			With inspection report		
											Y			With traceability certificate		
												0		AC power. CE, KC, UKCA-compliant		
												D		DC power. CE, KC, UKCA-compliant		
												A		AC power. CE, KC, UKCA, UL-compliant		
												В		DC power. CE, KC, UKCA, UL-compliant		
													0	No special support		
													F	Overseas models: switchable between Celsius/Fahrenheit Do not use these models in Japan.		
		_														

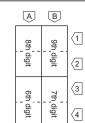
Symbol	Block Name	Description	
AI	Analog Input	Full-multi range (thermocouple, RTD, DC current, DC voltage) input × 1	
V-P	Voltage pulse output	Voltage pulse output (12 V DC) × 1 Input terminals for the current transformer (CT) for detecting heater burnout, overcurrent, and short circuit are included (× 2). ^{$x4$}	*1. A integrated mounting bracket and a dedicated cable
AO-C	Analog current output	Current output (4–20 mA DC / 0–20 mA DC) × 1 Input terminals for the current transformer (CT) for measuring current and the voltage transformer (VT) for measuring voltage are included (1 each). ^{$*4$}	for connecting the display unit are included with the product.
HMI2	Additional display unit	Additional connector for the second display unit *5	*2. RSP1 can be switched for use as PV3. *3. RSP2 can be switched for use as PV4.
CLOCK	Clock function	Clock (available for CDS and health index) with a battery	*4. Current transformer (CT) and voltage transformer (VT)
DI	Digital input	4 digital inputs (external power required)	are sold separately.
DO	Digital output	4 digital outputs (sink output)	*5. Additional display unit is sold separately.

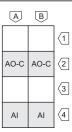
• Recommended models

Current output	1 output	2 outputs	3 outputs	4 outputs
8–9th digits	C0	сс	FC	FF
Layout	A B I I AO-C I	A B AO-C AO-C	AO-C (1) AO-C AO-C (2)	(A) (B) (A) (C) (A) (C)
Analog Input	1 input	2 inputs	3 inputs	4 inputs
-	1 input	2 inputs	3 inputs 21	4 inputs 22

• Block layout example

Model No. 6th–9th digits and slot position Example: C7GA411CC0D00





Model selection (models with motor output) Example: C7GA410M00D00 Main unit I/O slot Other Slots A2–3, B2–3 Slot A4 Slot B4 Slots A1, B1 Add'l Add'l Special support Basic model No. Size Comm Option Description proc. spec. 2 3 4 5 6 7 8 9 10 11 12 13 1 С 7 G Multi-loop controller with multifunction display Communications (Ethernet, RS-485, USB), DI/DO (× 7, sink output, source input) Α 3 Integrated mounting*1 4 Standard (separate) mounting Slot A4 PV1 (full-multi) 1 AI Slot B4 0 None PV2 (full-multi) *2 1 AI Slots A2-3, B2-3 М MOTOR Motor drive output (with MFB input) Slot A1 Slot B1 0 None Current output (CT and VT inputs, 1 each) × 1 С AO-C v Voltage pulse output (2 CT inputs) × 1 V-P N Current output (CT and VT inputs, 1 each) + voltage pulse output (2 CT inputs) AO-C V-P G Current output (CT and VT inputs, 1 each) + additional display unit AO-C HMI2 Current output (CT and VT inputs, 1 each) + clock (with battery) L AO-C CLOCK 1 Current output (CT and VT inputs, 1 each) + DO (× 4) (sink output) AO-C DO 4 DO (× 4) (sink output) + clock (with battery) DO CLOCK 0 None 0 None

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With inspection report

No special support

With traceability certificate AC power, CE, KC, UKCA-compliant

DC power. CE, KC, UKCA-compliant

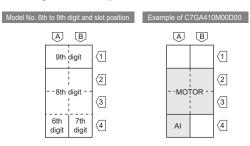
AC power. CE, KC, UKCA, UL-compliant

DC power. CE, KC, UKCA, UL-compliant

Overseas models: switchable between Celsius/Fahrenheit Do not use these models in Japan.

Symbol	Block Name	Description
AI	Analog Input	Full-multi range (thermocouple, RTD, DC current, DC voltage) input × 1
V-P	Voltage pulse output	Voltage pulse output (12 V DC) × 1 Input terminals for the current transformer (CT) for detecting heater burnout, overcurrent, and short circuit are included (× 2). * ³
AO-C	Analog current output	Current output (4–20 mA DC / 0–20 mA DC) × 1 Input terminals for the current transformer (CT) for measuring current and the voltage transformer (VT) for measuring voltage are included (1 each). *3
MOTOR	Motor drive output	Motor drive output (100/200 V AC) forward (OPEN) output, reverse (CLOSE) output with MFB (motor feedback) input
HMI2	Additional display unit	Additional connector for the second display unit *4
CLOCK	Clock function	Clock (available for CDS and health index) with a battery
DO	Digital output	4 digital outputs (sink output)

Block layout example



Option parts

■ Additional display unit (sold separately)

Example: C7D-400D00

		Main uni	t Oth		Other					
	Basic m	odel No.		Installation method			Special support	Description		
1	2	3	4	5	6	7	8	9	10	
С	7	D	-							Additional display unit for multi-loop controller with multifunction display
				3						Integrated mounting *
				4						Standard (separate) mounting
					0					English, Japanese
0		0				None				
							0			None
D					With inspection report					
0					0		CE, KC, UKCA-compliant			
* A integra	ated mount	ting brack	et is includ	led.					0	No special support

Service parts (sold separately)

Part name	Model No.
SLP-C7 Smart Loader Package (free version) *1	SLP-C7FJ91
SLP-C7 Smart Loader Package (paid version)	SLP-C7-J91
Power terminal covers (10)	81447704-001
C7 (display unit) mounting method change kit *2	84503167-001
MicroSD card (for replacement)	84502552-001
CLOCK block (for replacement) *3	84501420-001
MOTOR block (for replacement) *3	84501421-001
Current transformer (5.8 mm in diameter)	QN206A
Current transformer (12 mm in diameter)	QN212A
Voltage transformer (for 200 V AC)	81406725-003

*1. Downloadable from our website

https://www.azbil.com/products/factory/factory-product/controller-recorder/controller/index.html

*2. A integrated mounting bracket, a dedicated cable for connecting the display unit, and standard gasket,gasket with 92 × 92 mm hole are included with the product.

*3. Mounting bracket for replacement is included.

Accessories

Applicable model No.	Part name	Qty.	Remarks
C7G_4	Standard gasket	1	For the display unit
	Display unit mounting screws (6 mm)	5	
	Display unit mounting screws (10 mm)	5	
	Set screws (for securing temporarily)	2	
C7G_3	Gasket with 92 × 92 mm hole	1	
	Integrated-mounting bracket	1	
	Display unit mounting screws (6 mm)	5	
	Integrated-mounting cable	1	

Model No. and loop type

The following table shows the possible combinations of model No. and loop type with regard to analog input.

OK: Combination is possible

 Δ : Possible when the advanced loop type setting is enabled.

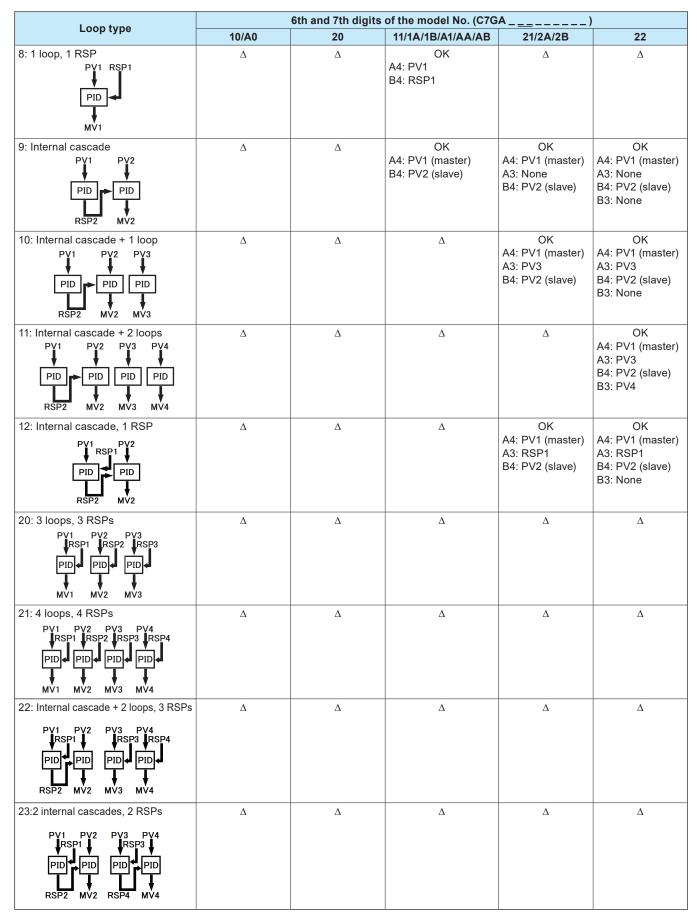
RSP1:	RSP for loop 1
RSP2:	RSP for loop 2
RSP3:	RSP for loop 3
RSP4:	RSP for loop 4

Unused: Although an analog input of the AI block is present, it is not assigned to the PV or RSP of the loop.

PV1:	LOOP1 PV
PV2:	LOOP2 PV
PV3:	LOOP3 PV
PV4:	LOOP4 PV

Loop type	6th and 7th digits of the model No. (C7GA)							
Loop type	10/A0	20	11/1A/1B/A1/AA/AB	21/2A/2B	22			
0: 1 loop	OK A4: PV1	OK A4: PV1 A3: Not used	OK A4: PV1 B4: Not used	OK A4: PV1 A3: Not used B4: Not used	OK A4: PV1 A3: Not used B4: Not used B3: Not used			
1: 1 loop, 1 RSP PV1 RSP1 PID MV1	Δ	OK A4: PV1 A3: RSP1	Δ	OK A4: PV1 A3: RSP1 B4: Not used	OK A4: PV1 A3: RSP1 B4: Not used B3: Not used			
2: 2 loops	Δ	Δ	OK A4: PV1 B4: PV2	OK A4: PV1 A3: Not used B4: PV2	OK A4: PV1 A3: Not used B4: PV2 B3: Not used			
3:2 loops, 1 RSP PV1 RSP1 PV2 PID PID PID PID MV1 MV2	Δ	Δ	Δ	OK A4: PV1 A3: RSP1 B4: PV2	OK A4: PV1 A3: RSP1 B4: PV2 B3: Not used			
4: 2 loops, 2 RSPs PV1 RSP1 PV2 RSP2 PID PID PID MV1 MV2	Δ	Δ	Δ	Δ	OK A4: PV1 A3: RSP1 B4: PV2 B3: RSP2			
5: 3 loops PV1 PV2 PV3 PID PID PID MV1 MV2 MV3	Δ	Δ	Δ	OK A4: PV1 A3: PV3 B4: PV2	OK A4: PV1 A3: PV3 B4: PV2 B3: Not used			
6: 3 loops, 1 RSP PV1 PV2 RSP2 PV3 PID PID PID MV1 MV2 MV3	Δ	Δ	Δ	Δ	OK A4: PV1 A3: PV3 B4: PV2 B3: RSP2			
7: 4 loops PV1 PV2 PV3 PV4 PID PID PID PID MV1 MV2 MV3 MV4	Δ	Δ	Δ	Δ	OK A4: PV1 A3: PV3 B4: PV2 B3: PV4			

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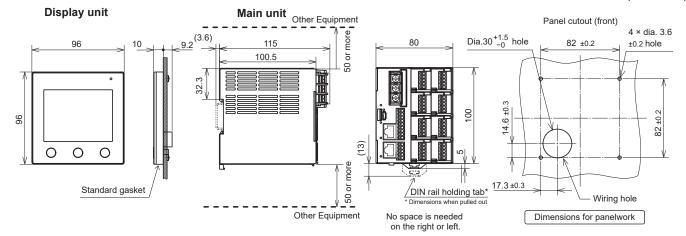
! Handling Precautions

- The value of an unused AI cannot be displayed. To display the value of the AI, even if it is not a control target, assign it to PV in the loop type. However, since the AI is actually not controlled, it is not necessary to assign the MV to the analog output or DI/DO.
- If the advanced loop type setting is enabled for [Loop type], any loop type can be selected regardless of the model number.

External Dimensions

Standard Installation

(Unit: mm)

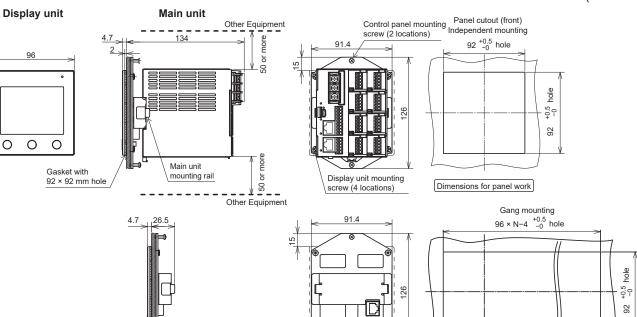


Integrated Installation

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0 Ο

96



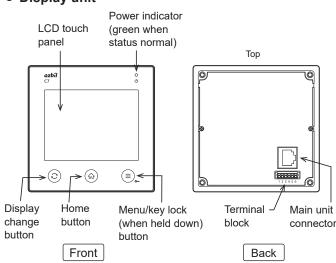
Integrating bracket

Dimensions for panel work

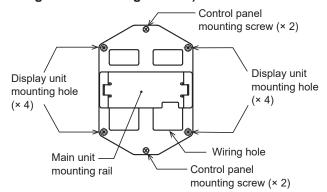
(Unit: mm)

Part Names and Functions

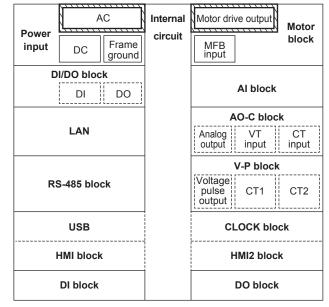
• Display unit



Integrated mounting bracket (included with integrated mounting models)

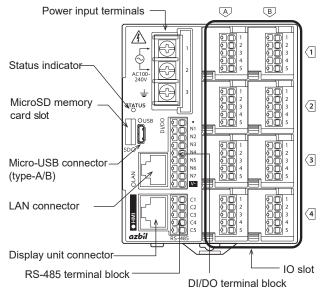


I/O isolation



Reinforced insulation Functional isolation No isolation

Main unit



Wiring Precautions

Before touching the main unit or display unit, or removing/ inserting cables, touch a grounded panel to discharge static electricity from your body.

> 100–240 V AC 50/60 Hz

(2)

(3)

 \bigcirc

Power input

- AC power 1: AC power supply live line
 - 2: AC power neutral line
 - 3: Frame ground

	· ⊥
DC power	(1) ⁺
1: DC power +	124 V DC
2: DC power –	2
3: Frame ground	3
	- -

! Handling Precautions

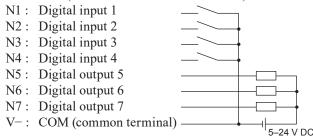
- Before touching the power input terminal box, shut off the input power.
- After completing the work, be sure to put the cover on the power input terminal block.
 - Note: For power input use crimp terminals for M4 screws (max. width 8.5 mm). Proper tightening torque: 1.4 N·m

■ DI/DO Block (7 digital input/outputs, input/ output selectable)

Either digital input or digital output (sink output) can be specified for each of terminals N1 to N7.

In the following wiring example, terminals N1-N4 are used for digital input and N5-N7 are used for digital output.

· : N.C. (Do not connect to this terminal.)



RS-485 Block

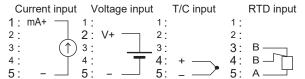
When connecting to the middle of	0		
the communication wire	the communication wire		
C1 : DA (+)	C1 : DA (+)		
C2 : DA (+)	C2 :		
C3 : DB (-)	C3 : DB (-) C4 :		
C4 : DB (-)	C4 : Tesistor		
C5 : SG	C5 : SG		

C1 and C2, and C3 and C4, are electrically continuous inside the port.

Handling Precautions

- Connect a terminating resistor (120 Ω, 1/2 W) to both ends of the communication line. If a resistor with leads is used, insert the leads directly without using ferrules. Do not connect a terminating resistor to the middle part of the communication line.
- · To connect two terminals together such as SG, use a crimp terminal without an insulation sleeve.

Al Block (analog input)



Allowable input voltage

DC current input: -1.5 to +1.5 V

DC voltage input: -15 to +15 V

Thermocouple input: -1.5 to +1.5 V

■ AO-C Block (current outputs / CT, VT in-

puts)

- 1 : CT input CT
- 2 : CT/VT common VT
- 3 : VT input
- 4 : Current output + mA
- 5 : Current output -
- Maximum allowable input
 - CT: 90 mA AC and 130 mA peak, 1 V AC and 1.4 V peak

VT: 18 V AC and 26 V peak

Transient overvoltage

CT: supply voltage + 250 V

! Handling Precautions

· If using a current transformer with the UL model of this product, use a UL 2808-certified product in the UL XOBA or XOBA7 category. An uncertified current transformer cannot be used with the UL model.

■ V-P Block (voltage pulse outputs / 2 CT inputs)

CT

- 1: CT1 input
- 2 : CT common
- 3 : CT2 input CT
- 4 : Voltage pulse output + V
- 5 : Voltage pulse output -
- Maximum input
 - CT: 90 mA AC and 130 mA peak, 1 V AC and 1.4 V peak

Transient overvoltage

CT: supply voltage + 250 V

Load current:

Voltage pulse output: 25 mA max.

Handling Precautions

· If a current transformer is used for a UL-compliant model, the transformer must be compliant with UL 2808 (categories XOBA and XOBA7). Do not use an uncertified current transformer.

DI Block (4 digital inputs)

- 1 : Digital input 1
- 2 : Digital input 2 3: Digital input 3 4 : Digital input 4
- 5 : COM (common terminal) 24 V DC 24 V DC

DO Block (4 digital outputs, sink output)

- 1 : Digital output 1
- 2 : Digital output 2
- 3 : Digital output 3
- 4 : Digital output 4
- 5 : COM (common terminal) 5-24 V DC

MOTOR Block (motor drive outputs and motor feedback inputs)



- 2 : Common ree. 3 : CLOSE Close
- 4: MFB(Y)Open
- 5 : MFB (T)
- 6 : MFB (G) Close

Contact rating:

For models other than UL-compliant models

2 A, 250 V AC (inductive load)

2.5 A, 24 V DC (inductive load)

For UL-compliant models

- 2 A, 250 V AC (general use)
- FLA: 2A, 240 V AC (100 W)
- Potentiometer for motor feedback

100 to 2500 Ω

! Handling Precautions

- · UL-compliant models cannot be used at the 24 V DC contact rating.
- · For the motor connection, use cables with a rated voltage of 300 V or more and a rated temperature of at least 60 °C.

Ferrules

For details about the types and sizes of ferrules, see the table below.

Manufacturer: Phoenix Contact

Crimping tool: CRIMPFOX 6

- The use of ferrules to connect the I/O signal lines of this device is recommended.
- If you do not use ferrules, use the following types of wire.
 - DI/DO, RS-485, AI, AO-C, V-P, DI, DO:

Use 0.2 to 1.5 mm² solid or stranded wire and strip off 8 mm of insulation.

Display unit:

Use 0.2 to 0.5 mm^2 solid or stranded wire and strip off 6 mm of insulation.

• If using stranded wire, do not solder the end of the wire.

Insert it while pressing the release button straight with a flat-blade screwdriver.

Model number	Product number	Cross section area [mm ²]	Notes
AI 0,25-8 YE	3203037	0.25 (24 AWG)	With insulating sleeve
AI 0,34-8-TQ	3203066	0.34 (22 AWG)	With insulating sleeve
AI 0,5-8 WH	3200014	0.50 (20 AWG)	With insulating sleeve
AI 0,75-8 GY	3200519	0.75 (18 AWG)	With insulating sleeve
A1-8	3202517	1.00 (18 AWG)	Without insulating sleeve. For crimping two wires, each 0.5 mm ² (in cross- sectional area), together
A1,5-7	3200263	1.50 (16 AWG)	Without insulating sleeve. For crimping two wires, each 0.75 mm ² (in cross- sectional area), together
AI-TWIN 2x0, 5-8 WH	3200933	0.50 (20 AWG)	With insulating sleeve. For crimping two wires, each 0.5 mm ² (in cross- sectional area), together
AI-TWIN 2x0, 75-8 GY	3200807	0.75 (18 AWG)	With insulating sleeve. For crimping two wires, each 0.75 mm ² (in cross- sectional area), together

DI/DO, RS-485, AI, AO-C, V-P, DI, DO

MOTOR

Model number	Product number	Cross sectional area [mm ²]	Notes
AI0,75-8 BU	3200027	0.75 (18 AWG)	With insulating sleeve
Al1-8 RD	3200030	1.00 (18 AWG)	With insulating sleeve
AI1,5-8 RD	3201136	1.50 (16 AWG)	With insulating sleeve
AI2,5-10 BU	3202533	2.00(14 AWG)	With insulating sleeve

HMI (display unit)

Model number	Product number	Cross sectional area [mm ²]	Notes
AI 0,25-6 YE	3203024	0.25 (24 AWG)	Without insulating sleeve When connecting an external power supply to the terminal block of display unit.

USB connection

Connect the device to the PC using a USB-MicroUSB cable (type A/B).

📖 Note

• Use a data communication cable.

Inserting/removing micro SD Memory Card

To insert the card, push it all the way in. To eject the card, press it slightly.

! Handling Precautions

- Do not insert or remove the card while the indicator near the connector is on.
- To avoid danger, shut off the power supply before inserting/removing a microSD because it is located near the power supply terminal.

LAN Cable for Ethernet

Use a LAN cable of Cat5E or higher for connection.

Connecting Main Unit and Display Unit

• For standard installation and additional display unit (cable length: less than 30 m)

Use a Cat5E or higher straight LAN cable to connect them. (Cat5E, T568A or T568B wiring, both ends RJ45 plug (8P8C modular))

- Note 1. The main unit and display unit cannot be connected with a 4-core LAN cable.
 - 2. If the length of the cable between the main unit and the display unit is from 30 m to 100 m, an external power source must be connected for the display.

C the User's Manual for C7G Multi-loop Controller with Multifunction Display, No.CP-SP-1402E, (see Relevant USER'S Manual) for details.

• Wiring for integrating installation

Insert the ferrules (part of the cable for integrated mounting supplied with the product) with the specified colors into the terminal block of the display unit.

- 1: White/orange 4:White/green
- 2: Blue 5: Green
- 3: White/blue 6: Brown

Operation Check

When the power is turned on after connecting the main unit and display unit, the display turns on. The screen first displayed after power-on is called the initial screen.

- Display change button: Switches displays
- HOME button: Returns to the initial screen
- MENU/Key lock button: Displays a menu. Pressing the
 - button for four seconds or longer leads to a key lock status in which only disabling of the key lock can be performed. Pressing the button for four seconds or longer again disables the key lock.

Troubleshooting

Model Number and Serial Number

Model number and serial number are printed on the front of the upper part of the main unit. Please refer to them when making an inquiry.

Handling Problems in Installation

First, check the following regarding wiring:

- \cdot Connectors are securely inserted into the ports.
- \cdot Connectors are inserted into the right ports.
- Wires are properly connected to the power terminal block.

• Power is not turned on

Status	Countermeasures
The status indicator on the main unit is off.	Check the the power input connections and voltage.
The status indicator on the main unit is lit green or the power indicator on the display unit is off.	Standard mounting: Check the LAN cable (8-core straight). Check the connectors. Integrated mounting: Check if the wiring on the back of the display unit is correct. Check connectors on the main unit.
The power indicator on the display unit is lit green and the LCD remains black.	There may be a problem with the device. Please contact us.
The status indicator on the main unit is lit red.	There may be a problem with the device. Please contact us.

• Blurry images on display

A thin protective film is sealed on the display to protect the product label in transportation. Remove the protective film. If it is hard to remove the film, use cellophane tape.

• Occurrence of an alarm

G Multi-loop Controller with Multifunction Display Model C7G Installation and Configuration Manual, No. CP-SP-1402E. MEMO

MEMO

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