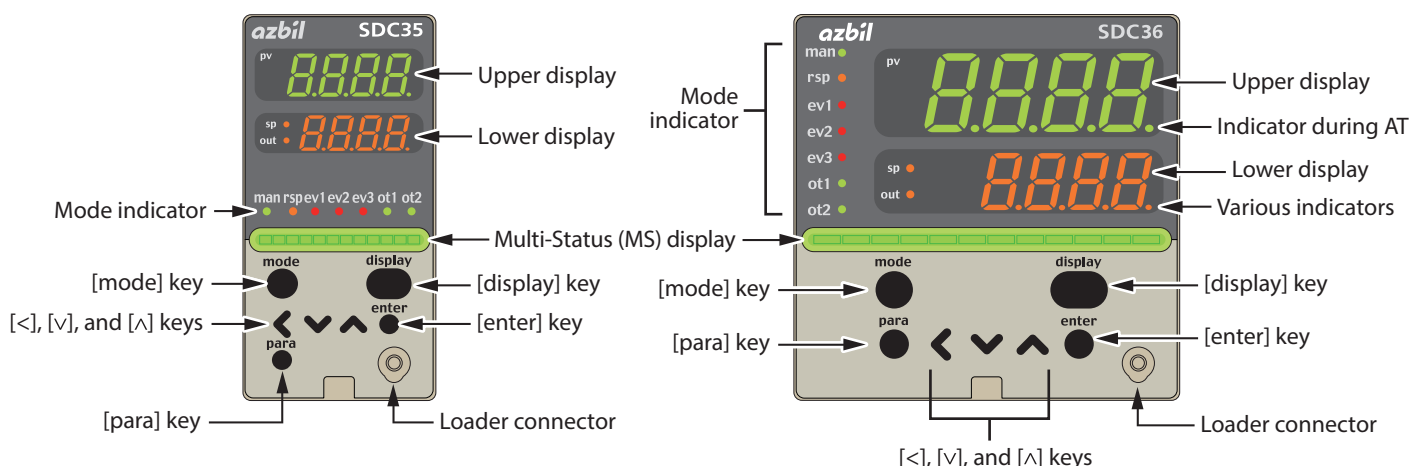


# Quick Reference Guide for Model C35/36

This guide offers a summary of key operations, parameter flowcharts, and settings, for convenient reference at the operation site. This guide is made for repeated use. Dirt wipes off easily and even notes written with an oil-based felt-tip pen can be removed with an eraser. If more detailed information on model C35/36 is needed, refer to the user's manuals: CP-SP-1150E for installation and configuration.



Upper display	This display shows either the PV value or the display value and set value for each displayed item. If an alarm is triggered, the normal display and alarm code are displayed alternately. During auto tuning (AT), the rightmost decimal point flashes twice repeatedly.
Lower display	This display shows either the SP/MV/CT or the display value and set value for each displayed item. The rightmost decimal point lights up or flashes to show RUN/READY mode or communications status, depending on the setting.
Multi-Status (MS) display	Turns ON in READY mode or when an alarm occurs, depending on the ON conditions and the current status. When lit, in addition to flashing and reciprocating between left and right, it performs MV graph, DI monitor, internal event monitor, and other display functions.
Mode indicators	man: Lights when MANUAL (AUTO mode if not lit) rsp: Lights when RSP (LSP mode if not lit) ev1, ev2, ev3: Lights when event relays are ON ot1, ot2: Lights when the control output is ON (always lit when the current output is used)
[mode] key	<ul style="list-style-type: none"> <li>When this key is pressed and held for more than 1 second in the operation display mode, any of the following operations from 0 to 7 which have been set previously can be executed:</li> <li>0 : Mode key does not operate</li> <li>1 : AUTO/MANUAL mode selection (Initial value)</li> <li>2 : RUN/READY mode selection</li> <li>3 : AT (Auto Tuning) start/stop selection</li> <li>4 : LSP (Local SP) group selection</li> <li>5 : Release all DO (Digital Output) latches</li> <li>6 : LSP/RSP mode selection</li> <li>7 : ON/OFF selection of communication DI1</li> </ul>
[display] key	This key is used to change the display item in the operation display mode. When pressing this key in the bank selection, bank setup, or user function setup display mode, the display is changed at the operation display.
[para] key	When this key is kept pressed for 2 s. or longer in the operation display mode, the display is then changed to the setup display.
[<], [v], [^] keys	These keys are used to increase or decrease the numeric value, or to shift the digit. The [v] and [^] keys are used to change the bank or display item.
[enter] key	This key is used to begin changing settings (display goes from lit to flashing) and to finalize new settings (display goes from flashing to steadily lit).
Loader connector	This connector is used for connecting to a PC using the dedicated cable supplied with the Smart Loader Package.

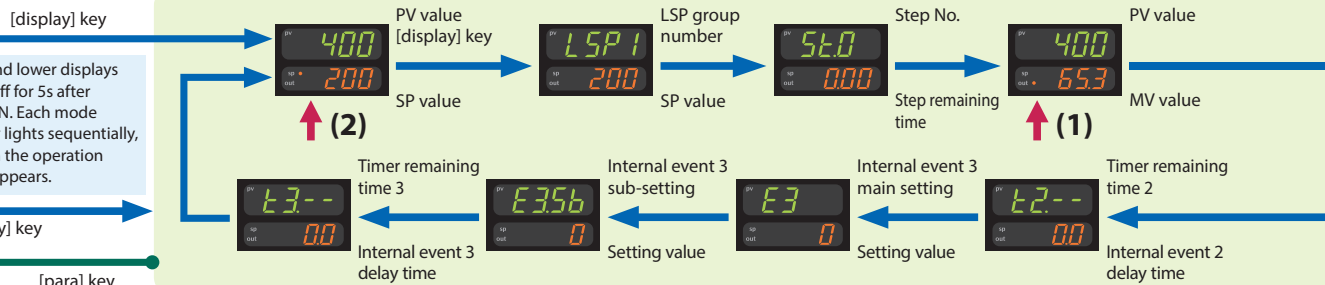
: Initial value

# Flowchart of key operations and displays

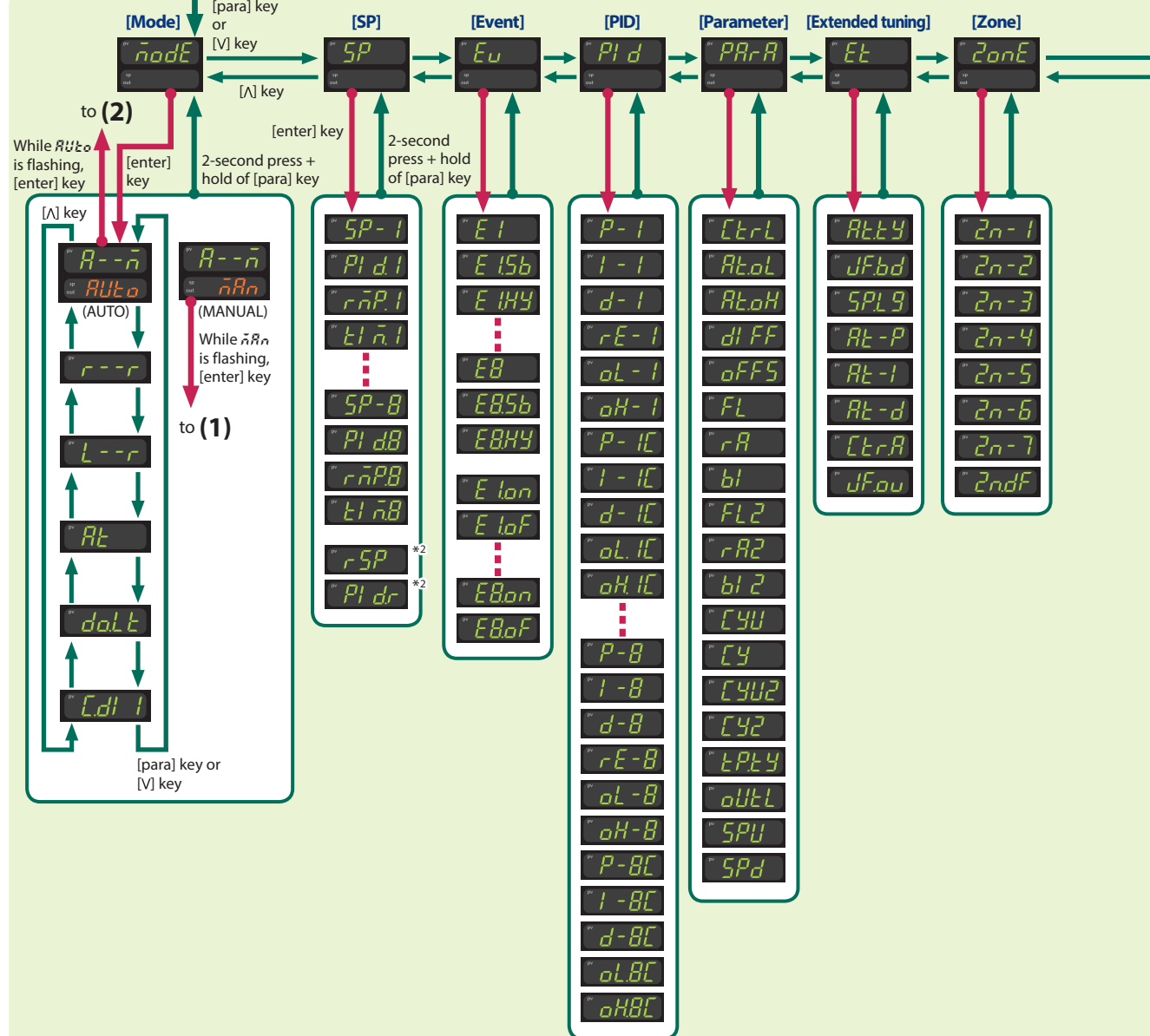
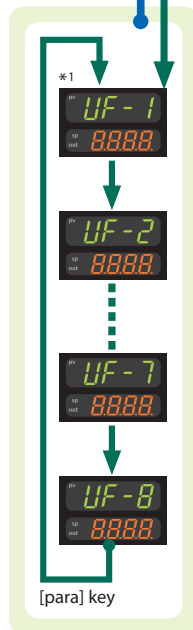
When the power is turned ON



[display] key  
Upper and lower displays remain off for 5s after power ON. Each mode indicator lights sequentially, and then the operation display appears.

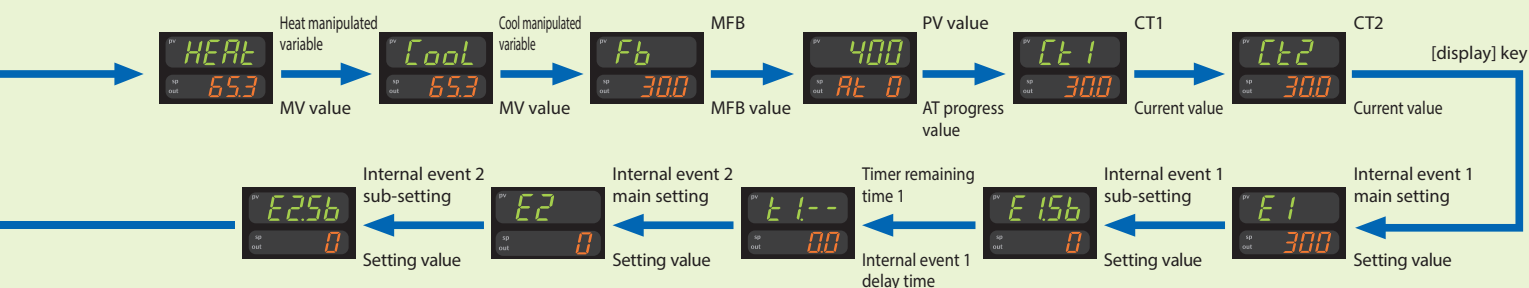


User function

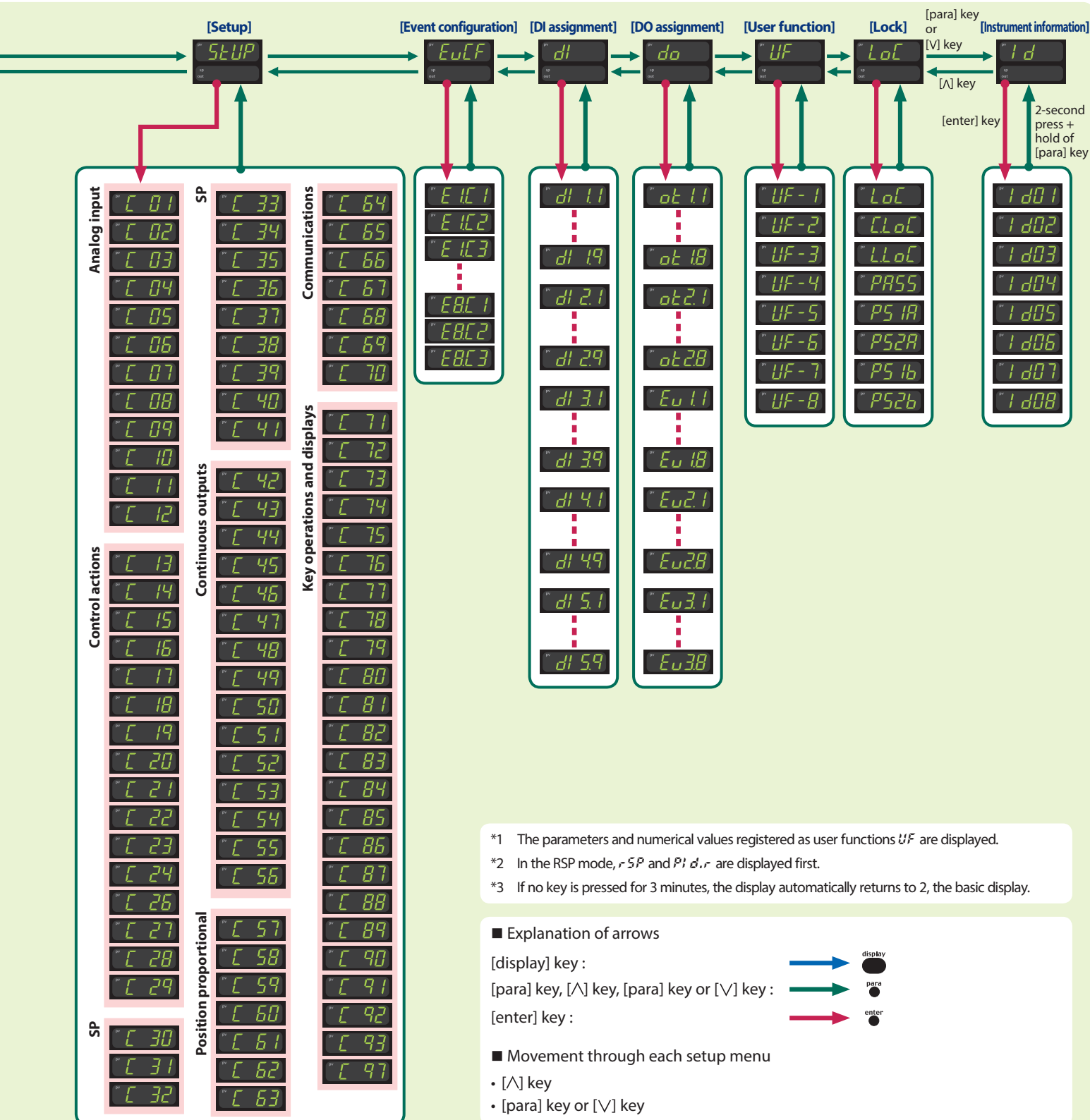


- Some items are not displayed depending on the availability of optional functions, model number, display setup (C73 to C78) and User level (C79).
- Pressing [display] key while bank item or user function item is displayed has the effect of canceling and returning to the operation display item.

## Operation displays



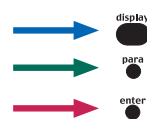
## Bank selection



- \*1 The parameters and numerical values registered as user functions *UF* are displayed.
- \*2 In the RSP mode, *rSP* and *P! d.r* are displayed first.
- \*3 If no key is pressed for 3 minutes, the display automatically returns to 2, the basic display.

### Explanation of arrows

- [display] key :
- [para] key, [/\] key, [para] key or [V] key :
- [enter] key :



### Movement through each setup menu

- [/\] key
- [para] key or [V] key

# Operation examples

## Setup of PV input range type

<b>1</b> 	<p>Press [display] once to get the operation display.</p> <p>If the sensor has not been wired or is disconnected, an alarm for abnormal PV input (any one from <math>Rt\ 0</math> to <math>Rt\ 1</math>) may appear on the upper display.</p>	<b>2</b> 	<p>Press and hold [para] for more than 2s to get the parameter setup display. <math>\tilde{node}</math> flashes on the upper display.</p>
<b>3</b> 	<p>Press [<math>\vee</math>] or [<math>\wedge</math>] repeatedly, and <math>SLUP</math> flashes on the upper display.</p>	<b>4</b> 	<p>Press [enter]. The current set value for <math>\xi\ 0</math> (PV input range type) is displayed.</p>
<b>5</b> 	<p>Press [enter]. The rightmost digit on the lower display flashes and its value can be changed.</p> <p>Press [<math>\leftarrow</math>], [<math>\vee</math>] or [<math>\wedge</math>] to change to the desired sensor type in the PV input range list.</p> <p>Then press [enter] to finalize your selection.</p> <p>If the number is flashing, the [enter] key has not yet been pressed, and the setting has not yet been saved.</p>		

## Setup of event operation type

In this example, the event 1 operation type is set to deviation high limit.

<b>1</b> 	<p>Press [display] once to get the operation display.</p>	<b>2</b> 	<p>Press and hold [para] for more than 2s to get the parameter setup display. <math>\tilde{node}</math> flashes on the upper display.</p>
<b>3</b> 	<p>Press [<math>\vee</math>] or [<math>\wedge</math>] repeatedly to get <math>EULF</math> flashing on the upper display.</p>	<b>4</b> 	<p>Press [enter] to get <math>\xi\ 1</math> on the upper display and <math>\emptyset</math> is displayed on the lower display.</p> <p><math>\emptyset</math> on the lower display indicates that the event operation type is set to "none."</p>
<b>5</b> 	<p>When [enter] is pressed, the rightmost digit on the lower display flashes.</p> <p>Press [<math>\vee</math>] or [<math>\wedge</math>] to get <math>\forall</math> flashing on the display.</p> <p><math>\forall</math> on the lower display indicates that the event operation type is set for deviation high limit.</p>		
<b>6</b> 	<p>Press [enter], and the displayed value <math>\forall</math> on the lower display changes from flashing to continuously lit and the displayed value is set.</p>		

Similarly, use  $E2.\xi$  to set the event 2 operation type, and use  $E3.\xi$  for event 3.

**Red letters** : Items before operation

**Blue letters** : Items during operation

## Execution of auto tuning (AT)

AT forces ON/OFF of the MV a number of times (a limit cycle) to calculate PID values.

Check that this operation does not create any problems for the associated equipment before executing AT.

<b>1</b> 	<p>Press [display] once to get the operation display.</p>	<b>2</b> 	<p>Press and hold [para] for more than 2s to get the parameter setup display. <math>\tilde{node}</math> flashes on the upper display.</p>
<b>3</b> 	<p>Press [enter] or [<math>\leftarrow</math>] to get <math>R-n</math> on the upper display and <math>Auto</math> on the lower display.</p> <p>If the control method is ON/OFF control and if Bit 3 (AT stop/start display) of the mode display setting (<math>\xi\ 73</math>) is set to "disabled: 0," nothing is displayed.</p>	<b>4</b> 	<p>Press [<math>\vee</math>] as needed until <math>Rt</math> and <math>Rt.oF</math> appear on the upper and lower displays respectively.</p>
<b>5</b> 	<p>When [enter] is pressed, <math>Rt.oF</math> flashes on the lower display.</p> <p>The display flashes only in RUN and AUTO modes, and only if there is no PV problem.</p> <p>Also, if DI is set to "AT stop/start", the display does not flash and the setting cannot be changed.</p>		
<b>6</b> 	<p>Press [<math>\vee</math>] or [<math>\wedge</math>] once, and <math>Rt.oF</math> flashes on the lower display.</p>		
<b>7</b> 	<p>If [enter] is pressed, <math>Rt.on</math> remains steadily lit and AT begins. During AT, the rightmost decimal point flashes twice repeatedly.</p> <p>When AT is done, the light goes off and the new PID values go into effect.</p> <p>During the AT process, if the mode is changed to READY or MANUAL, if PV input is faulty, or if a power failure occurs, AT stops automatically without changing the PID values.</p> <p>AT can also be stopped by changing the setting from <math>Rt.on</math> to <math>Rt.oF</math> (return to step 4 above).</p>		

## Setup of SP value





<b>1</b> 	<p>Press [display] repeatedly so that the orange SP indicator lights up on the lower display.</p> <p>The operation display now shows the SP.</p>	<b>2</b> 	<p>If [enter] is pressed, the rightmost digit on the lower display flashes and numerical value can be changed.</p>
<b>3</b> 	<p>Press [<math>\leftarrow</math>], [<math>\vee</math>] or [<math>\wedge</math>] to change to the desired SP value.</p> <p>The flashing of the number indicates that the setting has not yet been finalized.</p> <p>If an SP limit is in effect, the numerical value cannot be changed to a value above the limit. The SP limit must be changed first.</p>		
<b>4</b> 	<p>If [enter] is pressed, the displayed value is set and the display changes from flashing to continuously lit.</p> <p>If the [display] key is pressed without pressing [enter] key, the status returns to that of step 1.</p>		



For step numbers indicated in red like **5**, the following precaution applies:

- If the key lock is set, the numerical value does not flash, and the value cannot be changed.  
To change a numerical value, cancel the key lock first.







## AUTO/MANUAL mode selection

<p><b>1</b></p>  <p>Press [display] once to get the operation display.</p> <p>The [mode] key can be used for 1 of 7 different operations. The initial (factory) setting is "AUTO/MANUAL selection".</p>	<p><b>2</b></p>  <p>Press and hold [mode] for more than 2s, nAn flashes on the lower display.</p> <p>If the control method is set to "ON/OFF control" and if the DI assignment is "AUTO/MANUAL" the display does not blink and the setting cannot be changed.</p>
<p><b>3</b></p>  <p>When nAn appears, stop pressing [mode]. The MV is shown on the lower display. The rightmost digit of the MV on the lower display flashes and its value can be changed.</p>	<p><b>4</b></p>  <p>Press [&lt;], [v] or [^] to change to the desired MV value. Even while the number is flashing, the MV is changed at the same time that the number is changed.</p>

For the flashing MV in step 3, either bumpless transition (the same value as before the change) or preset MANUAL value (the value set in setup  $\zeta 2 \bar{G}$ ) can be selected (in setup  $\zeta 1 \bar{G}$ , Output operation at changing Auto/Manual).

## Execution of position proportional control auto adjust









When control output is R1 (motor relay output) and setup  $\zeta 5 \bar{7}$  is "0" (initial value) or "1", the following position proportional control auto adjust is necessary.

<p><b>1</b></p>  <p>Press [display] once to get the operation display.</p>	<p><b>2</b></p>  <p>Press and hold [para] for more than 2s to get the parameter setup display. nAn flashes on the upper display.</p>
<p><b>3</b></p>  <p>Press [v] or [^] repeatedly until 5tUP is flashing on the upper display.</p>	<p><b>4</b></p>  <p>Press [enter] to get <math>\zeta 0 \bar{1}</math> on the upper display. Press [&lt;], [v] or [^] to change to <math>\zeta 6 \bar{0}</math>. (<math>\zeta 6 \bar{0}</math>: motor adjust)</p>
<p><b>5</b></p>  <p>If [enter] is pressed, the lower display flashes. Press [v] or [^] to get <math>\bar{1}</math>. Press [enter] and auto adjustment starts.</p>	<p><b>6</b></p>  <p><math>\zeta \bar{R}, \zeta \bar{L}</math> is displayed on the upper display and open contact is ON. The lower display shows the MFB count value and when count is stable, <math>\zeta \bar{R}, \zeta \bar{P}</math> is displayed on the upper display and closed contact is ON. When the count value is stable, auto adjust completes to get operation display.</p>

After starting auto adjust, press [display] key to stop auto adjust. During auto adjust the key operation except [display] key of stopping auto adjust is impossible.

## Setup of event value

In this example, the event set value and hysteresis for the event 1 operation type is set to deviation high limit.

<p><b>1</b></p>  <p>Press [display] once to get the operation display.</p>	<p><b>2</b></p>  <p>Press and hold [para] for more than 2s to get the parameter setup display. nAn flashes on the upper display.</p>
<p><b>3</b></p>  <p>Press [v] twice or [^] repeatedly, and 5tUP flashes on the upper display.</p>	<p><b>4</b></p>  <p>Press [enter] to get <math>\zeta 1 \bar{1}</math> on the upper display and <math>\bar{G}</math> is displayed on the lower display.</p> <p><math>\bar{G}</math> on the lower display indicates that the event main setting is "0".</p>
<p><b>5</b></p>  <p>If [enter] is pressed, the rightmost digit on the lower display flashes, and can be changed. Press [&lt;], [v] or [^], and change to the desired value for event set value. In this case, the flashing of the numerical value implies that it is not yet set.</p>	<p><b>6</b></p>  <p>If [enter] is pressed, the changed numerical value is set and changes from flashing to continuously lit.</p>
<p>Similarly, use <math>\zeta 2 \bar{1}</math> to set a value for event 2, and <math>\zeta 3 \bar{1}</math> to set a value for event 3.</p>	
<p><b>7</b></p>  <p>To continue from this point and set hysteresis as well, press [v] twice or [^] repeatedly to get <math>\zeta 1 \bar{H} \bar{Y}</math> on the upper display. The lower display says 5.</p> <p>5 on the lower display indicates that the event hysteresis is "5".</p>	<p><b>8</b></p>  <p>In the same way that event settings were changed, press [enter] to make the number flash, and then press [&lt;], [v] or [^] to change to the desired setting for hysteresis. After that, press [enter] to finalize the setting.</p>

Similarly, use  $\zeta 2 \bar{H} \bar{Y}$  to set a value for event 2, and  $\zeta 3 \bar{H} \bar{Y}$  to set a value for event 3.

## Memo

List of parameters

List of operation displays

Display	Item	Contents	Initial value	Setting value
Upper display: PV Lower display: SP				
PV SP	SP (Target value)	SP low limit to SP high limit	0	
LSP (Display example) LSP	LSP No. (1st digit: Value at the right end digit)	1 to LSP system group (Max. 8)	1	
StP (Display example) Step No. Step remaining time	Step operation remaining time	Setting is disabled. The step No. distinguishes up ramp, down ramp, and soak.	-	
PV MV	MV (Manipulated Variable)	-10.0 to +110.0% Setting is enabled in MANUAL mode (Numeric value flashed)	-	
HEAt Numeric value	Heat MV (Manipulated Variable)	Setting is disabled. -10.0 to +110.0%	-	
Cool Numeric value	Cool MV (Manipulated Variable)		-	
Fb Numeric value	MFB (Motor opening feedback value)	Setting is disabled. +10.0 to +110.0% Flashing when the value is 0.0 to 100.0% during estimate.	-	
PV At (Display example) At (Display example)	AT progress display (1st digit = Numeric value at right end digit)	Setting is disabled.	-	
Ct1 Numeric value	CT current value 1	Setting is disabled.	-	
Ct2 Numeric value	CT current value 2	Setting is disabled.	-	
E1 Numeric value	Internal Event 1 main setting	-1999 to +9999U or 0 to 9999U	0	
E1.5b Numeric value	Internal Event 1 sub setting		0	
t1 (Display example) Numeric value	Timer remaining time 1	Setting is disabled. Upper display: The distinction by ON delay or OFF delay is displayed at the side location of "t1."	-	
E2 Numeric value	Internal Event 2 main setting	Same as Internal Event 1 main setting	0	
E2.5b Numeric value	Internal Event 2 sub setting	Same as Internal Event 1 sub setting	0	
t2 (Display example) Numeric value	Timer remaining time 2	Same as Timer remaining time 1	-	
E3 Numeric value	Internal Event 3 main setting	Same as Internal Event 1 main setting	0	
E3.5b Numeric value	Internal Event 3 sub setting	Same as Internal Event 1 sub setting	0	
t3 (Display example) Numeric value	Timer remaining time 3	Same as Timer remaining time 1	-	

List of parameter setting displays

Mode (Mode bank)

Display	Item	Contents	Initial value	Setting value
Run	AUTO/MANUAL	Run: AUTO mode Stop: MANUAL mode	AUTO	
Run	RUN/READY	Run: RUN mode Stop: READY mode	RUN	
Run	LSP/RSP	LSP: LSP RSP: RSP	LSP	
Run	AT stop/start	Run: AT stop Stop: AT start	AT stop	
Run	Release all DO latches	Run: Latch continue Stop: Latch release	Latch continue	
Run	Communication DI1	Run: OFF Stop: ON	OFF	

SP (SP bank)

Display	Item	Contents	Initial value	Setting value
RSP	RSP	Setting is disabled.	-	
Pid	PID group No. (RSP)	1 to 8	1	
SP - i to SP - 8	SP (for LSP 1 to 8)	SP low limit to SP high limit	0	
Pid, i to Pid, 8	PID group No. (for LSP 1 to 8)	1 to 8	1	
rSP, i to rSP, 8	Ramp (for LSP 1 to 8)	0 to 9999	0	
bi, i to bi, 8	Time (for LSP 1 to 8)	0.0 to 999.9 or 0 to 9999	0	

Event (Event bank)

Display	Item	Contents	Initial value	Setting value
E1 to E8	Internal Event 1 to 8 main setting	-1999 to +9999 or 0 to 9999 *	0	
E1.5b to E8.5b	Internal Event 1 to 8 sub setting		0	
E1.HY to E8.HY	Internal Event 1 to 8 hysteresis	0 to 9999 *	5	
E1.ON to E8.ON	Internal Event 1 to 8 ON delay time	0.0 to 999.9 or 0 to 9999	0	
E1.OF to E8.OF	Internal Event 1 to 8 OFF delay time		0	

\* The decimal point position varies by meeting the internal event operation type.

PID (PID bank)

Display	Item	Contents	Initial value	Setting value
P - i to P - 8	Proportional band (PID1 to 8 group)	0.1 to 999.9%	5.0	
i - i to i - 8	Integration time (PID1 to 8 group)	0 to 9999s or 0.0 to 999.9s (No integration control action when set at "0")	120	
d - i to d - 8	Derivative time (PID1 to 8 group)	0 to 9999s or 0.0 to 999.9s (No derivative control action when set at "0")	30	
r - E - i to r - E - 8	Manual reset (PID1 to 8 group)	-10.0 to +110.0%	50.0	
oL - i to oL - 8	MV low limit (PID1 to 8 group)	-10.0 to +110.0%	0.0	
oH - i to oH - 8	MV high limit (PID1 to 8 group)	-10.0 to +110.0%	100.0	
P - iC to P - 8C	Cool-side proportional band (PID1 to 8 group)	0.1 to 999.9%	5.0	
i - iC to i - 8C	Cool-side Integration time (PID1 to 8 group)	0 to 9999s or 0.0 to 999.9s (No integration control action when set at "0")	120	
d - iC to d - 8C	Cool-side derivative time (PID1 to 8 group)	0 to 9999s or 0.0 to 999.9s (No derivative control action when set at "0")	30	
oL, iC to oL, 8C	Cool-side MV low limit (PID1 to 8 group)	-10.0 to +110.0%	0.0	
oH, iC to oH, 8C	Cool-side MV high limit (PID1 to 8 group)	-10.0 to +110.0%	100.0	

Parameter (Parameter bank)

Display	Item	Contents	Initial value	Setting value
Control	Control method	0: ON/OFF control 1: Fixed PID	0 or 1	
At, oL	MV low limit at AT	-10.0 to +110.0%	0.0	
At, oH	MV high limit at AT	-10.0 to +110.0%	100.0	
d, FF	ON/OFF control differential	0 to 9999U	5	
oFFS	ON/OFF control operating point offset	-1999 to +9999U	0	
PV	PV filter	0.0 to 120.0s	0.0	
r	PV ratio	0.001 to 9.999	1.000	
b, i	PV bias	-1999 to +9999U	0	
F, L	RSP filter	0.0 to 120.0s	0.0	
r, R	RSP ratio	0.001 to 9.999	1.000	
b, i	RSP bias	-1999 to +9999U	0	
Time proportional output	Time proportional cycle unit 1	0 to 3 <sup>*1</sup>	0	
CY	Time proportional cycle 1	5 to 120s or 1 to 120s <sup>*2</sup>	10 or 2	
CY2	Time proportional cycle unit 2	0 to 3 <sup>*1</sup>	0	
CY2	Time proportional cycle 2	5 to 120s or 1 to 120s <sup>*2</sup>	10 or 2	
tP, tY	Time proportional cycle mode	0: Controllability aiming type 1: Operation end service life aiming type (Only ON/OFF operation within Time proportional cycle)	0 or 1	
MV	MV variation limit	0.0 to 999.9% (No limit when set at "0.0U")	0.0	
SP	SP up ramp (U/min)	0.0 to 999.9U (No ramp when set at "0.0U")	0.0	
SPd	SP down ramp (U/min)		0.0	

\*1 0: Unit of "1s" 1: Fixed at 0.5s 2: Fixed at 0.2s 3: Fixed at 0.1s U: Unit Maximum unit of Industrial volume in PV range (°C, Pa, L/min, etc.)  
\*2 5 to 120s when output includes the relay output

- Essential parameters for PV measurement and control
- Basic parameters
- Required parameters when using optional functions

Extended tuning bank

Display	Item	Contents	Initial value	Setting value
At, tY	AT type	0: Normal 1: Immediate response 2: Stable <sup>*1</sup>	0	
uF, b	Just-FITTER setting band	0.00 to 10.00	0.30	
SP, L	SP lag constant	0.0 to 999.9	0.0	
At - P	AT Proportional Band adjust	0.00 to 99.99	1.00	
At - i	AT Integral time adjust	0.00 to 99.99	1.00	
At - d	AT Derivative time adjust	0.00 to 99.99	1.00	
Ct, R	Control algorithm	0: PID (Conventional PID) 1: Ra-PID (High-performance PID)	0	
uF, o	Just-FITTER assistance coefficient	0 to 100	0	

\*1 Normal = Standard control characteristics, Immediate response = Control characteristics that respond immediately to external disturbance, Stable = Control characteristics having less up/down fluctuation of PV

Zone bank

Display	Item	Contents	Initial value	Setting value
Zone - i to Zone - 7	Zone 1 to 7	-1999 to +9999U	9999U	
Zone F	Zone hysteresis	0 to 9999.5U	5U	

List of setup setting displays

Setup bank

Display	Item	Contents	Initial value	Setting value
Analog input	PV input range type	For details, refer to the PV Input Range Table	88	
C01	Temperature unit	0: Celsius (°C) 1: Fahrenheit (°F)	0	
C03	Cold junction compensation	0: Performed (internal) 1: Not performed (external)	0	
C04	Decimal point position	0: No decimal point 1 to 3: 1 to 3 digits below decimal point	0	
C05	PV range low limit	When the PV input type is DC voltage/DC current, -1999 to +9999U	0	
C06	PV range high limit		1000	
C07	SP low limit	PV input range low limit to PV input range high limit	0	
C08	SP high limit		1000	
C09	PV square root extraction dropout	0.0 to 100.0% (PV square root extraction is not performed when set at "0.0")	0.0	
C10	RSP input range type	0: 4 to 20mA 1: 0 to 20mA 2: 0 to 5V 3: 1 to 5V 4: 0 to 10V	0	
C11	RSP range low limit	-1999 to +9999U	0	
C12	RSP range high limit		1000	
C13	PID calculation adjustment function <sup>*1</sup>	0: Enabled 1: Disabled	0	
C14	Control action (Direct/Reverse)	0: Heat control (Reverse action) 1: Cool control (Direct action)	0	
C15	Output operation at PV alarm	0: Control calculation is continued. 1: Output at PV alarm is output.	0	
C16	Output at PV alarm	-10.0 to +110.0%	0.0	
C17	Output at READY (Heat)	-10.0 to +110.0%	0.0	
C18	Output at READY (Cool)	-10.0 to +110.0%	0.0	
C19	Output operation at changing AUTO/MANUAL	0: Bumpless transfer 1: Preset	0	
C20	Preset MANUAL value	-10.0 to +110.0%	0.0 or 50.0	
C21	Initial output type (mode) of PID control	0: Auto 1: Not initialized 2: Initialized	0	
C22	Initial output of PID control	-10.0 to +110.0%	0.0 or 50.0	
C23	PID decimal point position (decimal point of integral time and derivative time)	0: No decimal point 1: 1 digit after decimal point	0	
C24	Zone PID operation	0: Disabled 1: Changed by SP 2: Changed by PV	0	
C26	Heat/Cool control	0: Not used 1: Used	0	
C27	Heat/Cool	0: Normal 1: Energy saving	0	
C28	Heat/Cool control dead zone	-100.0 to +100.0%	0.0	
C29	Heat/Cool change point	-10.0 to +110.0%	50.0	
C30	LSP system group	1 to 8	1	
C31	SP ramp type	0: Standard 1: Multi-ramp 2: Step operation When the power is turned ON again, the step operation is stopped (READY) 3: Step operation When the power is turned ON again, the step operation is reset	0	
C32	SP ramp unit	0: 0.1U/s 1: 0.1U/min 2: 0.1U/h	1	
C33	STEP time unit	0: 0.1s 1: 1s 2: 1min	0	
C34	STEP PV start	0: Disabled 1: Enabled	0	
C35	STEP loop	0: Stop 1: Loop 2: Final step continued	0	
C36	CT1 operation type	0: Heater burnout detection 1: Current value measurement	0	
C37	CT1 output	0 to 1: Control output 1 to 2, 2 to 4: Event output 1 to 3	0	
C38	CT1 measurement wait time	30 to 300ms	30	
C39	CT2 operation type	Same as CT1	0	
C40	CT2 output	Same as CT1	0	
C41	CT2 measurement wait time	Same as CT1	30	
C42	Control output 1 range	Current output 1: 4 to 20mA 2: 0 to 20mA Continuous voltage output 1: 1 to 5V 2: 0 to 5V 3: 0 to 10V	1	
C43	Control output 1 type	0: MV 1: Heat MV 2: Cool MV 3: PV 4: PV before ratio, bias, and filter 5: SP 6: Deviation 7: CT1 current value 8: CT2 current value 9: MFB (Including estimation MFB) 10: SP+MV 11: PV+MV	0	
C44	Control output 1 scaling low limit	-1999 to +9999U	0.0	
C45	Control output 1 scaling high limit		100.0	
C46	Control output 1 MV scalable bandwidth	0 to 9999 (Valid when control output 1 type is 10 or 11)	200	
C47	Control output 2 range	Same as control output 1	1	
C48	Control output 2 type	Same as control output 1	3	
C49	Control output 2 scaling low limit	Same as control output 1	0	
C50	Control output 2 scaling high limit	Same as control output 1	1000	
C51	Control output 2 MV scalable bandwidth	Same as control output 1	200	
C52	Auxiliary output range	Same as control output 1	1	
C53	Auxiliary output type	Same as control output 1	3	
C54	Auxiliary output scaling low limit	Same as control output 1	0	
C55	Auxiliary output scaling high limit	Same as control output 1	1000	
C56	Auxiliary output MV scalable bandwidth	Same as control output 1	200	
C57	Position proportional type	0: MFB control + Estimated position control 1: MFB control 2: Estimated position control (MFB disabled) 3: Estimated position control (MFB disabled) + Position adjustment at power ON.	0	
C58	Position proportional dead zone	0.5 to 25.0%	10.0	
C59	Motor long life mode	0: Aiming at controllability 1: Aiming at service life of potentiometer	0	
C60	Motor adjust	0: Stop 1: Start	0	
C61	Input with motor fully closed	0 to 9999	1000	
C62	Input with motor fully open	0 to 9999	3000	
C63	Motor full close-full open time	5.0 to 240.0s	30.0	
C64	Communication type	0: CPL 1: Modbus (ASCII format) 2: Modbus (RTU format)	0	
C65	Station address	0 to 127 (Communication is disabled when set at "0")	0	
C66	Transmission speed (bps)	0: 4800 1: 9600 2: 19200 3: 38400	2	
C67	Data format (Data length)	0: 7 bits 1: 8 bits	1	
C68	Data format (Parity)	0: Even parity 1: Odd parity 2: No parity	0	
C69	Data format (Stop bit)	0: 1 bit 1: 2 bits	0	
C70	Communication minimum response time	1 to 250ms	3	
C71	Key operation type	0: Standard type 1: Special type	0	
C72	[mode] key function	0: Invalid 1: AUTO/MANUAL selection 2: RUN/READY selection 3: AT Stop/Start 4: LSP group selection 5: Release all DO latches 6: LSP/RSP selection 7: Communication DI1 selection 8: Invalid 9: AUTO/MANUAL display (Enabled: +1) 10: RUN/READY display (Enabled: +2) 11: LSP/RSP display (Enabled: +4) 12: AT Stop/Start display (Enabled: +8) 13: Release all DO latches display (Enabled: +16) 14: Communication DI1 ON/OFF display (Enabled: +32) Other invalid setting, 0, +64, +128	1	
C73	MODE display setup (Sum of the weighting)	Bit 0: AUTO/MANUAL display (Enabled: +1) Bit 1: RUN/READY display (Enabled: +2) Bit 2: LSP/RSP display (Enabled: +4) Bit 3: AT Stop/Start display (Enabled: +8) Bit 4: Release all DO latches display (Enabled: +16) Bit 5: Communication DI1 ON/OFF display (Enabled: +32) Other invalid setting, 0, +64, +128	255	
C74	PV/SP display setup (Sum of the weighting)	Bit 0: PV display (Enabled: +1) Bit 1: SP display (Enabled: +2) Bit 2: LSP group number display (Enabled: +4) Other invalid setting, 0, +8	15	

- Items marked ● in the tables are displayed in standard and/or high function configuration.
- To change a user level, refer to **Changing the user level** in the lower right part of this page.

	Display	Item	Contents	Initial value	Setting value
Key operation - display	℄75	● MV display setup (Sum of the weighting)	Bit 0: MV display (Enabled: +1) Bit 1: Heat MV/cool MV display (Enabled: +2) Bit 2: MFB display (Enabled: +4) Bit 3: AT progress display (Enabled: +8)	15	
	℄76	● Event setting value display setup (Operation display)	0: Not displayed 1: Set value of Internal event 1 is displayed 2: Set values of Internal event 1 to 2 are displayed 3: Set values of Internal event 1 to 3 are displayed	0	
	℄77	● Event remaining time display setup (Operation display)	0: Not displayed 1: Internal event 1 is displayed 2: Internal event 1 to 2 is displayed 3: Internal event 1 to 3 is displayed	0	
	℄78	● CT input current value display setup (Operation display)	0: Not displayed 1: CT1 current value is displayed 2: CT1 to 2 current values are displayed	0	
	℄79	● User level	0: Simple configuration 1: Standard configuration 2: High function configuration	1	
	℄80	● LED monitor	0: Not used 1: Flashing while data is sending through RS-485 communication. 2: Flashing while data is receiving through RS-485 communication. 3: Logical OR of all DI statuses 4: Flashing in READY mode	0	
	℄81	● MS indicating lamp ON condition (1st priority)	0: Normally OFF 1: Normally ON 2 to 9: Internal event 1 to 8 10 to 13: Undefined 14: MV1 15: MV2 16 to 17: Undefined 18 to 21: DI1 to 4 22 to 25: Undefined 26 to 30: Internal contact 1 to 5 31 to 33: Undefined 34 to 37: Communication DI1 to 4 38: MANUAL 39: READY 40: RSP 41: AT 42: During ramp 43: Undefined 44: Alarm 45: PV alarm 46: Undefined 47: (mode) key pressing status 48: Event output 1 terminal status 49: Control output 1 terminal status	39	
	℄82	● MS indicating lamp ON status (1st priority)	0: Not used 1: Fast flashing 4: Left to right 5: Right to left 6: Reciprocating between left and right 7: Deviation OK 8: Deviation graph 9: MV graph 10: Heat-side MV graph 11: Cool-side MV graph 12: MFB graph 13: DI monitor 14: Internal contact monitor 15: Internal event monitor	1	
	℄83	● MS indicating lamp ON condition (2nd priority)	Same as MS display, Condition (1st priority)	44	
	℄84	● MS indicating lamp ON status (2nd priority)	Same as MS display, Status (1st priority)	6	
	℄85	● MS indicating lamp ON condition (3rd priority)	Same as MS display, Condition (1st priority)	1	
	℄86	● MS indicating lamp ON status (3rd priority)	Same as MS display, Status (1st priority)	9	
	℄87	● MS indicating lamp deviation range	0 to 9999U	5	
	℄88	● Special function	0 to 15 (This value becomes "0" when the power is turned ON).	0	
	℄89	● Zener barrier adjustment	The value can be changed with the adjustment. The numeric value cannot be directly input with the manual operation.	0.00	
	℄90	● Number of CT1 turns	0: 800 turns 1 to 40: CT turns divided by 100	8	
	℄91	● Number of CT1 power wire loops	0: 1 time 1 to 6: Number of times	1	
	℄92	● Number of CT2 turns	0: 800 turns 1 to 40: CT turns divided by 100	8	
	℄93	● Number of CT2 power wire loops	0: 1 time 1 to 6: Number of times	1	
	℄97	● PV input failure (under range) type*1	0: -10%FS 1: -5 mV (This setting is applicable if C01 (PV input range type) is set for sensor type B (No.17) or PR40-20 (No.23))	0	

\*1 Cannot be selected if ROM version 1 (℄02) of the instrument information bank is 2.26 or earlier.

### ℄0F [Event configuration bank]

	Display	Item	Contents	Initial value	Setting value
℄1, ℄1 to ℄8, ℄1	℄1, ℄2 to ℄8, ℄2	● Internal event 1 to 8 Configuration 1	Refer to event type (see page 8)	0	
		● Internal event 1 to 8 Configuration 2	The digits are determined to 1st, 2nd, 3rd, and 4th digit from the right end.		
		1st digit: Direct/Reverse	0: Direct 1: Reverse	0	
		2nd digit: Standby	0: None 1: Standby 2: Standby + Standby at SP change	0	
℄1, ℄3 to ℄8, ℄3		3rd digit: EVENT state at READY	0: Continue 1: Forced OFF	0	
		4th digit: Undefined	0	0	
		● Internal event 1 to 8 Configuration 3	The digits are determined to 1st, 2nd, 3rd, and 4th digit from the right end.		
		1st digit: Alarm OR	0: None 1: Alarm direct + OR operation 2: Alarm direct + AND operation 3: Alarm reverse + OR operation 4: Alarm reverse + AND operation	0	
		2nd digit: Special OFF	0: As usual 1: When the event set value (main setting) is 0, the event is "OFF".	0	
		3rd digit: Delay time unit	0: 0.1s 1: 1s 2: 1min	0	
		4th digit: Undefined	0	0	

### ℄1 [DI assignment bank]

	Display	Item	Contents	Initial value	Setting value
℄1, ℄1 to ℄1, ℄1	℄1, ℄2 to ℄1, ℄2	● Internal contact 1 to 5 Operation type	0: No function 1: LSP group selection (0/+1) 2: LSP group selection (0/+2) 3: LSP group selection (0/+4) 4: PID group selection (0/+1) 5: PID group selection (0/+2) 6: PID group selection (0/+4) 7: RUN/READY selection 8: AUTO/MANUAL selection 9: LSP/RSP selection 10: AT Stop/Start 11: Invalid 12: Control action direct/reverse 13: SP Ramp enabled/disabled 14: PV Hold 15: PV Maximum value hold 16: PV Minimum value hold 17: Timer Stop/Start 18: Release all DO latches (Continue/Release) 19: Advance 20: Step hold	0	
	℄1, ℄3 to ℄1, ℄3	● Internal contact 1 to 5 Input assignment A	0: Not used (Default Input) 1: Function 1 (A and B) or (C and D) 2: Function 2 (A or B) and (C or D) 3: Function 3 (A or B or C or D) 4: Function 4 (A and B and C and D)	0	
	℄1, ℄4 to ℄1, ℄4	● Internal contact 1 to 5 Input assignment B	0: Direct 1: Reverse	0	
	℄1, ℄5 to ℄1, ℄5	● Internal contact 1 to 5 Input assignment C	0: Normally opened 1: Normally closed 2: DI1 3: DI2 4: DI3 5: DI4 6 to 9: Undefined	2 to 5 or 0	
℄1, ℄6 to ℄1, ℄6	℄1, ℄7 to ℄1, ℄7	● Internal contact 1 to 5 Input assignment D	10 to 17: Internal event 1 to 8 18 to 21: Communication DI1 to 4 22: MANUAL 23: READY 24: RSP 25: AT running 26: During SP ramp 27: Undefined 28: Alarm occurs 29: PV alarm occurs 30: Undefined 31: mode key pressing status 32: Event output 1 status 33: Control output 1 status	0	
	℄1, ℄8 to ℄1, ℄8	● Internal contact 1 to 5 Polarity A	The digits are determined to 1st, 2nd, 3rd and 4th digit from the right end.		
	℄1, ℄9 to ℄1, ℄9	● Internal contact 1 to 5 Polarity B	0: Direct 1: Reverse	0	
	℄1, ℄10 to ℄1, ℄10	● Internal contact 1 to 5 Polarity C	0: Direct 1: Reverse	0	
℄1, ℄11 to ℄1, ℄11	℄1, ℄12 to ℄1, ℄12	● Internal contact 1 to 5 Polarity D	0: Direct 1: Reverse	0	
	℄1, ℄13 to ℄1, ℄13	● Internal contact 1 to 5 Polarity A	0: Direct 1: Reverse	0	
	℄1, ℄14 to ℄1, ℄14	● Internal contact 1 to 5 Polarity B	0: Direct 1: Reverse	0	
	℄1, ℄15 to ℄1, ℄15	● Internal contact 1 to 5 Polarity C	0: Direct 1: Reverse	0	

### ℄1 [DO assignment bank]

	Display	Item	Contents	Initial value	Setting value
℄1, ℄1 to ℄1, ℄1	℄1, ℄2 to ℄1, ℄2	● Control output 1 to 2, event output 1 to 3 Operation type	0: Default output 1 to 2: MV1 to 2 3 to 6: Function 1 to 4	0	
	℄1, ℄3 to ℄1, ℄3	● Control output 1 to 2, event output 1 to 3 Output assignment A	0: Normally opened 1: Normally closed 2: DI1 3: DI2 4 to 15: MV1 to 2 16 to 17: Undefined 18 to 21: DI1 to 4 22 to 25: Undefined 26 to 30: Internal Contact 1 to 5 31 to 33: Undefined 34 to 37: DI1 to 4 38: MANUAL 39: READY 40: RSP mode 41: AT running 42: During SP ramp 43: Undefined 44: Alarm occurs 45: PV alarm occurs 46: Undefined 47: Mode key pressing status 48: Event output 1 status 49: Control output 1 status	14: Output 1 15: Output 2 2: Event 1 3: Event 2 4: Event 3	
	℄1, ℄4 to ℄1, ℄4	● Control output 1 to 2, event output 1 to 3 Output assignment B	The digits are determined to 1st, 2nd, 3rd, and 4th digit from the right end.		
	℄1, ℄5 to ℄1, ℄5	● Control output 1 to 2, event output 1 to 3 Output assignment C	0: Direct 1: Reverse	0	
℄1, ℄6 to ℄1, ℄6	℄1, ℄7 to ℄1, ℄7	● Control output 1 to 2, event output 1 to 3 Polarity A to D	0: Direct 1: Reverse	0	
	℄1, ℄8 to ℄1, ℄8	● Control output 1 to 2, event output 1 to 3 Polarity B	0: Direct 1: Reverse	0	
	℄1, ℄9 to ℄1, ℄9	● Control output 1 to 2, event output 1 to 3 Polarity C	0: Direct 1: Reverse	0	
	℄1, ℄10 to ℄1, ℄10	● Control output 1 to 2, event output 1 to 3 Polarity D	0: Direct 1: Reverse	0	
℄1, ℄11 to ℄1, ℄11	℄1, ℄12 to ℄1, ℄12	● Control output 1 to 2, event output 1 to 3 Polarity A	0: Direct 1: Reverse	0	
	℄1, ℄13 to ℄1, ℄13	● Control output 1 to 2, event output 1 to 3 Polarity B	0: Direct 1: Reverse	0	
	℄1, ℄14 to ℄1, ℄14	● Control output 1 to 2, event output 1 to 3 Polarity C	0: Direct 1: Reverse	0	
	℄1, ℄15 to ℄1, ℄15	● Control output 1 to 2, event output 1 to 3 Polarity D	0: Direct 1: Reverse	0	

### ℄F [User function bank]

Display	Item	Contents	Initial value	Setting value
℄F - ℄ to ℄F - 8	● User function 1 to 8	–	–	–

### ℄0F [Lock bank]

Display	Item	Contents	Initial value	Setting value
℄0C	Key lock	0: All settings are possible 1: Mode, event, operation display, SP, UF, lock, manual MV can be set 2: Operation display, SP, UF, lock, manual MV can be set 3: UF, lock, manual MV can be set	0	
℄1, ℄0C	● Communication lock	0: read/write enabled 1: read/write disabled	0	
℄1, ℄0C	● Loader lock	0: read/write enabled 1: read/write disabled	0	
℄R55	Password display	0 to 15 (5: Password 1A to 2B display)	0	
℄S1R	Password 1A	0000 to FFFF (Hexadecimal value)	0000	
℄S2R	Password 2A	0000 to FFFF (Hexadecimal value)	0000	
℄S1b	Password 1B	0000 to FFFF (Hexadecimal value)	0000	
℄S2b	Password 2B	0000 to FFFF (Hexadecimal value)	0000	

### ℄d [Instrument information bank]

Display	Item	Contents	Initial value	Setting value
℄d01	● ROM ID	2: Fixed	0	
℄d02	● ROM Version 1	XX.XX (2 digits after decimal point)	–	
℄d03	● ROM Version 2	XX.XX (2 digits after decimal point)	–	
℄d04	● Loader information	–	–	
℄d05	● EST information	–	–	
℄d06	● Manufacturing date code (year)	Subtract 2000 from the year. Example: "3" means the year 2003.	–	
℄d07	● Manufacturing date code (month, day)	Month + day divided by 100. Example: "12.01" means the 1st day of December.	–	
℄d08	● Serial No.	–	–	

### ! Precaution for setup

- The type of auto tuning can be changed by changing the value of  $\mathcal{R}k.k\mathcal{F}$  (AT type) in the extended tuning bank. Set it to match the control characteristics.
- Make sure that the motor will be adjusted. Set  $\mathcal{C}60$  (Motor auto adjust) in [Setup bank] to "1" (Start).
- For position proportional control models, derivative time (D) will be 0 seconds when AT is complete. If satisfactory control results cannot be obtained, set  $\mathcal{R}k.k\mathcal{F}$  (AT derivative time adjust) in [Extended tuning bank] to "1.00."

## Memo

## Changing the user level

This controller's user level can be set to 1 of 3 types in setup  $\mathcal{C}79$ . The number of possible displays and settings decreases according to the user level: high function > standard > simple. All items are displayed when high function is selected.

1 Press [display] once to get the operation display. Next, press and hold [para] for more than 2s to get the parameter setup display.  $\mathcal{h}odE$  flashes on the upper display.

2 Press [v] or [v] repeatedly as needed to get  $5kUP$  flashing on the upper display.

3 Press [enter].  $\mathcal{C}01$  is shown on the upper display. Press [v], [v] or [v] to change to  $\mathcal{C}79$  (user level).

4 When [enter] is pressed, the lower display flashes. Press [v] or [v] to change to the desired setting, and press [enter] to finalize your selection.

0: Simple configuration  
1: Standard configuration (initial value)  
2: High function configuration



## PV input range table

[Thermocouple]				[RTD]			
Set value	Sensor type	Range (°C)	Range (°F)	Set value	Sensor type	Range (°C)	Range (°F)
1	K	-200 to +1200	-300 to +2200	41	Pt100	-200 to +500	-300 to +900
2	K	0 to 1200	0 to 2200	42	JPt100	-200 to +500	-300 to +900
3	K	0.0 to 800.0	0 to 1500	43	Pt100	-200 to +200	-300 to +400
4	K	0.0 to 600.0	0 to 1100	44	JPt100	-200 to +200	-300 to +400
5	K	0.0 to 400.0	0 to 700	45	Pt100	-100 to +300	-150 to +500
6	K	-200.0 to +400.0	-300 to +700	46	JPt100	-100 to +300	-150 to +500
7	K	-200.0 to +200.0	-300 to +400	47	Pt100	-100 to +200	-150 to +400
8	J	0 to 1200	0 to 2200	48	JPt100	-100 to +200	-150 to +400
9	J	0.0 to 800.0	0 to 1500	49	Pt100	-100 to +150	-150 to +300
10	J	0.0 to 600.0	0 to 1100	50	JPt100	-100 to +150	-150 to +300
11	J	-200.0 to +400.0	-300 to +700	51	Pt100	-50.0 to +200.0	-50 to +400
12	E	0.0 to 800.0	0 to 1500	52	JPt100	-50.0 to +200.0	-50 to +400
13	E	0.0 to 600.0	0 to 1100	53	Pt100	-50.0 to +100.0	-50 to +200
14	T	-200.0 to +400.0	-300 to +700	54	JPt100	-50.0 to +100.0	-50 to +200
15	R	0 to 1600	0 to 3000	55	Pt100	-50.0 to +100.0	-50 to +200
16	S	0 to 1600	0 to 3000	56	JPt100	-60.0 to +40.0	-60 to +100
17	B	0 to 1800	0 to 3300	57	Pt100	-60.0 to +40.0	-60 to +100
18	N	0 to 1300	0 to 2300	58	JPt100	-40.0 to +60.0	-40 to +140
19	PL II	0 to 1300	0 to 2300	59	Pt100	-40.0 to +60.0	-40 to +140
20	WR5-26	0 to 1400	0 to 2400	60	JPt100	-10.00 to +60.00	-10 to +140
21	WR5-26	0 to 2300	0 to 4200	61	Pt100	-10.00 to +60.00	-10 to +140
22	NI-NI-Mo	0 to 1300	0 to 2300	62	JPt100	0.0 to 100.0	0 to 200
23	PR40-20	0 to 1900	0 to 3400	63	Pt100	0.0 to 100.0	0 to 200
24	DIN U	-200.0 to +400.0	-300 to +700	64	JPt100	0.0 to 200.0	0 to 400
25	DIN L	-100.0 to +800.0	-150 to +1500	65	Pt100	0.0 to 300.0	0 to 500
26	Gold iron chromel	0.0K to 360.0 K	0 to 360 K	66	JPt100	0.0 to 300.0	0 to 500
				67	Pt100	0 to 500	0 to 900
				68	JPt100	0 to 500	0 to 900

### [DC voltage/DC current]

Set value	Input type	Range
81	0 to 10 mV	The scaling and decimal point position can be changed variably in a range of -1999 to +9999
82	-10 to +10 mV	
83	0 to 100 mV	
84	0 to 1 V	
86	1 to 5 V	
87	0 to 5 V	
88	0 to 10 V	
89	0 to 20 mA	Initial value
90	4 to 20 mA	

- \*1 The accuracy of the B thermocouple is  $\pm 4.0$  %FS for a range of 260 °C or less,  $\pm 0.4$  %FS for 260 to 800 °C and  $\pm 0.2$  %FS for 800 to 1800 °C. The PV values under 20 °C are not shown.
- The accuracy of the No.15 (sensor type R) or No.16 (sensor type S) is  $\pm 0.2$  %FS for a range of 100 °C or less, and  $\pm 0.15$  %FS for 100 to 1600 °C.
- The accuracy of the No.23 (sensor type PR40-20) is  $\pm 2.5$  %FS for 0 to 300 °C, and  $\pm 1.5$  %FS for 300 to 800 °C,  $\pm 0.5$  %FS for 800 to 1900 °C.
- The accuracy of the No.26 (sensor type gold iron chromel) is  $\pm 1.5$  K.
- The accuracy of the No.55 to 62 and 81 are  $\pm 0.15$  %FS  $\pm 1$  digit for each ranges.
- \*2 The indicated low limit for a B thermocouple is 20°C. However, if ROM version 1 of the instrument information bank (i.e. 2.04), the value is -180°C.

## List of alarm codes

Alarm code	Failure name	Cause	Corrective action
$\mathcal{A}L01$	PV input failure (Over-range)	Sensor burnout, incorrect wiring, incorrect PV input type setting	Check the wiring. Set the PV input type again.
$\mathcal{A}L02$	PV input failure (Under-range)	Sensor burnout, incorrect wiring, incorrect PV input type setting	Check the wiring. Set the PV input type again.
$\mathcal{A}L03$	CJ failure	Terminal temperature is faulty (thermocouple).	Check the ambient temperature.
$\mathcal{A}L05$	PV input failure (RTD)	Sensor burnout, incorrect wiring	Check the wiring.
$\mathcal{A}L06$	RSP input failure*1 (over range)	Sensor line break, incorrect wiring, incorrect RSP range setting	Checking wiring or reset RSP range code.
$\mathcal{A}L06$	RSP input failure*1 (under range)	Sensor line break, incorrect wiring, incorrect RSP range setting	Checking wiring or reset RSP range code.
$\mathcal{A}L07$	MFB input failure	Motor line break, incorrect wiring	Checking wiring or confirm the MFB input.
$\mathcal{A}L10$	Motor adjustment failure	Motor line break, incorrect wiring, motor power supply failure.	Checking wiring, confirm the motor power supply, reset.
$\mathcal{A}L11$	CT input failure (Over-range) (CT input 1 or 2, or both)	A current exceeding the upper limit of the display range was measured. The number of CT turns or the number of CT power wire loops is incorrectly set, or wiring is incorrect.	<ul style="list-style-type: none"> <li>Use a CT with the correct number of turns for the display range.</li> <li>Reset the number of CT turns.</li> <li>Reset the number of CT power wire loops.</li> <li>Check the wiring.</li> </ul>
$\mathcal{A}L17$	A/D conversion failure	A/D converter is faulty.	Replace the unit.
$\mathcal{A}L95$	Parameter failure	Power is shut-down while the data is being set, or data is corrupted by noise.	<ul style="list-style-type: none"> <li>Restart the unit.</li> <li>Set the data again (set data for <math>\mathcal{A}L95/97</math> and adjustment data for <math>\mathcal{A}L96/98</math>).</li> <li>Replace the unit.</li> </ul>
$\mathcal{A}L96$	Adjustment data failure	Power is shut-down while the data is being set, or data is corrupted by noise.	<ul style="list-style-type: none"> <li>Restart the unit.</li> <li>Set the data again (set data for <math>\mathcal{A}L95/97</math> and adjustment data for <math>\mathcal{A}L96/98</math>).</li> <li>Replace the unit.</li> </ul>
$\mathcal{A}L97$	Parameter failure (RAM area)	Data is corrupted by noise.	<ul style="list-style-type: none"> <li>Restart the unit.</li> <li>Set the data again (set data for <math>\mathcal{A}L95/97</math> and adjustment data for <math>\mathcal{A}L96/98</math>).</li> <li>Replace the unit.</li> </ul>
$\mathcal{A}L98$	Adjustment data failure (RAM area)	Data is corrupted by noise.	<ul style="list-style-type: none"> <li>Restart the unit.</li> <li>Set the data again (set data for <math>\mathcal{A}L95/97</math> and adjustment data for <math>\mathcal{A}L96/98</math>).</li> <li>Replace the unit.</li> </ul>
$\mathcal{A}L99$	ROM failure	ROM (memory) is faulty.	<ul style="list-style-type: none"> <li>Reset the unit.</li> <li>Replace the unit.</li> </ul>

\*1 Displays in RSP mode

## Handling Precautions

- If ROM version 1 (i.e. 2.04) of the instrument information bank is 2.04 or earlier, CT input failure ( $\mathcal{A}L11$ ) is not displayed.

## Event type

Operation type	Set value	Direct action	Reverse action
No event	0	Always OFF	Always OFF
PV high limit	1		
PV low limit	2		
PV high/low limit	3		
Deviation high limit	4		
Deviation low limit	5		
Deviation high/low limit	6		
Deviation high limit (Final SP reference)	7		
Deviation low limit (Final SP reference)	8		
Deviation high/low limit (Final SP reference)	9		
Heater 1 burnout/Over-current	16		
Heater 1 short-circuit	17		
Heater 2 burnout/Over-current	18		
Heater 2 short-circuit	19		
Alarm (status)	23	ON if alarm occurs (alarm code AL01 to 99). OFF in other cases.	OFF if alarm occurs (alarm code AL01 to 99). ON in other cases.
High and low limits of MFB value*2	33		

: initial value

- \*1 If the main setting is greater than the sub-setting, operations are performed with the main setting and sub-setting automatically swapped.

- \*2 Motor feedback

### Event types other than the above:

Operation type	Set value	Operation type	Set value	Operation type	Set value
SP high limit	10	Loop diagnosis 1	20	During AT (status)	27
SP low limit	11	Loop diagnosis 2	21	During SP ramp	28
SP high/low limit	12	Loop diagnosis 3	22	Control action (status)	29
MV high limit	13	READY (status)	24	ST setting standby (status)	30
MV low limit	14	MANUAL (status)	25	Estimated position control (status)	31
MV high/low limit	15	RSP (status)	26	Timer (status)	32

**azbil**

Azbil Corporation  
Advanced Automation Company

1-12-2 Kawana, Fujisawa  
Kanagawa 251-8522 Japan

URL: <https://www.azbil.com>

© 2007–2019 Azbil Corporation. All Rights Reserved.

Specifications are subject to change without notice. (11)

1st edition: Dec. 2007 (W)  
3rd edition: May 2019 (B)