

NOTICE

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In no event shall Azbil Corporation be liable to anyone for any indirect, special or consequential damages. This information and specifications in this document are subject to change without notice.

Instruction Manuals

Safety-related precautions, general operating procedures, and other general information related to Model CFS100 (CommStaff) can be found in the Common Edition manual (No. CM2-CFS100-2001). For information on the operation of a device used with Model CFS100, consult the manual for that particular device.

The Common Edition manual for Model CFS100, as well as the manuals for individual devices, are included in electronic form (as PDF files) on the CommStaff installation CD-ROM

Devices Covered by This Manual

This manual pertains to AT9000 Advanced Transmitter Electronic Differential Pressure/Pressure Transmitter with the model number pattern $GTX _ _$ and $JT_9 _ _$.

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Chapter 1. Overview

1-1. Introduction

Model CFS100 (CommStaff) is a tool for communicating with Azbil Corporation's smart field devices (DSTJ and others) that enables configuration of device settings. It is a software product that operates on Windows PCs. CommStaff communicates with Azbil Corporation's smart field devices using a USB interface connected to a Windows PC, which is then connected by communications cable to the USB port of a device.

CommStaff supports Azbil Corporation's proprietary SFN/DE communication protocol as well as the HART communication protocol.

* HART is a registered trademark of the FieldComm Group.

For information on the specifications common to all types of devices and information on how to install CommStaff, please refer to the main Model CFS100 Operation Manual. Before reading this manual, make sure that you read the main Model CFS100 Operation Manual thoroughly.

For information on smart transmitter functions and method of connection, refer to manual No. CM2-GTX100-2001, AT9000 Advanced Transmitter model GTX (CM2-GTX100-2001) or AT9000 SuperAce (CM2-ATS100-2001) Electronic Differential Pressure/ Pressure Transmitter User's Manual

1-2. Important Notes

* When changing connected devices

CommStaff continues communicating with the device when displaying dynamic values, such as pressure, so that it can continuously update these values. If you remove the communications cable to change the device during this communication, an error will occur.

Exit CommStaff before detaching the communications cable from the device, and then start CommStaff again after connecting the communications cable to the new device.

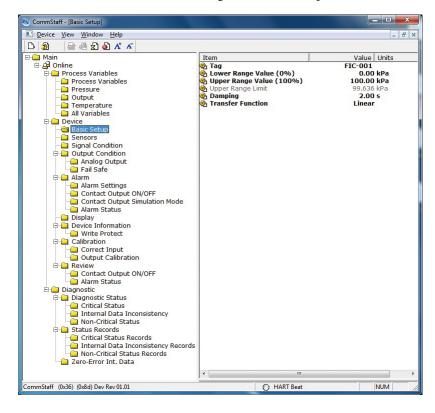
- * The use of SFN communication changes the transmission signal, so be sure to switch the process control loop to manual mode beforehand.
- * For known troubleshooting issues, refer to section 7.4 of CM2-CFS100-2001, the common edition manual.

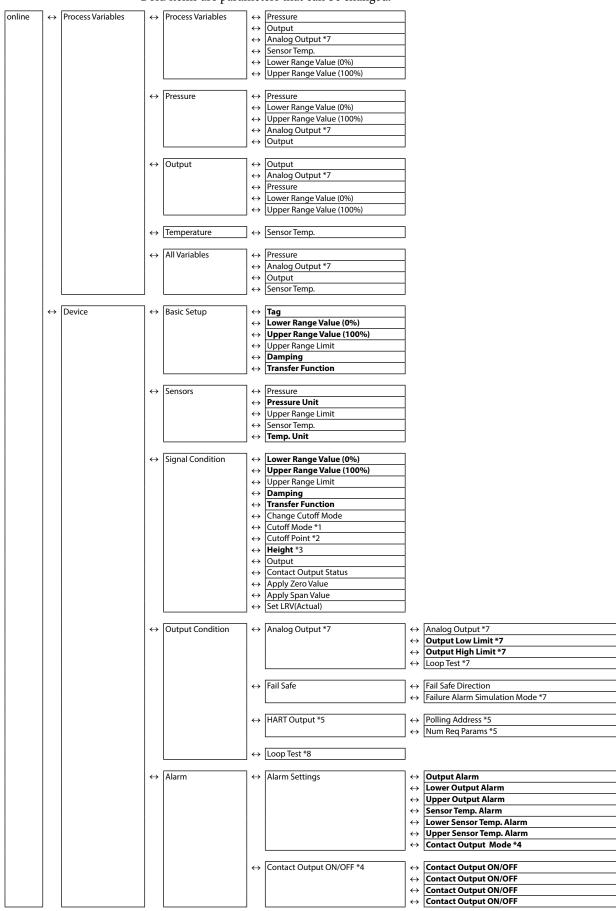
Chapter 2. Configuration

2-1. Menu List

Right-clicking Online on the menu tree in the left pane of the CommStaff application window displays a menu. Selecting Expand on the menu displays the expanded menu tree.

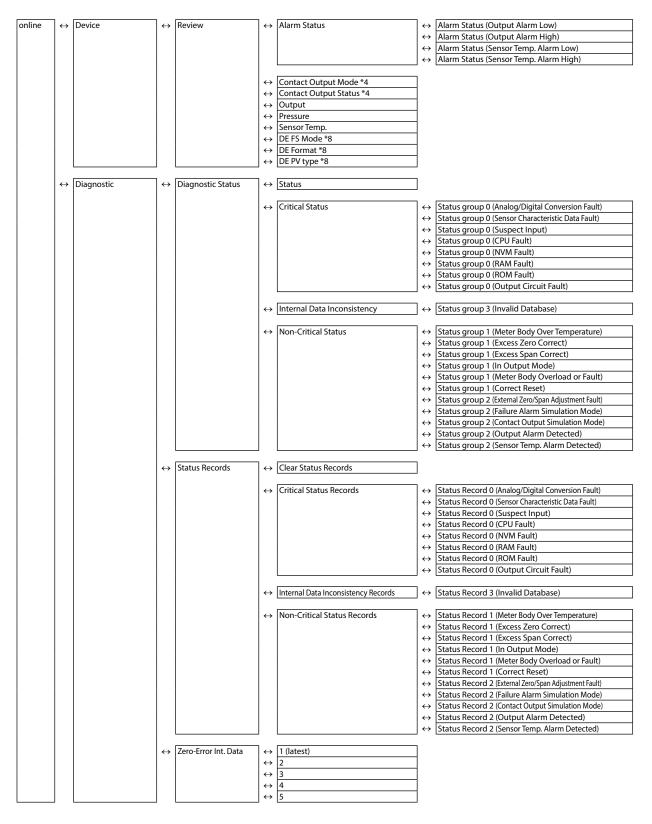
Parameters displayed in gray (Upper Range Limit in the following window) in the parameter display in the right pane are parameters that cannot be changed. Those displayed in black (Tag, Lower Range Value (0%), Upper Range Value (100%), Damping and Transfer Function in the following window) are the parameters that can be changed.





The following gives details of the menus displayed in the menu tree. Bold items are parameters that can be changed.

anlina	-				-			
online	\leftrightarrow	Device	\leftrightarrow	Alarm	\leftrightarrow	Contact Output Simulation Mode *4	$ \leftrightarrow$	
							\rightarrow	Closed
							_	
					$ \leftrightarrow$	Alarm Status	$ \leftrightarrow$	Alarm Status (Output Alarm Low)
							$ \leftrightarrow$	Alarm Status (Output Alarm High)
							$ \leftrightarrow$	Alarm Status (Sensor Temp. Alarm Low)
							$ \leftrightarrow$	Alarm Status (Sensor Temp. Alarm High)
1					1		\leftrightarrow	
				•	-		_	· · ·
			\leftrightarrow	Display	\rightarrow	Display Mode		
					\leftrightarrow	Display Function	-	
					$ \leftrightarrow$	Transfer Function	-	
							-	
					\leftrightarrow	EUHI (100%)	-	
					$ \leftrightarrow$		-	
					$ \leftrightarrow$	Disp. Unit	_	
					\leftrightarrow	User Unit	_	
					\leftrightarrow	Exponent		
					-		_	
			$ \leftrightarrow$	Device Information	\leftrightarrow	Manufacturer	_	
					\leftrightarrow	Model		
					\leftrightarrow	Measurement Type		
					\leftrightarrow	Device ID *5		
					$ \leftrightarrow$	Tag		
					\leftrightarrow	Date *5		
					\leftrightarrow		1	
	1				\leftrightarrow	Message	1	
					\leftrightarrow		-	
						PROM No.	-	
					\leftrightarrow			
					\leftrightarrow	Final Assembly Number *5	-	
					1	Software Version		
							_	
					$ \leftrightarrow$	Revision Numbers *5	\rightarrow	
	1						\leftrightarrow	Field Device Rev *5
					1		\leftrightarrow	Software Rev *5
	1				1	L	_ ``	
						Write Protect	\rightarrow	Hardware Write Protect
					17			
							\leftrightarrow	
							\leftrightarrow	Change SW Write Protect
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							\rightarrow	Scaled D/A min -/
				DE Configuration *6	٦.,	DE ES Mada *6	7	
				DE Configuration *6	\leftrightarrow		-	
						DE Format *6	_	
						DE PV type *6	_	
						Switch Analog to DE *6 *7		
					\leftrightarrow	Switch DE to Analog *6 *8		
	1		1					
		1						
			\leftrightarrow	Review	\rightarrow	Model		
			\leftrightarrow	Review	$\left \begin{array}{c} \leftrightarrow \\ \leftrightarrow \end{array} \right $			
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			\leftrightarrow	Review	$\begin{array}{c} \diamond \\ \diamond \\ \diamond \\ \diamond \\ \diamond \\ \diamond \end{array}$	Measurement Type Transfer Function Cutoff Point Cutoff Mode		
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			\leftrightarrow	Review	$\begin{array}{c} \uparrow \uparrow$	Measurement Type Transfer Function Cutoff Point Cutoff Mode Height *3 PROM No. Software Rev *5		
			\leftrightarrow	Review	$\begin{array}{c} \uparrow \uparrow$	Measurement Type Transfer Function Cutoff Point Cutoff Mode Height *3 PROM No. Software Rev *5 Software Version *6		
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			\leftrightarrow	Review	\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$	Measurement Type Transfer Function Cutoff Point Cutoff Mode Height *3 PROM No. Software Rev *5 Software Version *6 Damping Lower Range Value (0%) Upper Range Value (100%) Upper Range Limit Fail Safe Direction Display Mode Disp. Unit User Unit EULO (0%) EUHI (100%) Exponent Output Low Limit *7 Output High Limit *7 Output Alarm Low Output Alarm Lower Sensor Temp. Alarm		Contact Output ON/OFF (Output Low)
			\leftrightarrow	Review	\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$	Measurement Type Transfer Function Cutoff Point Cutoff Mode Height *3 PROM No. Software Rev *5 Software Version *6 Damping Lower Range Value (0%) Upper Range Value (100%) Upper Range Limit Fail Safe Direction Display Mode Disp. Unit EULO (0%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) Exponent Output Alarm Low Output Alarm Lower Sensor Temp. Alarm Upper Sensor Temp. Alarm	\leftrightarrow	Contact Output ON/OFF (Output High)
			\leftrightarrow	Review	\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$	Measurement Type Transfer Function Cutoff Point Cutoff Mode Height *3 PROM No. Software Rev *5 Software Version *6 Damping Lower Range Value (0%) Upper Range Value (100%) Upper Range Limit Fail Safe Direction Display Mode Disp. Unit EULO (0%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) Exponent Output Alarm Low Output Alarm Lower Sensor Temp. Alarm Upper Sensor Temp. Alarm	\leftrightarrow	Contact Output ON/OFF (Output High) Contact Output ON/OFF (Sensor Temp. Low)
			\leftrightarrow	Review	\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$	Measurement Type Transfer Function Cutoff Point Cutoff Mode Height *3 PROM No. Software Rev *5 Software Version *6 Damping Lower Range Value (0%) Upper Range Value (100%) Upper Range Limit Fail Safe Direction Display Mode Disp. Unit EULO (0%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) EUHI (100%) Exponent Output Alarm Low Output Alarm Lower Sensor Temp. Alarm Upper Sensor Temp. Alarm	\leftrightarrow	Contact Output ON/OFF (Output High)



- *1 Valid when Transfer Function is set to Sq root. (Displayed.)
- *2 Valid when Cutoff mode is not set to DEFAULT. (Displayed.)
- *3 Valid when a GTX _ _ R or JTE model is connected. (Displayed.)
- *4 Valid if the contact output option is selected. (Displayed.)
- *5 Not displayed if SFN or DE communication is selected.
- *6 Not displayed if HART communications is selected.
- *7 Not displayed if DE communication is selected.
- *8 Valid (displayed) if DE communication is selected.

Setting items and references

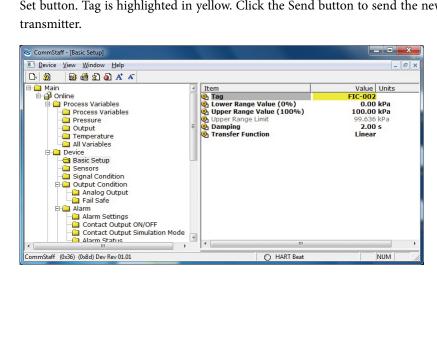
	Task	Parameter	Section of Manual
Preparation,	Tag No., set or check	TAG	2.2
Adjustment	Measurement range, check or change	Basic Setup	2.6
	Linear/square root output signal, check or set	Transefer Function	2.3
	Output limit (saturation point), check or set	Output Limit	2.9
	Damping time constant, check or set	Damping	2.8
	Units of pressure, check or change	Pressure Unit	2.5
	Zero adjustment, execute	Apply value	3.2
	Zero adjustment, execute (when current input value is not 0 %)	Set LRV (Actual)	3.3
	Output behavior in case of error, check	Fail Safe Direction	3.4
	Loop test, execute	Loop Test	3.1
	Alarm settings, check or change	Alarm Settings	2.10
	Contact output setting, check or change	Contact Output ON/OFF	2.11
	Indicator, set	Display	2.4
Maintenance	Calibrate	Correct Input	4.2
	Calibration default settings, restore	Restore factory setting	4.3
	Self-diagnosis messages, check	Diagnostic Status	4.4
	Self-diagnosis log, check	Status Records	4.5

Tag Number Configuration 2-2.

This section explains how to input or change the tag No. In the menu tree in the left pane, select Device \rightarrow Basic Setup \rightarrow Tag.

CommStaff - [Basic Setup]		
Device View Window Help		_ 8 ×
D 🔊 🖓 🖑 🛣 🖓 🗡 🗸		
Main Main Process Variables Process Variables	 Item Tag Lower Range Value (0%) Upper Range Value (100%) Upper Range Limit Damping Transfer Function 	Value Units FIC-001 0.00 kPa 100.00 kPa 99.636 kPa 2.00 s Linear
CommStaff (0x36) (0x8d) Dev Rev 01.01	🕥 HART Beat	NUM

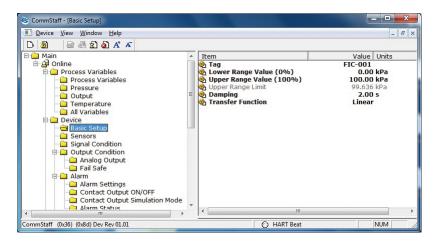
Double-clicking Tag displays the settings screen. On this screen, set the Tag and click the Set button. Tag is highlighted in yellow. Click the Send button to send the new Tag to the



2-3. Output Format Configuration

This section explains how to switch between linear and square root output. This menu is useful for when communicating with a differential pressure transmitter.

Select Device \rightarrow Basic Setup \rightarrow Transfer Function.

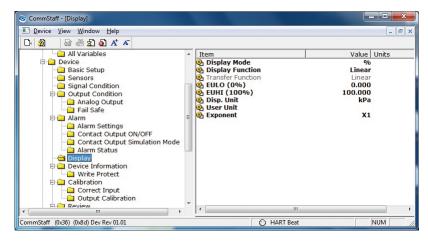


Linear: Linear output Sq root: Square root output

2-4. Indicator Display Format

This section explains how to configure the display format of the indicator and the upper and lower limits for engineering units.

Select Device \rightarrow Display.



Some parameters are enabled while others are disabled, depending on the Display Mode settings.

In the following table, enabled parameters are indicated with the \bigcirc symbol and disabled parameters with the — symbol.

Display Mode	%	Pressure	Scale
Display Function	0	—	0
Transfer Function	As in reference information	As in reference information	As in reference information
EULO (0%)	—	—	0
EUHI (100%)	—	—	0
Disp. Unit	—	—	0
User Unit	—	_	— (Jap. vers.: SI units) ○ (Eng. vers.: SI & non-SI)
Exponent	—	—	0

2-4-1. Display format

This function is enabled if Transfer Function is set to Linear.

Configuration	Description	
Linear	Indicates that both output and display are linear.	
Square root	Indicates output is linear and display is square root.	

2-4-2. EULO/EUHI (upper and lower limits for engineering units)

This is enabled when Display Mode is set to Scale.

EULO and EUHI values are the upper and lower limits for engineering units (scale readings) displayed on the indicator. They are displayed in the range of -19999 to +19999.

- EULO: Value displayed when output is 0%.
- EUHI: Value displayed when output is 100%.

2-4-3. Disp. Unit

This is enabled when Display Mode is set to Scale. Disp. Unit is displayed on the indicator. Values shown in the table below may be selected.

(Japanese version:	SI)
--------------------	-----

kPa	MPa	Ра	hPa	kPaG
MPaG	kPa abs	MPa abs	Pa abs	hPa abs
g/cm3	kg/m3	m3	I	kl
ml/h	l/h	kl/h	t/h	m3/h
km3/h	l/min	kl/min	m3/min	kl/d
m3/d	t/d	kg/h	mm	m
%	t	kg	none	

(English version: non-SI)

user define unit	mmH2O	mmAq	mH2O	inH2O
ftH2O	kPa	MPa	Ра	hPa
kPaG	MPaG	kPa abs	MPa abs	Pa abs
hPa abs	bar	mbar	barG	mbarG
mmHg	inHg	mmHg abs	inHg abs	gf/cm2
kgf/cm2	g/cm2	kg/cm2	kgf/cm2G	kgf/cm2 abs
atm	Torr	psi	g/cm3	kg/m3
m3	I	kl	ml/h	l/h
kl/h	Skl/h	Sm3/h	t/h	m3/h
km3/h	Nm3/h	kNm3/h	l/min	kl/min
m3/min	Nml/min	NI/min	Nm3/min	kl/d
m3/d	t/d	Nm3/d	kg/h	gal/min
gal/h	mm	m	%	t
kg	none			

2-4-4. User Unit

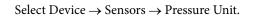
Non-SI units are available in the English version only. This is enabled when Display Mode is set to Scale. Available when Disp. Unit is set to User define unit. Any desired display unit can be set.

2-4-5. Exponent

This is enabled when Display Mode is set to Scale. By setting Exponent, "x10," "x100," or "x1000" can be shown on the display. If "x1" is set, it is not shown on the display.

2-5. Selecting a Unit of Pressure

This function allows you to select the measurement units for pressure used by the transmitter.



Device View Window Help	
	. 8 ×
D. 20 20 20 20 At A	
Item Value Units Precess Variables 0.0023 kPa Pressure 0.0023 kPa Pressure 0.0023 kPa Output 99.635 kPa Output 99.635 kPa Device Basic Setup Sensore 99.635 kPa All Variables 97.635 kPa Output 0.0023 kPa Marrisolation 99.635 kPa Pressure 99.635 kPa Alarn Setup 97.635 kPa Analog Output 17.617 kPa Analog Output 17.617 kPa Analog Output 17.617 kPa Analog Output 17.617 kPa Contact Output ON/OFF 17.617 kPa Contact Output ON/OFF 17.617 kPa Display 11.617 kPa	4
CommStaff (0x36) (0x8d) Dev Rev 01.01	

Units for pressure can be selected from the following.

(Jap.	vers.:	SI	units)

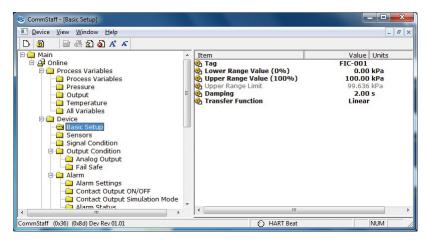
V 1	,		
kPa	MPa	Ра	hPa

(Eng. vers.: SI & non-SI)

mmH2O	mH2O	inH2O	kPa	MPa
Pa	hPa	bar	mbar	mmHg
inHg	g/cm2	kg/cm2	atm	Torr
psi				

2-6. Measurement Range Configuration

This section explains how to configure the measurement range of the transmitter. Select Device \rightarrow Basic Setup.



Lower Range Value (0%): Value at which 4 mA is output Upper Range Value (100%): Value at which 20 mA is output

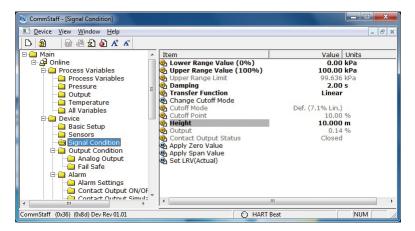
Note: In SFC and CommPad, when the LRV (Lower Range Value (0%)) is changed, the URV (Upper Range Value (100%)) also changes by the same amount in order to keep SPAN unchanged. In CommStaff, when Lower Range Value (0%) is changed, Upper Range Value (100%) does not change.

2-7. Function for Adjusting the Temperature of a Sealed Liquid

This function is valid only when a GTX__R or JTE model is connected. If a model other than GTX__R or JTE is connected, the menu is not displayed.

For remote seal pressure transmitters, this is Azbil Corporation's original correction function for minimizing the size of zero point shifts caused by density change in a sealed liquid. Specifically, a temperature sensor on the transmitter measures the ambient temperature, and on this basis the density is corrected.

For this function to be enabled, the height between flanges of the tank on which the transmitter is mounted must be specified.



Select Device \rightarrow Signal Condition \rightarrow Height.

Input the height difference between the flanges in meters. If this function is not enabled, "0.00 m" is displayed.

2-8. Damping Time Constant Configuration

This section explains how to configure the damping time constant. Select Device \rightarrow Basic Setup \rightarrow Damp.

CommStaff - [Basic Setup]				
Device View Window Help				_ 8 ×
D 2 4 2 2 2 5 X X				
Main Main Process Variables Process Variables Pressure Output Temperature All Variables Signal Condition Anango Output Fail Safe Alarm Arm Settings Contact Output Simulation Mode Alarm Alarm	4	Item Tag Tag Lower Range Value (0%) Upper Range Value (100%) Upper Range Limit Damping Transfer Function	Value FIC-001 0.00 100.00 99.636 2.00 Linear	(Pa
CommStaff (0x36) (0x8d) Dev Rev 01.01		O HART Beat	1	NUM //

If SFN communication is used, set a value in the range of 0 to 32 seconds.

The following values can be input. If a value other than the following is input, the closest value is automatically selected.

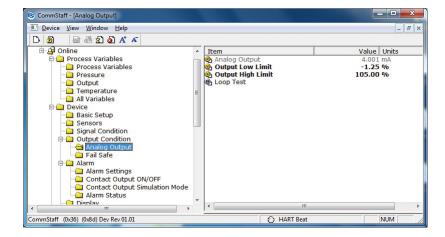
0.0 0.16 0.32 0.48 1.00 2.00 4.00 8.00 16.0 32.0	Unit: sec.
0.32 0.48 1.00 2.00 4.00 8.00 16.0	0.0
0.48 1.00 2.00 4.00 8.00 16.0	0.16
1.00 2.00 4.00 8.00 16.0	0.32
2.00 4.00 8.00 16.0	0.48
4.00 8.00 16.0	1.00
8.00 16.0	2.00
16.0	4.00
	8.00
32.0	16.0
	32.0

If HART communication is used, set a value in the range of 0 to 120 seconds.

2-9. Output Limit (Output Saturation Point) Configuration

Output limit is enabled only when Burnout is upward or downward. It is disabled if a nonburnout transmitter is used.

The output limit configuration is for specifying the saturation point for output current under normal conditions.



Select Device \rightarrow Output Condition \rightarrow Analog Output.

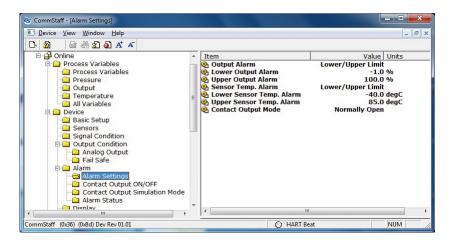
The following are the ranges of possible values.

Lo Limit: -2.50 to 49.99 % Hi Limit: 50.00 to 110.00 %

2-10. Alarm Settings

There are two types of alarm: Output Alarm for detecting output values and Sensor Temp. Alarm for detecting sensor temperatures. For models that support contact output, alarm results can be generated as contact outputs.

Select Device \rightarrow Alarm \rightarrow Alarm Setting.



The following are the four Output Alarm settings.

No Alarm	No alarm detection	
Lower Limit	Only Lower Output Alarm detection.	
Upper Limit	Only Upper Output Alarm detection.	
Lower/Upper Limit Both Lower Output Alarm and Upper Output Alarm detection.		

The following are the four Sensor Temp. Alarm settings.

No Alarm	No alarm detection	
Lower Limit	Only Lower Output Alarm detection.	
Upper Limit	Only Upper Output Alarm detection.	
Lower/Upper Limit	Both Lower Output Alarm and Upper Output Alarm detection.	

On models with a contact output function, contact output mode can be set.

There are 2 types of Contact Output Mode, as shown below.

Normally Open	Contacts are normally open.
Normally Closed	Contacts are normally closed.

2-11. Contact Output Settings

Contact Output can be set to ON or OFF.

ON: Contact output is valid. OFF: Invalid.

Chapter 3. Preparations and Starting Operation

This chapter explains how to prepare for transmitter operation, and provides general instructions to follow when starting transmitter operation.

3-1. Confirmation of Output Signals (Loop Test)

By putting the transmitter in constant current mode, you can keep current outputs constant in the range of 4 - 20 mA. This section explains how to configure the constant current mode and how to return to normal output mode.

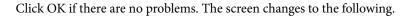
Select Device \rightarrow Output Condition \rightarrow Analog Output \rightarrow Loop Test.

CAUTION: If this operation is performed while the transmitter process is under automatic control, outputs may fluctuate, making transmitter operation dangerous. Before performing this operation, make sure that you switch the process control loop to manual control.

CommStaff - [Analog Output]			x
Device View Window Help		-	5 ×
D 2 4 4 2 5 5 K K			
Main Main Process Variables Process Variables Pressure Uput Temperature Basic Setup Sensors Sensors All Variables Device Analog Output Fail Safe Alarm Alarm Settings Contact Output ON/OFF Contact Output Simulation Mode Alarm Status	Item Analog Output Output Low Limit Output High Limit Loop Test Item Item Item Item Item Item Item It	Value Units 4.001 mA -1.25 % 105.00 %	Þ
CommStaff (0x36) (0x8d) Dev Rev 01.01	HART Beat	NUM	- //

Double-clicking Loop Test displays the following screen.

Loop Test		
WARN-Loop should be r	emoved from automatic control	
Press OK button to continue meth	od execution or Abort button to abort m	ethod execution.
Help	Abort	[0K]



Loop Test
Choose analog output level 4 mA 8 mA 12 mA 16 mA 20 mA Other End
Press DK button to continue method execution or Abort button to abort method execution.
Help Abort OK

SFN communication

Select 4 mA and click OK. Output signals will be fixed at 4 mA (0%). Select 8 mA and click OK. Output signals will be fixed at 8 mA (25%). Select 12 mA and click OK. Output signals will be fixed at 12 mA (50%). Select 16 mA and click OK. Output signals will be fixed at 16 mA (75%). Select 20 mA and click OK. Output signals will be fixed at 20 mA (100%). To input a different value, select Other and Click OK. If you select End and click OK, a message is displayed notifying you that normal output mode will resume.

• HART communication

Select 4 mA and click OK. Output signals will be fixed at 4 mA (0%). Select 20 mA and click OK. Output signals will be fixed at 20 mA (100%). To input a different value, select Other and Click OK. If you select End and click OK, a message is displayed notifying you that normal output mode will resume.

3-2. Range Configuration (Zero and Span Adjustments) according to Input Pressure

The range can be configured so that the current pressure input into the transmitter becomes 4 mA (0%) or 20 mA (100%).

CAUTION: If this operation is performed while the transmitter process is under automatic control, outputs may fluctuate, making transmitter operation dangerous. Before performing this operation, make sure that you switch the process control loop to manual control.

3-2-1. Zero adjustment

The following describes how the range can be set Zero adjustment to input pressure. Select Device \rightarrow Signal Condition \rightarrow Apply Zero Values.

该 CommStaff - [Signal Condition]		
	 Item Upper Range Value (0%) Upper Range Limit Damping Transfer Function Change Cutoff Mode Cutoff Mode Cutoff Point Output Contact Output Status Apply Zero Value 	Value Units 0.00 kPa 100.00 kPa 99.636 kPa 2.00 s Linear Def. (7.1% Lin.) 0.00 % 0.00 % 0.00 % Open
Contact Output Simulation Mode Alarm Status Display Calibration Calibration Calibration Correct Input Correct Input CommStaff (0x36) (0x8d) Dev Rev 01.01	Apply Span Value Set LRV(Actual)	NUM 4

Double-clicking Apply Zero Value displays the following warning. If there are no problems, click OK.

Ap	oply Span Value
	WARN-Loop should be removed from automatic control
	Press OK butten to continue mathed everytion or Abort butten to abort mathed everytion
	Abort DK
	Press OK button to continue method execution or Abort button to abort method execution.

Input the pressure that corresponds to 4 mA and click OK.

oply Zero Value		
Apply new 4 mA input.		
Press OK button to continue metho	ad execution or Abort button to abort	method execution
	od execution or Abort button to abort Abort	method execution.

After the input pressure stabilizes, click OK.

Apply Zero Value		
Press OK when pressure is stable		
Press DK button to continue method execution o		
Help	Abort	OK

The current input pressure is displayed.

If there are no problems, select "Set as 4 mA value" and click OK.

Current applied proce	ess value: 0.007 kPa
Set as 4 mA value	
Set as 4 mA value	A
Read new value Leave as found.	
LCOVE AS IUUIIU.	
Press OK button to continue	method execution or Abort button to abort method execution.
	Abort OK

To reread the input pressure, select "Read new value" and click OK. To end the adjustment process, select "Leave as found" and click OK.

3-2-2. Span adjustment

The following describes how the range can be set Span adjustment to input pressure. Select Device \rightarrow Signal Condition \rightarrow Apply Span Values.

CommStaff - [Signal Condition]			
Device View Window Help			- 8 ×
D 🕘 🗟 🖑 🛣 🖉 🗡 🔺			
All Variables Device Basic Setup Sensors Output Condition Analog Output Fail Safe Alarm Settings Contact Output ON/OFF Contact Output Simulation Mode Alarm Status Device Information Write Protect Calibration Output Calibration Review m	A	Item Item Upper Range Value (0%) Upper Range Limit Damping Transfer Function Cutoff Mode Cutoff Mode Cutoff Mode Cutoff Vaint Contact Output Status Apply Span Value Set LRV(Actual)	Value Units 0.00 kPa 99.636 kPa 2.00 s Linear Def. (7.1% Lin.) 0.00 % 97.95 % Open
CommStaff (0x36) (0x8d) Dev Rev 01.01		O HART Beat	NUM //

Double-clicking Apply Span Value displays the following warning. If there are no problems, click OK.

ply Span Value		
WARN-Loop should be	e removed from automatic control	
Press OK button to continue m	ethod execution or Abort button to abort me	thod execution.

Input the pressure that corresponds to 20 mA and click OK.

Apply	y Span Value
	Apply new 20 mA input.
F	Press OK button to continue method execution or Abort button to abort method execution.
	Help Abort OK

After the input pressure stabilizes, click OK.

Apply Span Value		
Press OK when pressure is s	table	
Press OK button to continue method e	xecution or Abort button to abort method ex	xecution.
Help	Abort	ОК

The current input pressure is displayed.

If there are no problems, select "Set as 20 mA value" and click OK.

Apply Span Value	
Current applied proce	
Set as 20 mA value	
Set as 20 mA value	A
Read new value	
Leave as found.	T
Press DK button to continue r	method execution or Abort button to abort method execution.
Help	Abort OK

To reread the input pressure, select "Read new value" and click OK. To end the adjustment process, select "Leave as found" and click OK.

3-3. Zero Point Adjustment according to the Actual Level

This section explains how to adjust the zero point according to the actual level. Perform this adjustment process when you want to set the present tank level to a specific value, for example, 50%.

다 최 쇄 원 호 장 작 조	^ Item	Value Units
Device Device Device Sensors Signal Condition Output Condition Analog Output Fail Safe Alarm Alarm Settings Contact Output ON/OFF Contact Output Simulation Mode Alarm Status Display Device Information Write Protect Calibration Output Calibration Output Calibration Review	Letin Lower Range Value (0° Upper Range Value (10 Upper Range Limit Damping Transfer Function Cutoff Mode Cutoff Mode Cutoff Mode Cutoff Point Output Contact Output Status Apply Sero Value Apply Sero Value Set LRV(Actual)	%) 0.00 kPa

Select Device \rightarrow Signal Condition \rightarrow Set LRV (Actual).

After two confirmation messages appear, the following screen is displayed. Enter the output value in percent that you want to assign, and click OK.

Set LRV(Actual)		
Enter output percent f	or current input	
Press UK button to continue i	method execution or Abort button to abort m	ethod execution.
Help	Abort	OK

The new LRV and URV are displayed.

If there are no problems, select "Set new LRV, URV" and click OK.

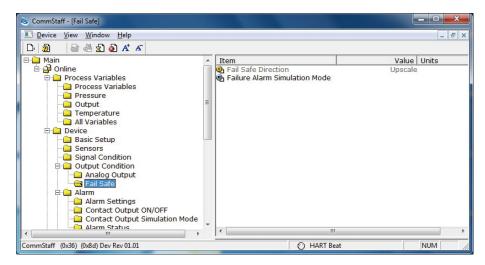
Enter percent : 50.00 % New LRV : -49.9901 43 k New URV : 50.007332 k	<pa< th=""></pa<>
Set new LRV, URV	•
Set new LRV, URV Read new value Leave as found	• •

To reread the input pressure, select "Read new value" and click OK. To end the adjustment process, select "Leave as found" and click OK.

3-4. Confirmation of Output Direction in Abnormal Operating Conditions

This section explains how to check the output direction in abnormal operating conditions. Select Device \rightarrow Output Condition \rightarrow Fall Safe.

Fail Safe Direction is the output direction under abnormal operating conditions.



Failure Alarm Simulation Mode allows you to perform a simulation of output current in abnormal operating conditions.

Double-clicking will display first the confirmation screen and then the following screen.

Failure Alarm Simulation Mode	
Set Failure Alarm Simulation Mode	
Press OK button to continue method execution o	Abort button to abort method execution.
Help	Abort OK

Click OK, and the output current will change to the same output as the output in abnormal operating conditions.

To end this process, select "End Simulation Mode" and click OK.

Failure Alarm Simulation Mode		
Now this device is in Failu Continue Simulation M	re Alarm Simulation Mode	
Continue Simulation M End Simulation Mode		
Press OK button to continue metho	d execution or Abort button to abort i	method execution.
Help	Abort	ОК

* Failure Alarm Simulation Mode becomes invalid with the DE output.

Chapter 4. Maintenance

This chapter explains how to calibrate the analog signals of the transmitter, how to calibrate the measurement range, and how to reset a calibrated value to the default value. It also explains how to check the transmitter's self-diagnostic messages.

4-1. Calibration of Analog Outputs

By connecting to an ammeter and comparing measured values, you can calibrate the 0% and 100% analog outputs.

Select Device \rightarrow Calibration \rightarrow Output Calibration \rightarrow D/A Trim.

CAUTION: If this operation is performed while the transmitter process is under automatic control, outputs may fluctuate, making transmitter operation dangerous. Before performing this operation, make sure that you switch the process control loop to manual control.

S CommStaff - [Output Calibration]					• ×
Device View Window Help					- 8 ×
D 2 2 2 2 2 2 2 5 5					
Device Basic Setup Sensors Signal Condition Output Condition Analog Output Fail Safe Alarm Settings Contact Output ON/OFF Contact Output Simulation Mode Alarm Status Display Device Information Write Protect Calibration Correct Input Contact Output Colibration Review	E	Item D/A Trim Scaled D/A Trim	Va	alue U	nits
Contact Output ON/OFE		•			+
CommStaff (0x36) (0x8d) Dev Rev 01.01			O HART Beat	N	

Step	Operation and indication
1	Double-click D/A Trim.
	WARN - Loop should be removed from automatic control
	A warning that the loop should be switched from automatic control to
	manual mode is displayed. After switching to manual mode, click OK.
	"Connect reference meter" is displayed. Connect the loop to an
	ammeter (mA) or voltmeter. (It is recommended that an ammeter or
	voltmeter with an accuracy of 0.03% or better be used.)
2	The following messages are displayed in the order given.
	Setting fld dev output to 4mA (about to set transmitter output to 4
	mA)
	Click OK if there are no problems.
	Enter meter value (input the ammeter reading).
	Input the reading of the ammeter and click OK. This allows the
	adjustment command to be sent to the transmitter.
	Eld day output 4,000mA agual to reference meter? (is the transmitter
	Fld dev output 4.000mA equal to reference meter? (is the transmitter output equal to the reading on the connected ammeter?)
	If the transmitter output is not equal to the reading of the ammeter,
	select No and click OK. This allows the adjustment process to continue.
3	Next do the 20 mA calibration.
	The following messages are displayed in the order given.
	Setting fld dev output to 20mA (about to set transmitter output to 20
	mA)
	Click OK if there are no problems.
	Enter meter value (input the ammeter reading)
	Input the reading of the ammeter and click OK. This allows the
	adjustment command to be sent to the transmitter.
	Fld dev output 20.000mA equal to reference meter? (is the transmitter
	output equal to a reading of the connected ammeter?)
	If the transmitter output is not equal to the reading of the ammeter,
	select No and click OK. This allows the adjustment process to continue.
	Finally, a message is displayed notifying you that this will return
	operation to normal measurement mode and that the 20 mA
	calibration process is complete.

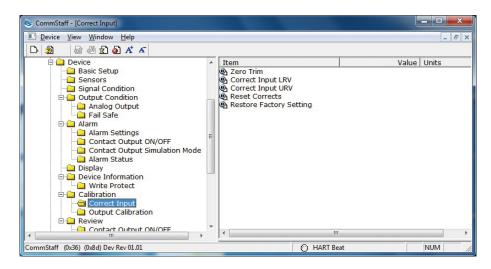
4-2. Measurement Range Calibration according to Actual Pressure

For the AT9000 series Electric differential pressure and pressure transmitters, the measurement range must be calibrated at two points, namely the Lower Range Value (input value at 0% output) and Upper Range Value (input value at 100% output).

This calibration is done when calibrating actual pressures using a standard pressure transmitter. For further details, refer to Chapter 5, "Maintenance" in AT9000 Advanced Transmitter model GTX (CM2-GTX100-2001) or AT9000 SuperAce (CM2-ATS100-2001).

CAUTION: If this operation is performed while the transmitter process is under automatic control, outputs may fluctuate, making transmitter operation dangerous. Before performing this operation, make sure that you switch the process control loop to manual control.

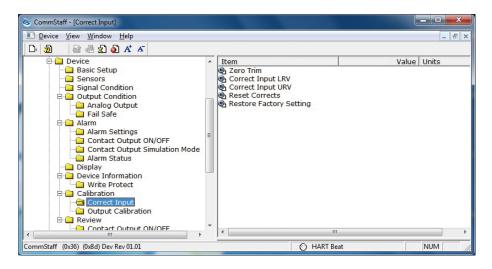
Select Device \rightarrow Calibration \rightarrow Correct Input.



- To calibrate the LRV (Lower Range Value) value, double-click Correct Input LRV. To calibrate the URV (Upper Range Value) value, double-click Correct Input URV.
- A warning that the loop should be switched from automatic control to manual mode is displayed (WARN Loop should be removed from automatic control). After switching to manual mode, click OK.
- "Apply LRV pressure" or "Apply URV pressure" is displayed. If the value of the standard pressure generator is equal to LRV (0%) or URV (100%), click OK.
- "Press OK when pressure is stable" is displayed. After confirming that input pressure has stabilized, click OK.
- The "Note Loop may be returned to automatic control" message is displayed to notify you that you can now switch back to automatic control. Click OK.

4-3. Calibrated Value Reset

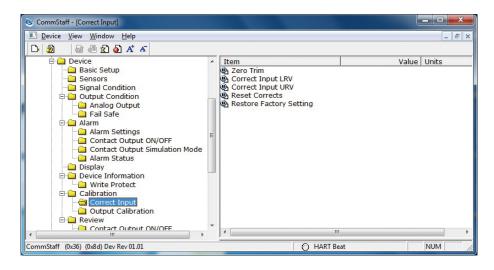
The calibrated zero span value can be reset to the factory-set value. Select Device \rightarrow Calibration \rightarrow Correct Input.



- CAUTION: If this operation is performed while the transmitter process is under automatic control, outputs may fluctuate, making transmitter operation dangerous. Before performing this operation, make sure that you switch the process control loop to manual control.
- Double-click Reset Corrects. The "WARN Loop should be removed from automatic control" message is displayed, warning that the loop should be switched from automatic control to manual mode. After switching to manual mode, click OK.
- The "About to Reset corrects" message is displayed to notify you that calibrated values will be reset. Click OK.
- After the calibrated values are reset, "Reset Corrects OK" is displayed. Click OK.
- The "Note Loop may be returned to automatic control" message is displayed to notify you that you can now switch the loop back to automatic control. Click OK.

4-4. Checking Self-diagnostic Messages

You can check self-diagnostic messages by clicking the Status icon or "Device status" in the "Display" menu.



For example, the button to the left of CORRECTS RESET turns red after the calibrated values are reset.

There are 4 status groups. The self-diagnosis details are shown for each group.

	d Device Status - 2
0	Meter Body Over Temperature
Ø	Excess Zero Correct
0	Excess Span Correct
0	In Output Mode
0	Meter Body Overload or Fault
Ø	Status 1-5
0	Correct Reset
0	Status 1-7

The following gives details of the information on self-diagnosis.

	Status message	Meaning	Required action	Display of Indicator
Internal data inconsistency	Invalid database	Indicates that the settings stored in EEPROM are not correct at the time the power is turned on. However, after the data is reset correctly the error status will be cleared.	Try communicating again. Verify configuration data and recalibrate the device.	Err.09 CONFIG
Critical failure	Analog/Digital Conversion Fault	Input signals for the A/D converter or its peripheral circuits are abnormal.	Contact appropriate personnel.	Err.01 A-D CNV
	Sensor Characteristic Data Fault	There is an error in the characteristic data for the sensor.	Contact appropriate personnel.	Err.02 PROM
	Suspect Input	Sensor operation failure.	Contact appropriate personnel.	Err.03 INPUT
	CPU Fault	CPU (MPU:Micro processing Unit) operation failure	Contact appropriate personnel.	Err.04 CPU
	NVM Fault	EEPROM failure	Contact appropriate personnel.	Err.05 NVM
	RAM Fault	RAM failure	Contact appropriate personnel.	Err.06 RAM
	ROM Fault	ROM failure	Contact appropriate personnel.	Err.07 ROM
	Output Circuit Fault	which the power voltage supplied to the transmitter dips for 1 second or more. Also, if the supply voltage has been abnormal for about 3 minutes, this alarm is displayed.	Contact appropriate personnel.	Err.08 OUTPUT
Non-critical status	Meter Body Over Temperature	Meterbody temperature is too high. The temperature of sensor in the meterbodyexceeds 125 degree C.	Reinstall the device to decrease the temperature to within specifications.	AL.20 M/B.TEMP
	Excess Zero Correct	The zero correction factor is outside the acceptable limits for accurate operation.	Check the input and be sure it matches the calibrated range value.	AL.21 ZERO.CAL
	Excess Span Correct	The span correction factor is outside the acceptable limits for accurate operation.	Check the input and be sure it matches the calibrated range value.	AL.22 SPAN.CAL
	In Output Mode	The device is operating in output mode (Loop test).	Go to the output mode menu to exit the output mode.	Output % OUTMODE
	Meter Body Overload or Meter Body Fault	- The input pressure is more than two times The upper range limit for The device. - Device error.	Check the PV value and replace the device with a larger range model if necessary.	AL.24 OVRLOAD
	Correct Reset	Calibration data is cleared.	Calibrate the lower and upper range values.	AL.26 NO.CALIB
	External Zero/Span Adjustment Fault	External zero/span adjustment error. When external zero/ span adjustment is available, this alarm is displayed if the zero or span adjustment switch is turned on for 45 seconds or more, or if both switches are turned on at the same time.	Contact appropriate personnel.	AL.AL.28 SWITCH28
	Contact Output Simulation Mode	The device is operating contact output simulation mode.	To exit contact output simulation mode, go to the alarm/contact output menu.	[Blank] DO.SIM
	Output Alarm Detected	The output is going over upper/lower limit of output alarm.	Check the output.	AL.51 OUT%.AL
	Sensor Temp. Alarm Detected	The sensor temperature is going over upper/lower limit of sensor temp. alarm.	Check the sensor temperature.	AL.52 TEMP.AL

With the AT9000, values can be checked or configured by viewing data in the EDD menu format.

EDD can present data related to self-diagnoses in an easy-to-understand manner. Click View on the menu bar and select Diagnostic from the menu.

💵 <u>D</u> evice <u>V</u> i	ew <u>W</u> indow <u>H</u> elp	_				- 8 >
	Toolbar	ds sistency Recor	E	Item Diagnostic Status Status Records Zero-Error Int. Data	Value Units	
•		•		< III		

Diagnostic results are displayed in the EDD menu format.

CommStaff - [Diagnostic]		
Device View Window Help		_ 6
Diagnostic Status Status Records Zero Calibr. Log I	n Device	
Device Tag		
Tag FIC-001		Status 👔 📷
		Status Non-Critical
		Nor-Critical
Status		
Critical Status	Internal Data Inconsistency	
Analog/Digital Conversion Fault	Invalid Database	
Sensor Characteristic Data Fault	Non-Critical Status	
Suspect Input	Meter Body Dver Temperature	🚳 External Zero/Span Adjustment Fault
🐵 CPU Fault	Excess Zero Correct	Failure Alarm Simulation Mode
NVM Fault	Excess Span Correct	Contact Output Simulation Mode
BAM Fault	In Output Mode	Output Alarm Detected
BOM Fault	Meter Body Overload or Fault	Sensor Temp. Alarm Detected
Output Circuit Fault	orrect Reset	
ommStaff (0x36) (0x8d) Dev Rev 01.01		HART Beat

4-5. Checking the Error Log

It is convenient to check the error log in the EDD menu format. Select (click) the "Status Record" tab as shown in the following screen.

CommStaff - [Diagnostic]			-
Device View Window Help			_ & ×
Diagnostic Status Status Records Zero Calibr. Log In Device Device Tag Tag FIC-001		Status Non-Critical	
Clear Status Records Chical Status Records Analog/Digital Conversion Fault Sensor Characteristic Data Fault Suspect Input CPU Fault RAM Fault ROM Fault Output Circuit Fault	Internal Data Inconsistency Records Invalid Database Non-Critical Status Records Keler Body Over Temperature Excess Zero Correct Excess Zero Correct Meter Body Overload or Fault	Correct Reset External Zero/Span Adjustment Fault Output Alarm Detected Sensor Temp. Alarm Detected	
•	m		۴
CommStaff (0x36) (0x8d) Dev Rev 01.01		HART Beat	NUM //

4-6. Checking Internal Data on Zero Calibrations

It is also convenient to check the internal data on zero calibrations in the EDD menu format as shown in the following screen.

Select (click) the "Zero Calibr. Log in Device" tab as shown below. You can check for internal data on the past five zero calibrations.

🎯 CommStaff - [I	Diagnostic]				
Device View	w <u>W</u> indow <u>H</u> elp				_ <i>8</i> ×
Diagnostic Status	Status Records Zero	Calibr. Log In Device			
Device Tag					
Tag	FIC-001]		Status	JU 🚳
				Status Non-Critical	
1 (Latest)	0.0682	~ *			
2	0.0591	*			
3	0.0634	*			
4	0.0635	*			
5	0.0012	~ %			
•			III		۲
CommStaff (0x36	5) (0x8d) Dev Rev 01.01	1		i HART Beat	NUM

4.7 Storage of Device Data

You can store device data from the menu bar.

Device (D) \rightarrow Storage (S) \rightarrow CVS or PDF

ۍ کې	ommStaff - [Process Variables]					- C X
	Device View Window Help					_ 8 ×
D	New Ctrl+N	A ⁻				
	Save 🕨	CSV	Ctrl+S	Item	Value	Units
	Preferences	PDF	Ctrl+D	 Process Variables Device Diagnostic 		
	Exit Temperature All Variables Device Basic Setup Sensors Signal Condition Condition Alarm Display Calibration Calibration	1	E			
	Diagnostic	-	-			
Joaveti	he current device configuration f	ne			HART Beat	

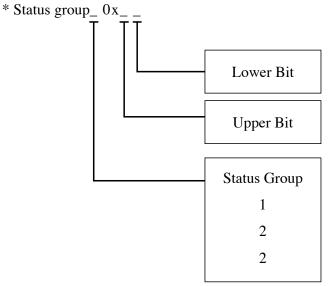
4.8 Confirmation of Diagnostic Log

You can make sure the diagnostic log from stored device data.

If device data is stored, the diagnostic log is shown as follows. $\Gamma_{\rm ext} = 1 + \Omega_{\rm ext} + \Omega_{\rm e$

Example: Status group0 0xC3

This code denotes the following status.



"Status Group 0 0xC3" of the diagnostic result is as follows. The codes "C" and "3" are in accordance with the following tables.

Upper bit C: ROM Fault and Output Circuit Fault

Lower bit 3: Analog/Digital Conversion Fault and Sensor Characteristic Data Fault

If "Status Group 0 0x00" is shown, the item of the group is normal.

Upper Bit of Status group 0

	÷ .			
1	NVM Fault			
2	RAM Fault			
3	NVM Fault	RAM Fault		
4	ROM Fault			
5	NVM Fault	ROM Fault		
6	RAM Fault	ROM Fault		
7	NVM Fault	RAM Fault	ROM Fault	
8	Output Circuit Fault			
9	NVM Fault	Output Circuit Fault		
Α	RAM Fault	Output Circuit Fault		
В	NVM Fault	RAM Fault	Output Circuit Fault	
С	ROM Fault	Output Circuit Fault		
D	NVM Fault	ROM Fault	Output Circuit Fault	
E	RAM Fault	ROM Fault	Output Circuit Fault	
F	NVM Fault	RAM Fault	ROM Fault	Output Circuit Fault

Lower Bit of Status group 0

1	Analog/Digital Conversion Fault			
2	Sensor Characteristic Data Fault			
3	Analog/Digital Conversion Fault	Sensor Characteristic Data Fault		
4	Suspect Input			
5	Analog/Digital Conversion Fault	Suspect Input		
6	Sensor Characteristic Data Fault	Suspect Input		
7	Analog/Digital Conversion Fault	Sensor Characteristic Data Fault	Suspect Input	
8	CPU Fault			
9	Analog/Digital Conversion Fault	CPU Fault		
А	Sensor Characteristic Data Fault	CPU Fault		
В	Analog/Digital Conversion Fault	Sensor Characteristic Data Fault	CPU Fault	
С	Suspect Input	CPU Fault		
D	Analog/Digital Conversion Fault	Suspect Input	CPU Fault	CPU Fault
E	Sensor Characteristic Data Fault	Suspect Input		
F	Analog/Digital Conversion Fault	Sensor Characteristic Data Fault		

Upper Bit of Status group 1

1	Meter Body Overload or Fault		
4	Correct Reset		
5	Meter Body Overload or Fault	Correct Reset	

Lower Bit of Status group 1

	<u> </u>			
1	Meter Body Over Temperature			
2	Excess Zero Correct			
3	Meter Body Over Temperature	Excess Zero Correct		
4	Excess Span Correct			
5	Meter Body Over Temperature	Excess Span Correct		
6	Excess Zero Correct	Excess Span Correct		
7	Meter Body Over Temperature	Excess Zero Correct	Excess Span Correct	
8	In Output Mode			
9	Meter Body Over Temperature	In Output Mode		
А	Excess Zero Correct	In Output Mode		
В	Meter Body Over Temperature	Excess Zero Correct	In Output Mode	
С	Excess Span Correct	In Output Mode		
D	Meter Body Over Temperature	Excess Span Correct	In Output Mode	
E	Excess Zero Correct	Excess Span Correct	In Output Mode	
F	Meter Body Over Temperature	Excess Zero Correct	Excess Span Correct	In Output Mode

Upper Bit of Status group 2

	5 1			
1	Failure Alarm Simulation Mode			
2	Contact Output Simulation Mode			
3	Failure Alarm Simulation Mode	Contact Output Simulation Mode		
4	Output Alarm Detected			
5	Failure Alarm Simulation Mode	Output Alarm Detected		
6	Contact Output Simulation Mode	Output Alarm Detected		
7	Failure Alarm Simulation Mode	Contact Output Simulation Mode	Output Alarm Detected	
8	Sensor Temp. Alarm Detected			
9	Failure Alarm Simulation Mode	Sensor Temp. Alarm Detected		
А	Contact Output Simulation Mode	Sensor Temp. Alarm Detected		
в	Failure Alarm Simulation Mode	Contact Output Simulation Mode	Sensor Temp. Alarm	
			Detected	
С	Output Alarm Detected	Sensor Temp. Alarm Detected		
D	Failure Alarm Simulation Mode	Output Alarm Detected	Sensor Temp. Alarm	
			Detected	
E	Contact Output Simulation Mode	Output Alarm Detected	Sensor Temp. Alarm	
			Detected	
F	Failure Alarm Simulation Mode	Contact Output Simulation Mode	Output Alarm Detected	Sensor Temp. Alarm
Ľ				Detected

Upper Bit of Status group 3

External Zero/Span Adjustment		
Fault		

Lower Bit of Status group 3

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0 "0"			

Lower Bit of Status group 3

1 Invalid Database

Diagnostic Message and Measure

	Diagnostic Message	Description	Measure	Display of Indicator
Internal data inconsistency	Invalid Database	Configuration data of the device or calibration data is broken	Push quit button and communicate again. Reconfigure device data and calibrate the device again.	Err.09CONFIG
	Analog/Digital Conversion Fault	Breakdown of A/D Converter	Contact Azbil group due to an abnormal condition of the sensor or the printed wiring board.	Err.01A-D CNV
	Sensor Characteristic Data Fault	Abnormal condition of sensor characteristic data	Contact Azbil group due to an abnormal condition of the sensor characteristic data.	Err.02PROM
Critical failure	Suspect Input	Abnormal condition of input data	Contact Azbil group due to an abnormal condition of the sensor or the printed wiring board.	Err.02PROM Err.03INPUT
	CPU Fault	Abnormal condition of CPU		Err.04CPU
	NVM Fault	Abnormal condition of R/W of NVM	Contact Azbil group	Err.05NVM
	RAM Fault	Abnormal condition of R/W of RAM	due to an abnormal condition of the	Err.06RAM
	ROM Fault	Abnormal condition of R/W of ROM	printed wiring board.	Err.07ROM
	Output Circuit Fault	Abnormal condition of the output circuit		Err.08OUTPUT

	Diagnostic Message	Description	Measure	Display of Indicator
	Meter Body Over Temperature	The meter body temperature is too high.	Configure the meter body temperature to be within the specification, or make sure whether the process liquid temperature is normal.	AL.20M/B TEMP
	Excess Zero Correct	The Zero Correct is too high.	Make sure whether there is no difference	AL.21ZERO. CAL
	Excess Span Correct	The Span Correct is too high.	between the input	AL.22SPAN. CAL
	In Output Mode	The device operates in the output mode.	Cancel the output mode.	OUTPUT%OUTMODE
Non-critical status	Meter Body Overload or Fault	 The input pressure exceeds twice as wide as the configurable range. Breakdown of the device 	 Make sure whether the input pressure is within the specification. If the input pressure is very high, decrease the input pressure or change the device with a wider range. 	AL.24OVRLOAD
	Correct Reset	The correct value is erased.	Perform recovery of the initial correct value, or calibrate the lower limit and the upper limit of the range.	AL.26NO.CALIB
	External Zero/Span Adjustment Fault	The external zero adjustment switch is broken.	Contact Azbil group due to an abnormal condition of the external zero adjustment switch or the printed wiring board.	AL.28SWITCH
Non-critical status	Output Alarm Detected	The output value exceeds the lower limit or the upper limit of the Output Alarm.	Make sure the output value.	AL.51OUT%. AL.
	Sensor Temp. Alarm Detected	The sensor temperature exceeds the lower limit or the upper limit of the Sensor Temp. Alarm.	Make sure the sensor temperature.	AL.52TEMP. AL

Terms and Conditions

We would like to express our appreciation for your purchase and use of Azbil Corporation's products.

You are required to acknowledge and agree upon the following terms and conditions for your purchase of Azbil Corporation's products (system products, field instruments, control valves, and control products), unless otherwise stated in any separate document, including, without limitation, estimation sheets, written agreements, catalogs, specifications and instruction manuals.

1. Warranty period and warranty scope

1.1 Warranty period

Azbil Corporation's products shall be warranted for one (1) year from the date of your purchase of the said products or the delivery of the said products to a place designated by you.

1.2 Warranty scope

In the event that Azbil Corporation's product has any failure attributable to azbil during the aforementioned warranty period, Azbil Corporation shall, without charge, deliver a replacement for the said product to the place where you purchased, or repair the said product and deliver it to the aforementioned place. Notwithstanding the foregoing, any failure falling under one of the following shall not be covered under this warranty:

- (1) Failure caused by your improper use of azbil product (noncompliance with conditions, environment of use, precautions, etc. set forth in catalogs, specifications, instruction manuals, etc.);
- (2) Failure caused for other reasons than Azbil Corporation's product;
- (3) Failure caused by any modification or repair made by any person other than Azbil Corporation or Azbil Corporation's subcontractors;
- (4) Failure caused by your use of Azbil Corporation's product in a manner not conforming to the intended usage of that product;
- (5) Failure that the state-of-the-art at the time of Azbil Corporation's shipment did not allow Azbil Corporation to predict; or
- (6) Failure that arose from any reason not attributable to Azbil Corporation, including, without limitation, acts of God, disasters, and actions taken by a third party.

Please note that the term "warranty" as used herein refers to equipment-only-warranty, and Azbil Corporation shall not be liable for any damages, including direct, indirect, special, incidental or consequential damages in connection with or arising out of Azbil Corporation's products.

2. Ascertainment of suitability

You are required to ascertain the suitability of Azbil Corporation's product in case of your use of the same with your machinery, equipment, etc. (hereinafter referred to as "Equipment") on your own responsibility, taking the following matters into consideration:

- (1) Regulations and standards or laws that your Equipment is to comply with.
- (2) Examples of application described in any documents provided by Azbil Corporation are for your reference purpose only, and you are required to check the functions and safety of your Equipment prior to your use.
- (3) Measures to be taken to secure the required level of the reliability and safety of your Equipment in your use Although azbil is constantly making efforts to improve the quality and reliability of Azbil Corporation's products, there exists a possibility that parts and machinery may break down. You are required to provide your Equipment with safety design such as fool-proof design,*1 and fail-safe design*2 (anti-flame propagation design, etc.), whereby preventing any occurrence of physical injuries, fires, significant damage, and so forth. Furthermore, fault avoidance,*3 fault tolerance,*4 or the like should be incorporated so that the said Equipment can satisfy the level of reliability and safety required for your use.
 - *1. A design that is safe even if the user makes an error.
 - *2. A design that is safe even if the device fails.
 - *3. Avoidance of device failure by using highly reliable components, etc.
 - *4. The use of redundancy.

3. Precautions and restrictions on application

3.1 Restrictions on application

Please follow the table below for use in nuclear power or radiation-related equipment.

	Nuclear power quality ^{*5} required	Nuclear power quality ^{*5} not required
Within a radiation controlled area*6	Cannot be used (except for limit switches for nuclear power*7)	Cannot be used (except for limit switches for nuclear power*7)
Outside a radiation controlled area*6	Cannot be used (except for limit switches for nuclear power*7)	Can be used

*5. Nuclear power quality: compliance with JEAG 4121 required

- *6. Radiation controlled area: an area governed by the requirements of article 3 of "Rules on the Prevention of Harm from Ionizing Radiation," article 2 2 4 of "Regulations on Installation and Operation of Nuclear Reactors for Practical Power Generation," article 4 of "Determining the Quantity, etc., of Radiation-Emitting Isotopes,"etc.
- *7. Limit switch for nuclear power: a limit switch designed, manufactured and sold according to IEEE 382 and JEAG 4121.

Any Azbil Corporation's products shall not be used for/with medical equipment.

The products are for industrial use. Do not allow general consumers to install or use any Azbil Corporation's product. However, azbil products can be incorporated into products used by general consumers. If you intend to use a product for that purpose, please contact one of our sales representatives.

3.2 Precautions on application

you are required to conduct a consultation with our sales representative and understand detail specifications, cautions for operation, and so forth by reference to catalogs, specifications, instruction manual, etc. in case that you intend to use azbil product for any purposes specified in (1) through (6) below. Moreover, you are required to provide your Equipment with fool-proof design, fail-safe design, antiflame propagation design, fault avoidance, fault tolerance, and other kinds of protection/safety circuit design on your own responsibility to ensure reliability and safety, whereby preventing problems caused by failure or nonconformity.

- (1) For use under such conditions or in such environments as not stated in technical documents, including catalogs, specification, and instruction manuals
- (2) For use of specific purposes, such as:
 - Nuclear energy/radiation related facilities
 [When used outside a radiation controlled area and where nuclear power quality is not required]
 [When the limit switch for nuclear power is used]
 - Machinery or equipment for space/sea bottom
 - * Transportation equipment
 - [Railway, aircraft, vessels, vehicle equipment, etc.]
 - * Antidisaster/crime-prevention equipment
 - * Burning appliances
 - * Electrothermal equipment
 - * Amusement facilities
 - * Facilities/applications associated directly with billing
- (3) Supply systems such as electricity/gas/water supply systems, large-scale communication systems, and traffic/air traffic control systems requiring high reliability
- (4) Facilities that are to comply with regulations of governmental/public agencies or specific industries
- (5) Machinery or equipment that may affect human lives, human bodies or properties
- (6) Other machinery or equipment equivalent to those set forth in items (1) to (5) above which require high reliability and safety
- 4. Precautions against long-term use

Use of Azbil Corporation's products, including switches, which contain electronic components, over a prolonged period may degrade insulation or increase contact-resistance and may result in heat generation or any other similar problem causing such product or switch to develop safety hazards such as smoking, ignition, and electrification. Although acceleration of the above situation varies depending on the conditions or environment of use of the products, you are required not to use any Azbil Corporation's products for a period exceeding ten (10) years unless otherwise stated in specifications or instruction manuals.

5. Recommendation for renewal

Mechanical components, such as relays and switches, used for Azbil Corporation's products will reach the end of their life due to wear by repetitious open/close operations.

In addition, electronic components such as electrolytic capacitors will reach the end of their life due to aged deterioration based on the conditions or environment in which such electronic components are used. Although acceleration of the above situation varies depending on the conditions or environment of use, the number of open/close operations of relays, etc. as prescribed in specifications or instruction manuals, or depending on the design margin of your machine or equipment, you are required to renew any Azbil Corporation's products every 5 to 10 years unless otherwise specified in specifications or instruction manuals. System products, field instruments (sensors such as pressure/flow/level sensors, regulating valves, etc.) will reach the end of their life due to aged deterioration of parts. For those parts that will reach the end of their life due to aged deterioration, recommended replacement cycles are prescribed. You are required to replace parts based on such recommended replacement cycles.

6. Other precautions

Prior to your use of Azbil Corporation's products, you are required to understand and comply with specifications (e.g., conditions and environment of use), precautions, warnings/cautions/notices as set forth in the technical documents prepared for individual Azbil Corporation's products, such as catalogs, specifications, and instruction manuals to ensure the quality, reliability, and safety of those products.

7. Changes to specifications

Please note that the descriptions contained in any documents provided by azbil are subject to change without notice for improvement or for any other reason. For inquires or information on specifications as you may need to check, please contact our branch offices or sales offices, or your local sales agents.

8. Discontinuance of the supply of products/parts

Please note that the production of any Azbil Corporation's product may be discontinued without notice. After manufacturing is discontinued, we may not be able to provide replacement products even within the warranty period.

For repairable products, we will, in principle, undertake repairs for five (5) years after the discontinuance of those products. In some cases, however, we cannot undertake such repairs for reasons, such as the absence of repair parts. For system products, field instruments, we may not be able to undertake parts replacement for similar reasons.

9. Scope of services

Prices of Azbil Corporation's products do not include any charges for services such as engineer dispatch service. Accordingly, a separate fee will be charged in any of the following cases:

- (1) Installation, adjustment, guidance, and attendance at a test run
- (2) Maintenance, inspection, adjustment, and repair
- (3) Technical guidance and technical education
- (4) Special test or special inspection of a product under the conditions specified by you

Please note that we cannot provide any services as set forth above in a nuclear energy controlled area (radiation controlled area) or at a place where the level of exposure to radiation is equivalent to that in a nuclear energy controlled area.

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